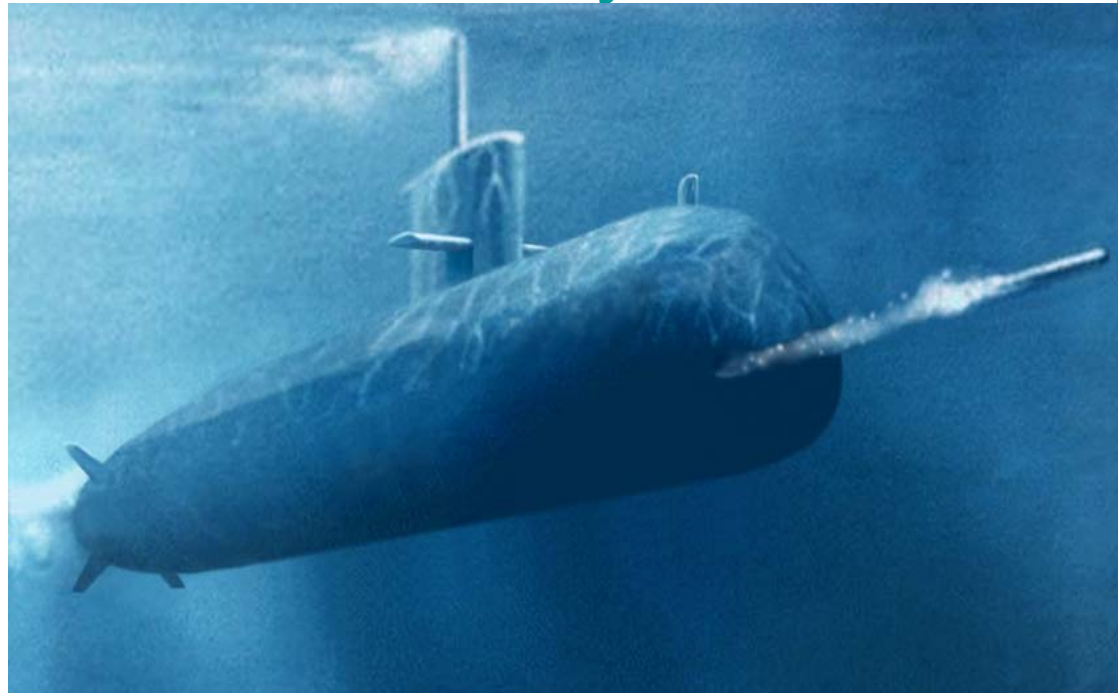




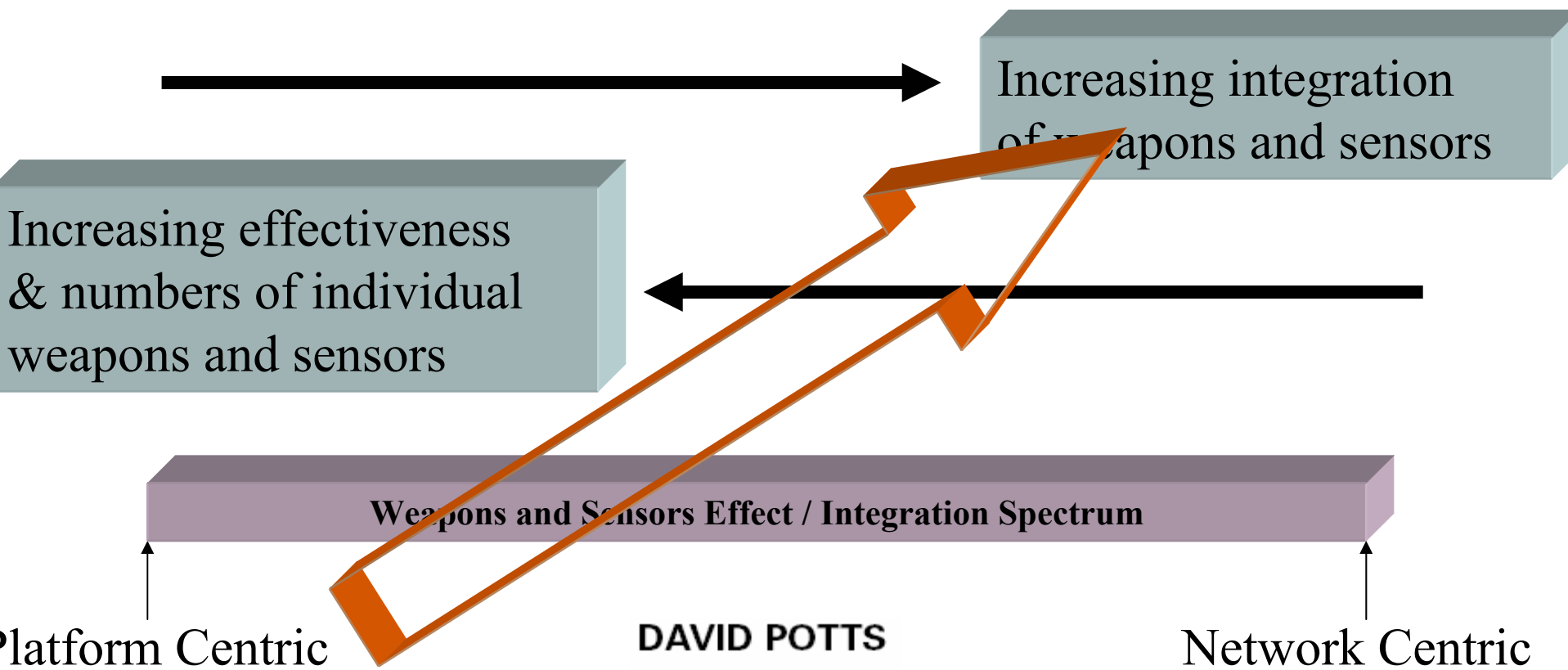
Investigating the network enabled conventional submarine II: A summary of Australian Experimentation



Sam Huf, Andrew Tynan, Sanjeev Arulampalam, Todd Mansell, Garry Brown, Rodger Manning (QINETIQ), CMDR Mel Jones (RANR).



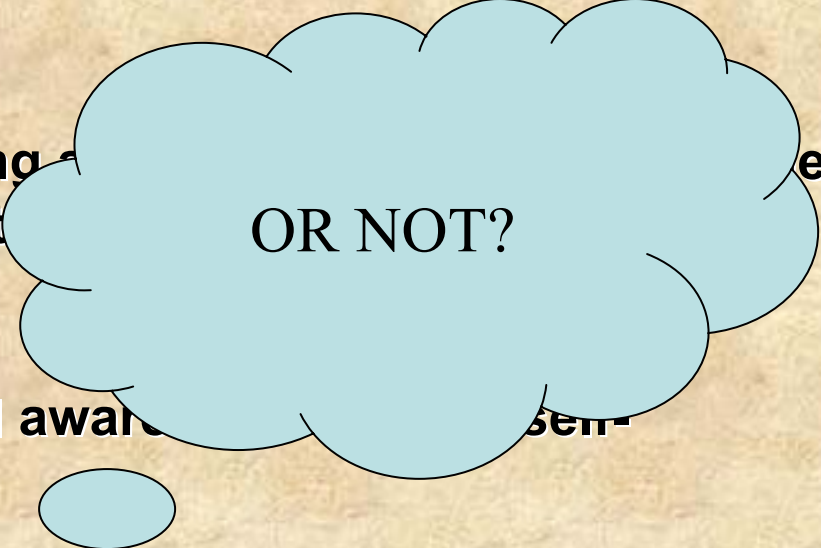
Investment in NCW?



DAVID POTTS

MARCH 2002

The tenets of NCW are:

1. A robustly networked force improves information sharing.
 2. Information sharing improves the quality of information and situational awareness.
 3. Shared situational awareness improves sensor synchronization.
 4. These, in turn, dramatically increase mission effectiveness.
- 

Ref: <http://www.dodccrp.org/research/ncw/ncw.htm>

NCW: Our BOSS (CDF)

“...Let me tell you what it means to the ADF.

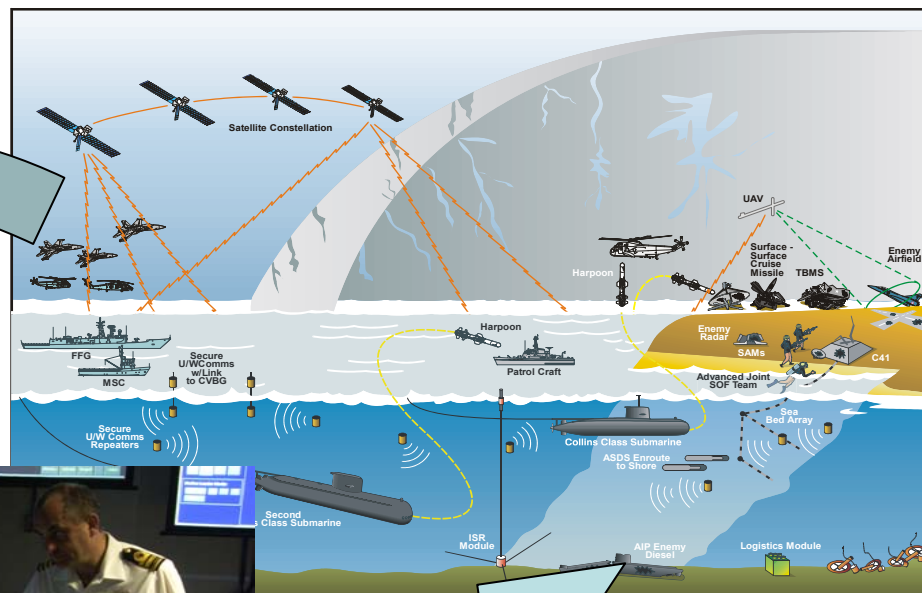
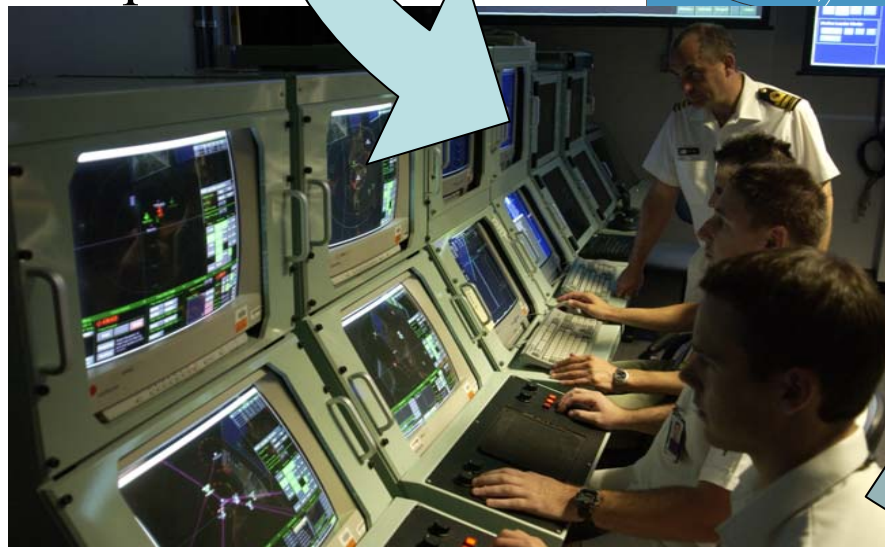
1. “... opportunities to detect, identify and engage targets using a broader range of sensors and weapons ...”
2. “... allows our people to collaborate ...”



Human-in-the-loop simulation experiments

Processes

People



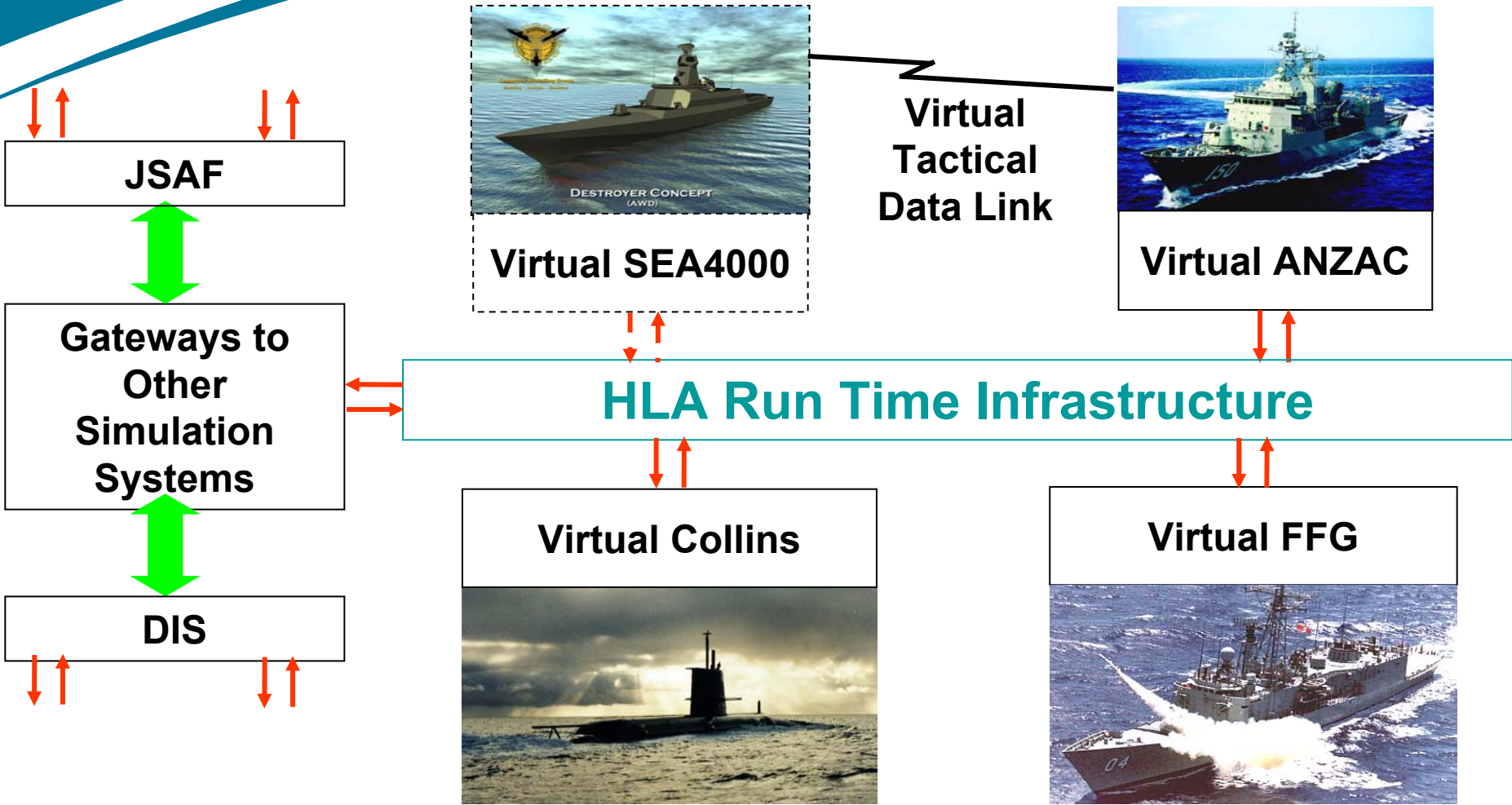
Technology

Processes



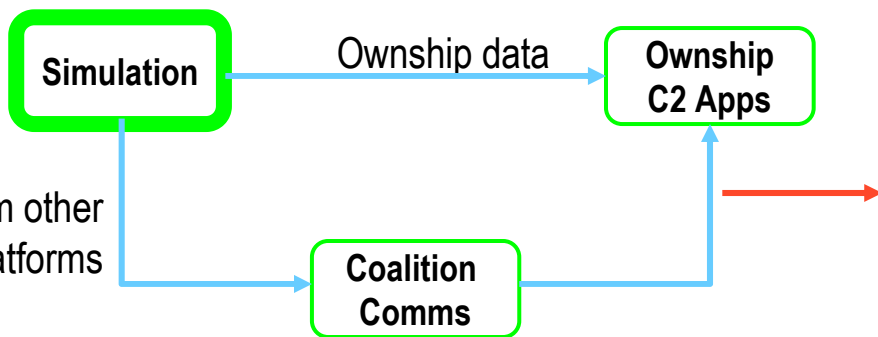


Virtual Maritime System Architecture



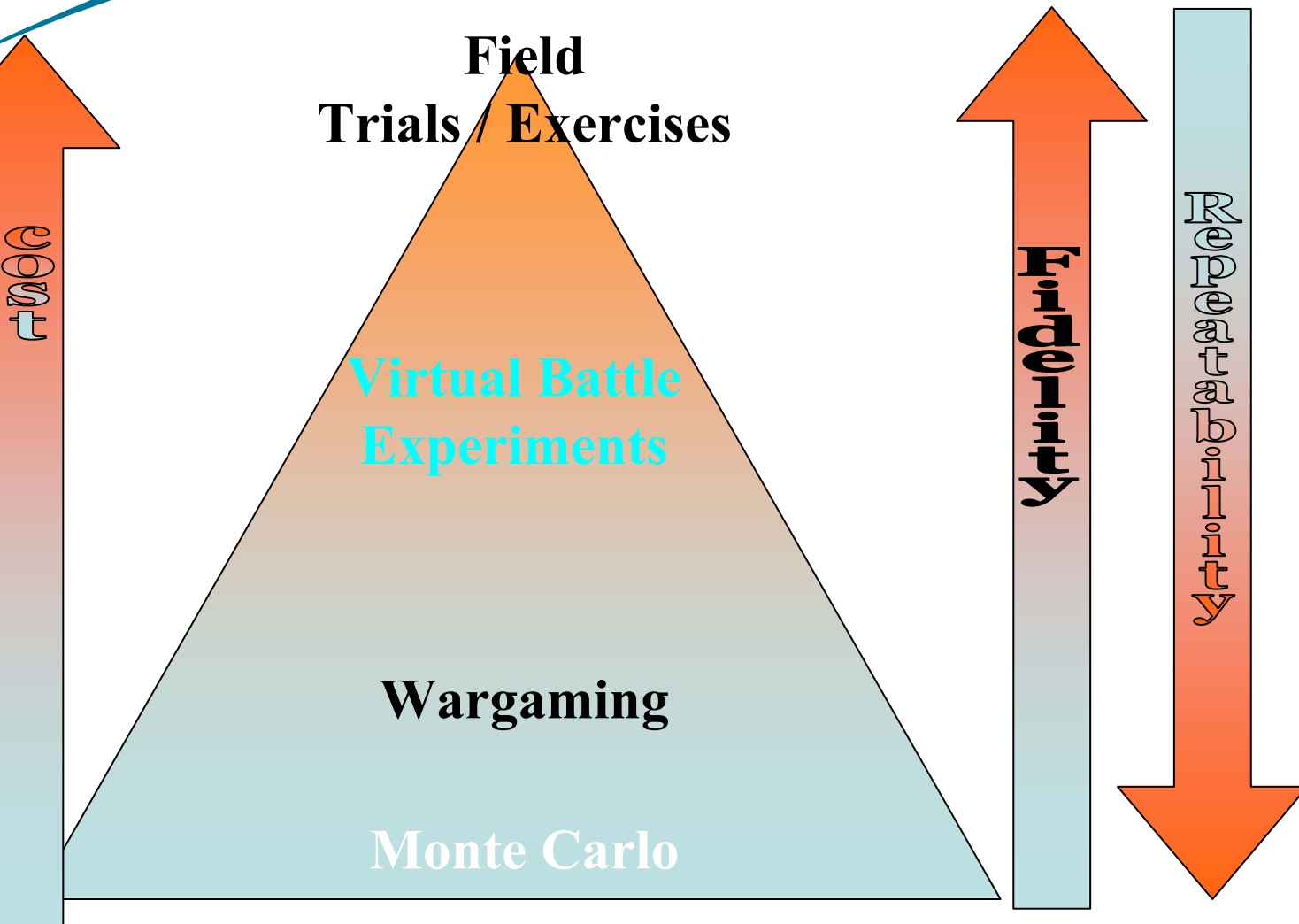


Simulating a Collins Control Room





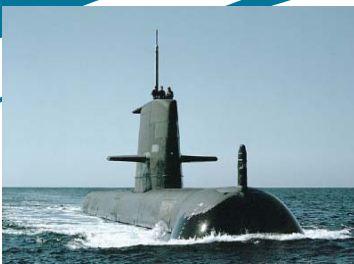
“Spectrum” of Experimentation



- Cheap
- Flexible
- Shorter timescales
- Controlled
- Instrumented for
 - o Analysis
 - o Evaluation
 - o Application
 - o Evolution



MAR TP-1 Conceptual Model



NCW Distribution Layer

AS



CA



NZ



UK



US



Scenario/Simulation Layer

Virtual Battle Experiment

- Experimental Methodology
- Analysis / Metrics

Common Simulation Environment

- Above water sensors
- Underwater sensors
- Motion
- NCW Comms

Warfare Domains

- ASuW ✓
- ASW ✓
- Amphibious Operations
- Maritime Strike
- AAW

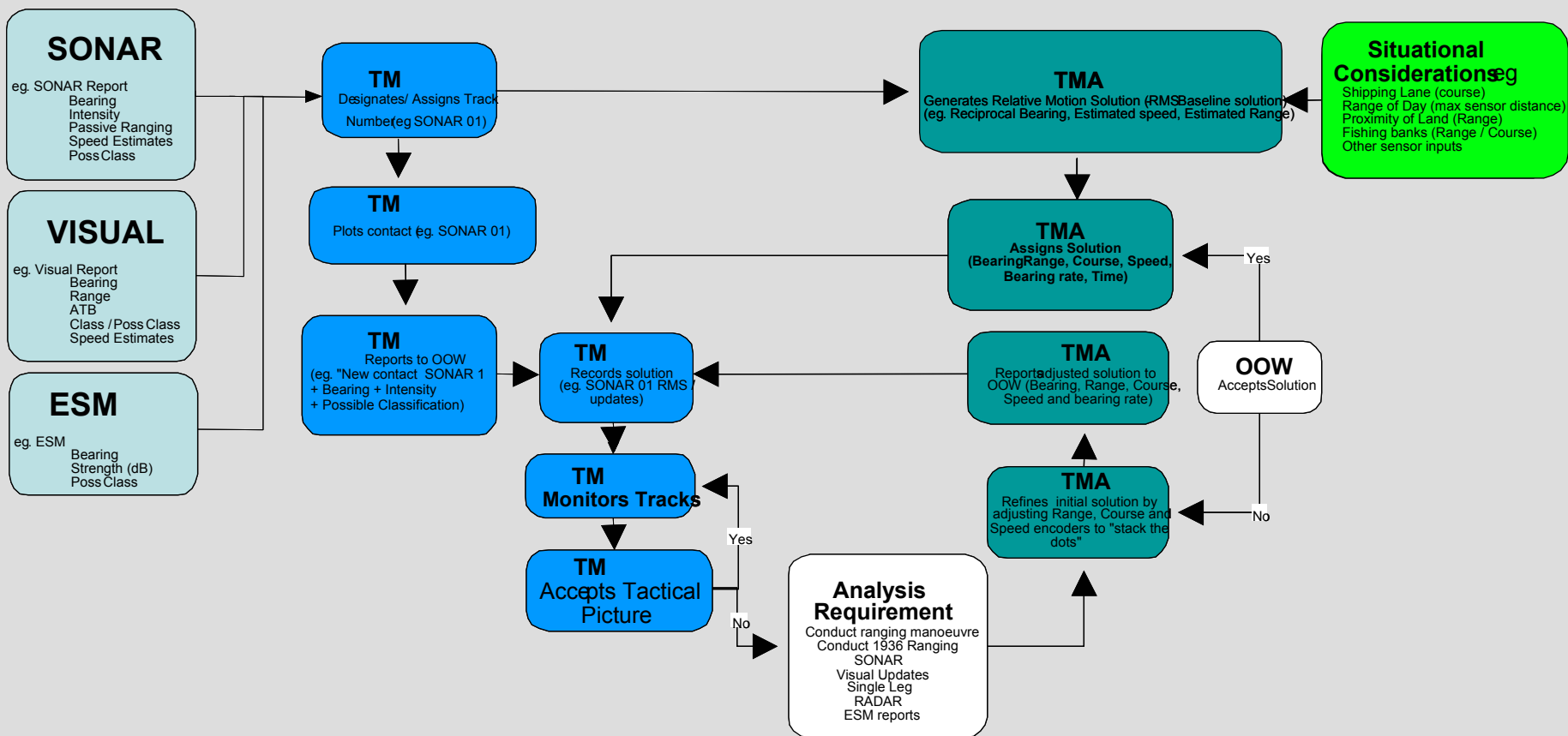
Virtual Combat Systems

- Submarine
- Surface Ship
- Generic Airborne Platform

A series of VBE Experiments

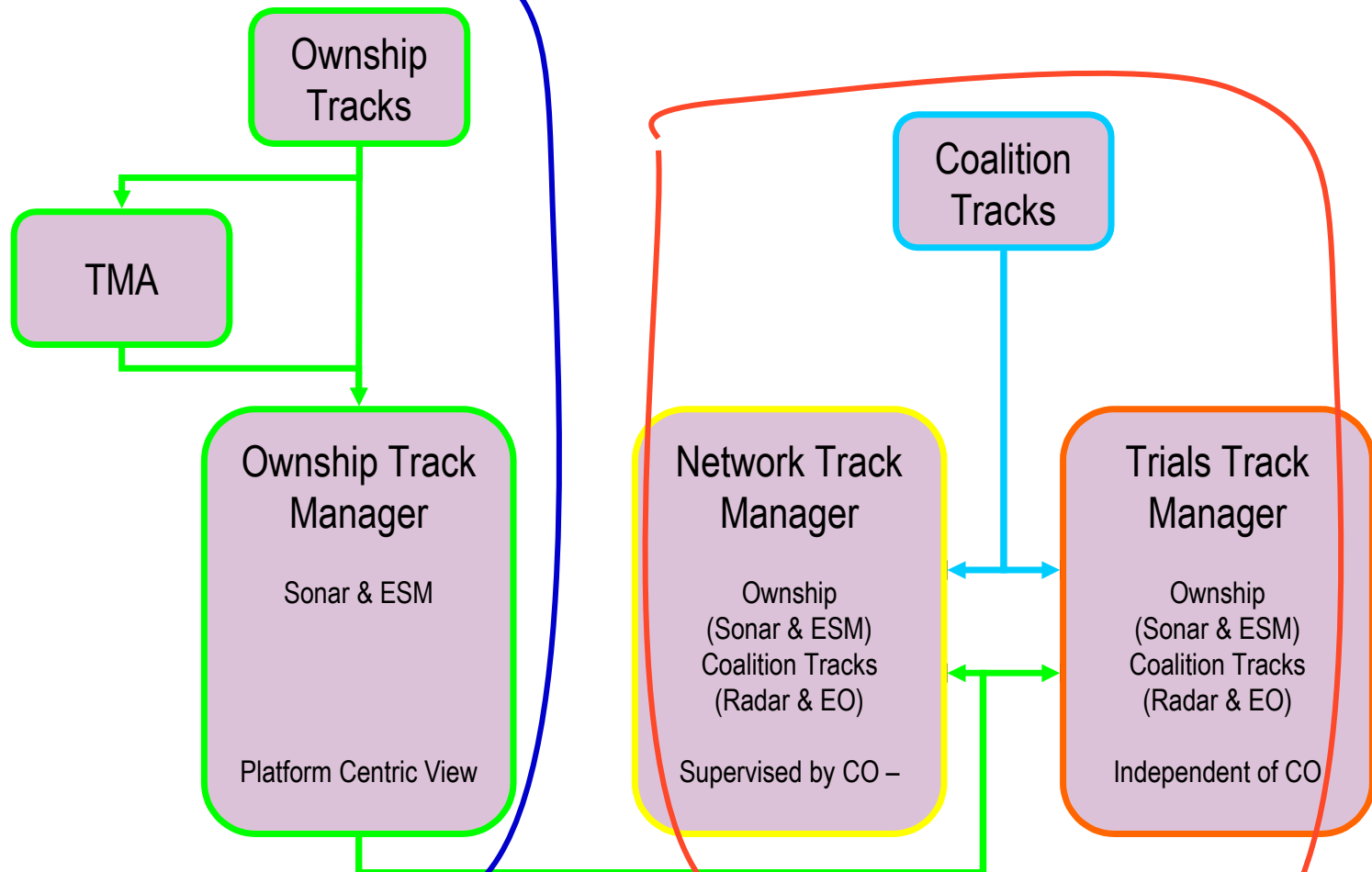
Title	Date	Location	Scenario	Principle Objectives
VBE-A	May 2002	UK	2 platform coalition	VMSA Connectivity verification
VBE-AS1	Sep 2002	AS	2 platform coalition	Develop baseline for experimentation (Conduct and infrastructure)
VBE-AS2	Oct 2002	AS	2 platform coalition	Introduction of non-scripted ownship Development and use of metrics for detailed analysis
VBE-AS3	Apr 2003	AS	4 platform coalition	Define baseline for VBE-B
VBE-B	May 2003	NZ	4 platform coalition	First five nation VBE Internet Connectivity Trial (NZ-CA)
VBE-AS4	August 2003	AS	4 platform coalition	Verify modified conduct & data fusion algorithms

Task Analyses: Picture Compilation





Method: Concurrent Comparison



Current Practice

Future Practice



Metrics

Picture Quality (SIAPS Attributes)

- ❑ **Accuracy** A reflection of the measurement errors.
- ❑ **Completeness** Degree to which information includes every RWO of interest
- ❑ **Continuity** A picture is continuous when the track number as signed to a RWO does not change and its attributes are maintained over time.

Human Performance (Human Performance)

- ❑ **Task Performance** (Association / Fusion / Application Usage)
- ❑ **Situation Awareness** (SART Ratings – recent move to objective measures)
- ❑ **Workload** ('moment-to-moment' measure developed at SPAWAR)

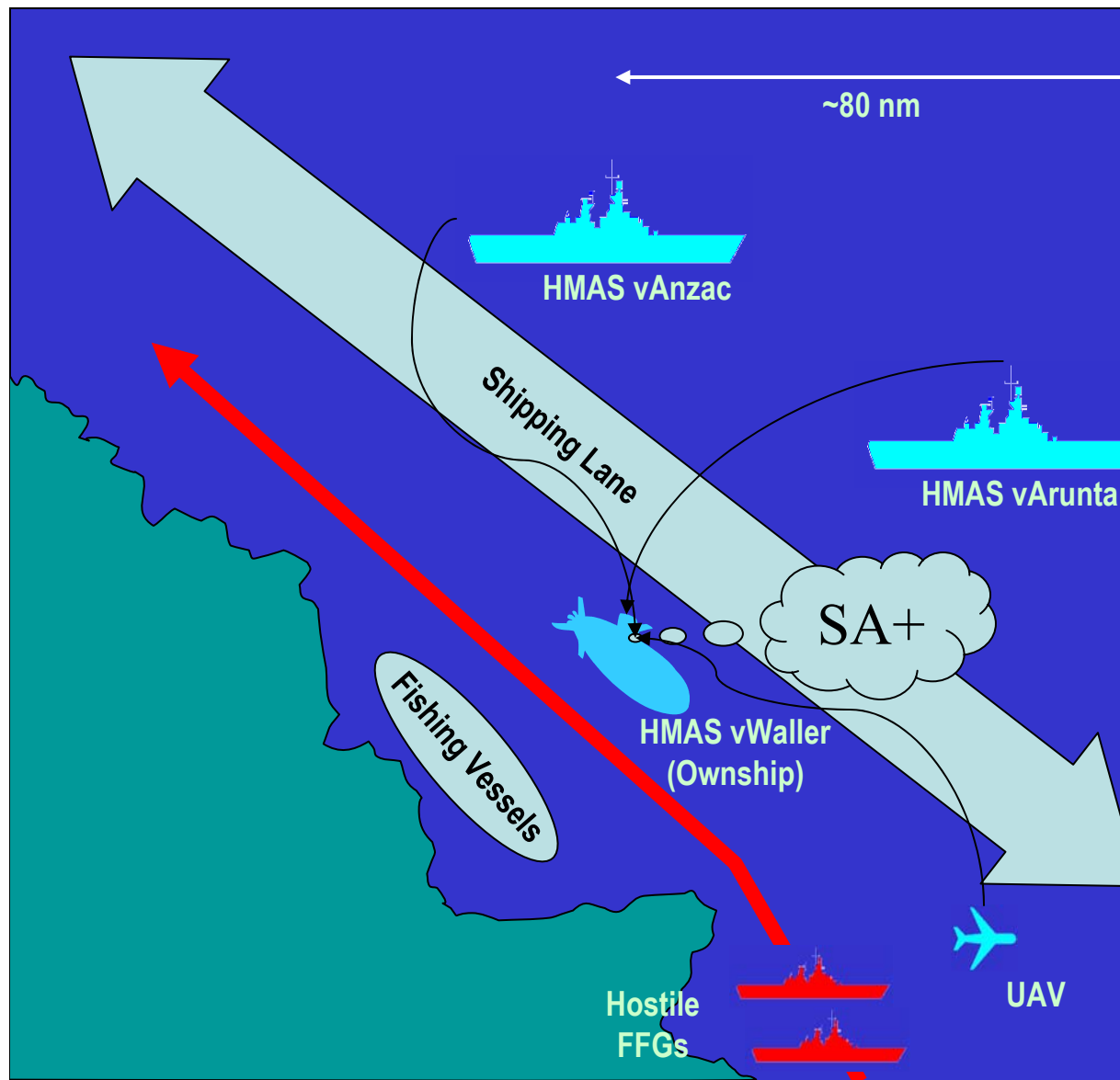


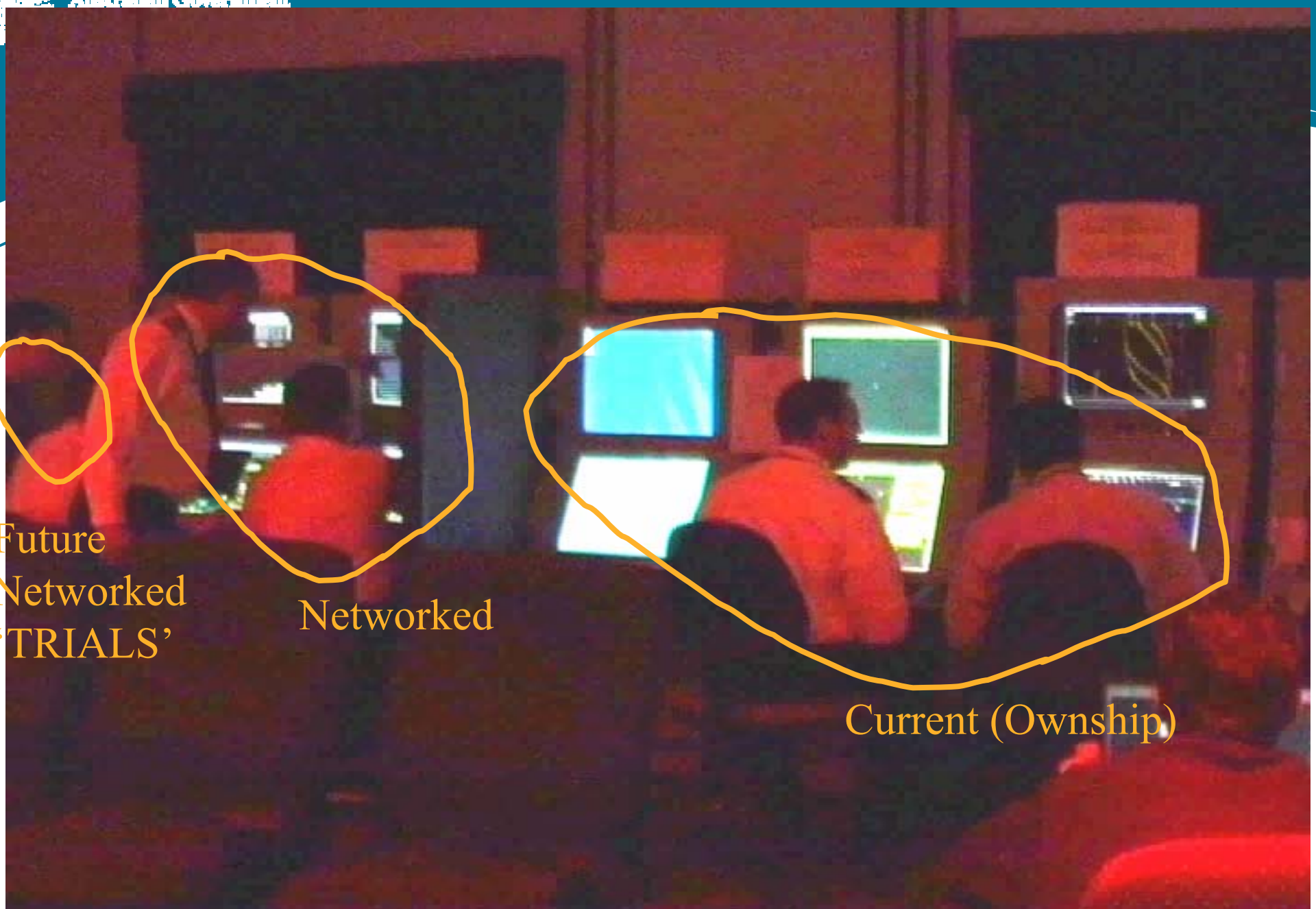
VBE AS-4 Hypotheses

- 1. IF track sharing occurs THEN a more complete and accurate representation of the operating environment can be maintained by each platform**
- 2. IF track-sharing of high priority targets occurs THEN they can be more continuously monitored with a greater accuracy**
- 3. IF background association algorithms are provided to the operator THEN a less cluttered picture can be maintained**



Simple but Representative Network Scenarios





Future
Networked
'TRIALS'

Networked

Current (Ownship)



Recording Plan (VBE-AS4)

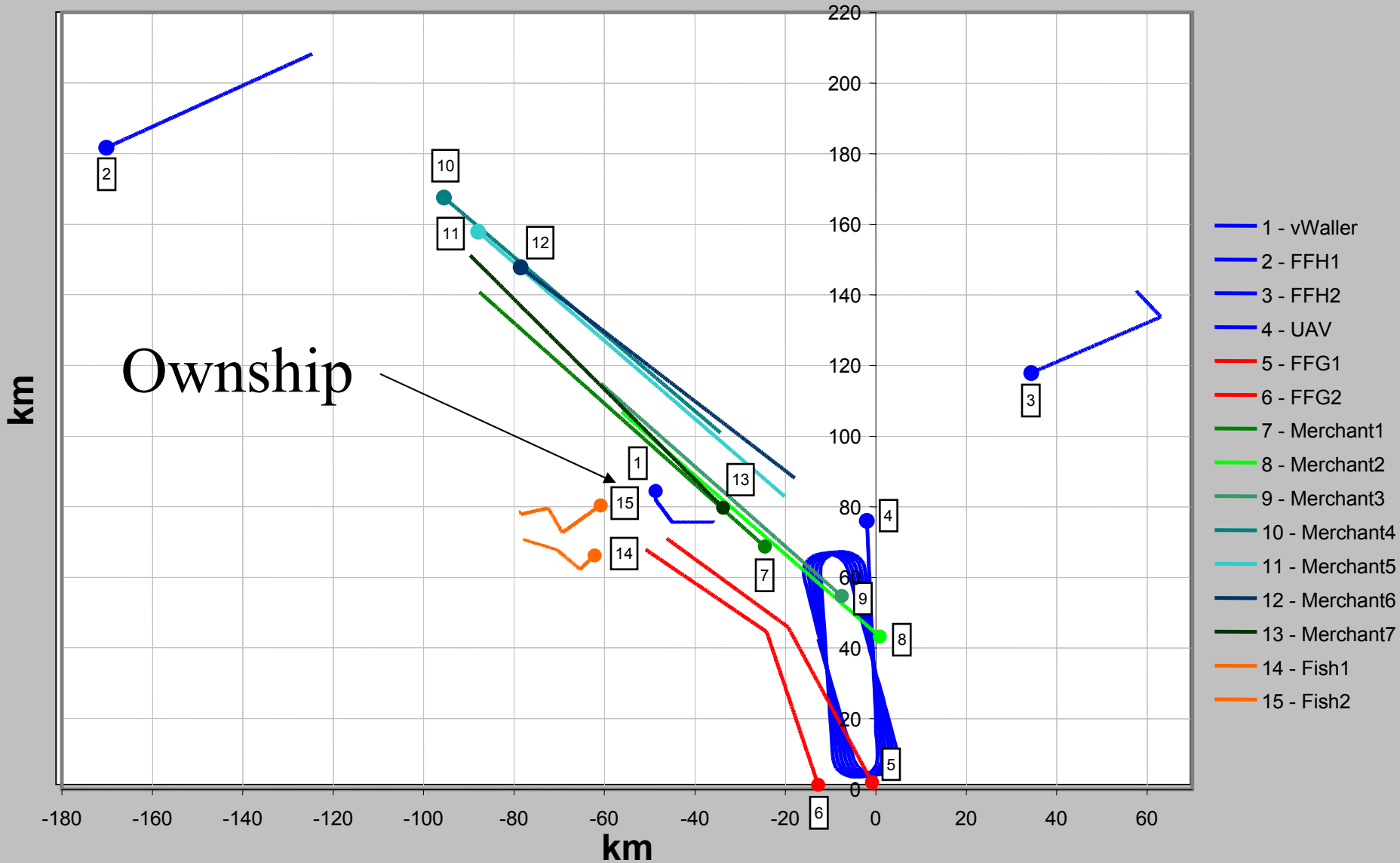
- ❑ Track data (every 30s)
- ❑ Truth data (every 30s)
- ❑ Mapping files to link truth and track data
- ❑ Alerts & recommendations to the operators
- ❑ Perceived operator workload / Situation Awareness
- ❑ Dictaphone for CO
- ❑ Plugin activation
- ❑ Photographic & video record
- ❑ Formal observer records
- ❑ Screen snapshots

Summary Findings





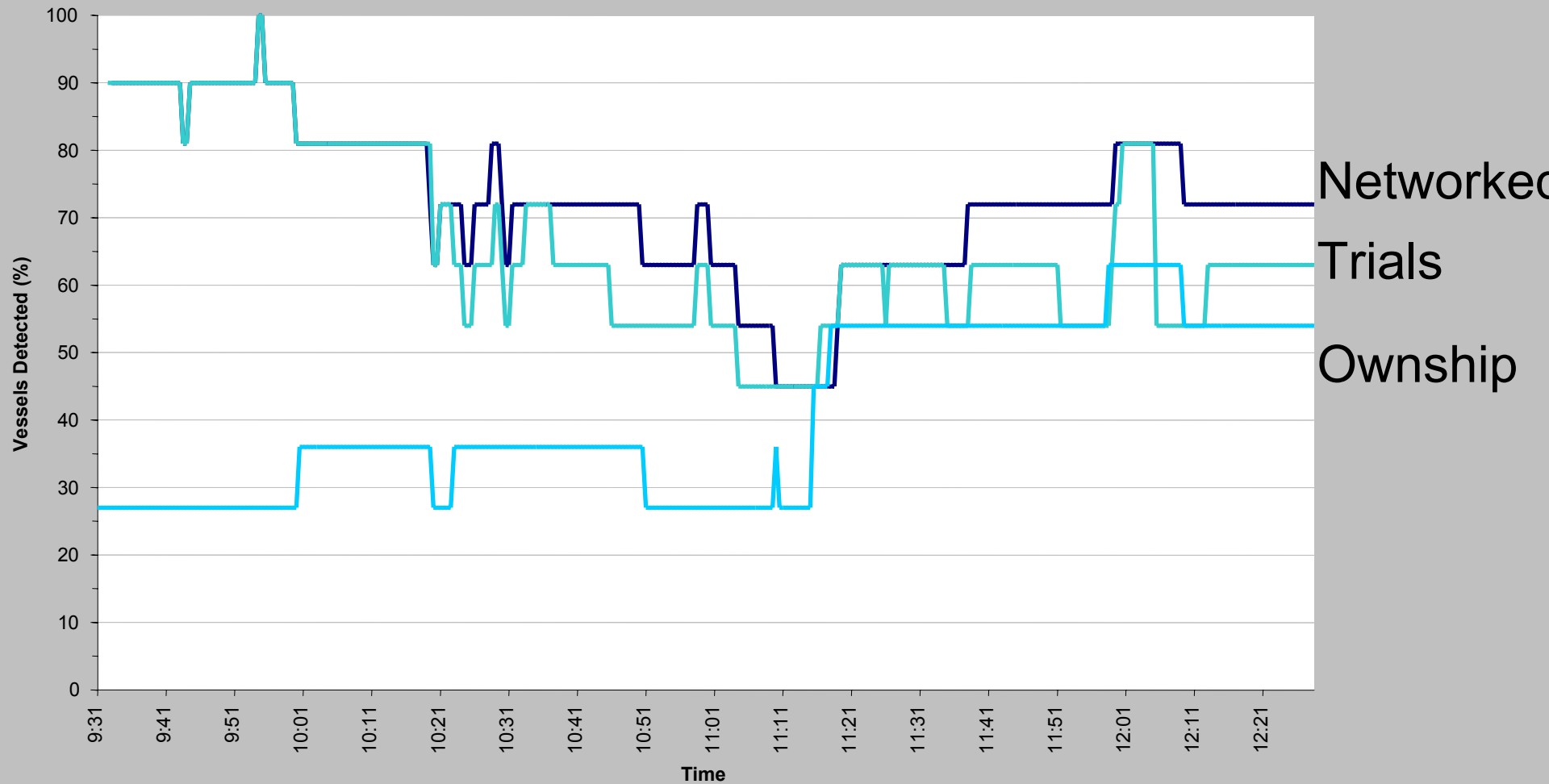
VBE-AS4 Ground Truth





Detection Completeness

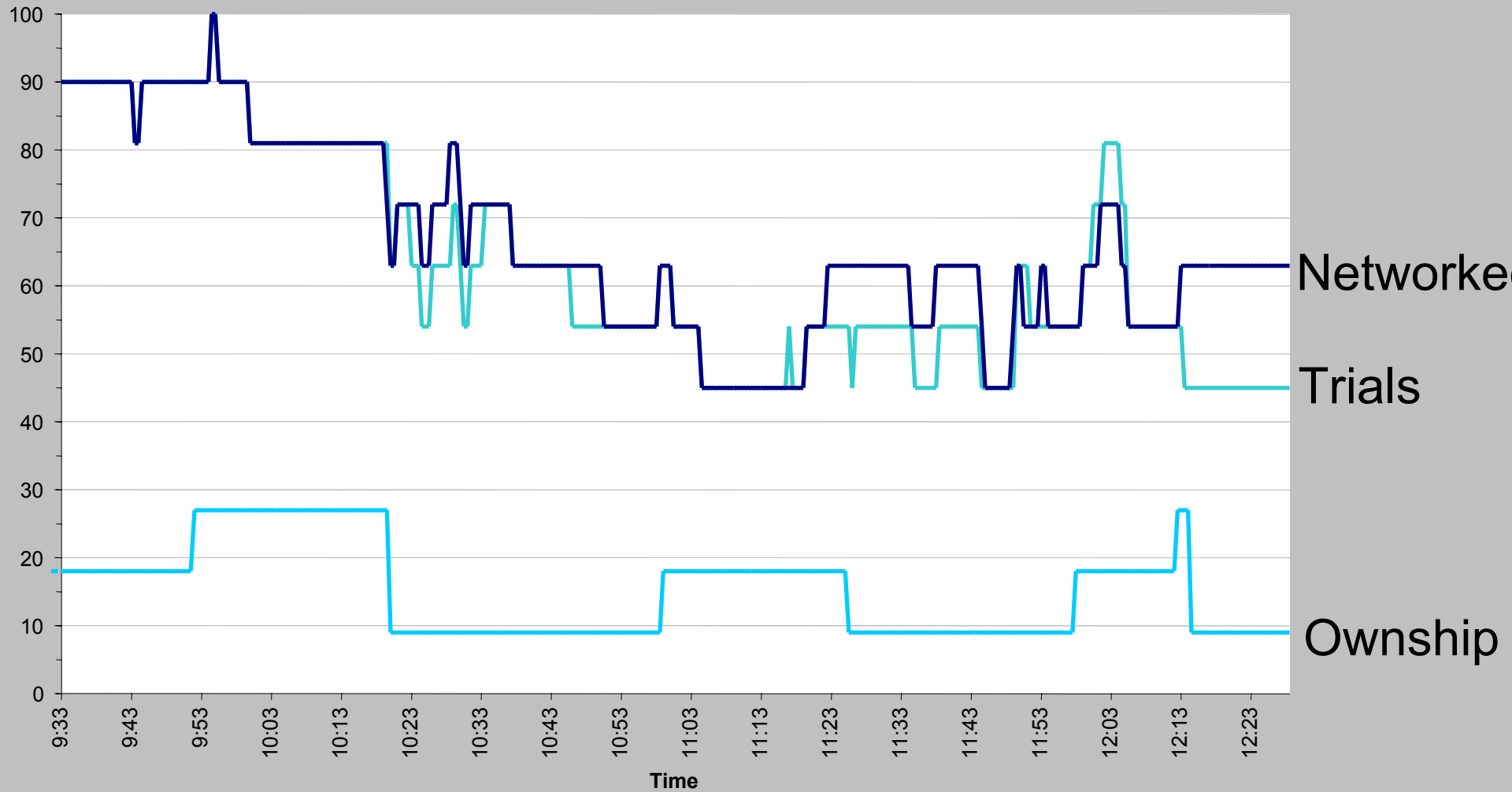
Percentage of Vessels Detected





Solution Completeness

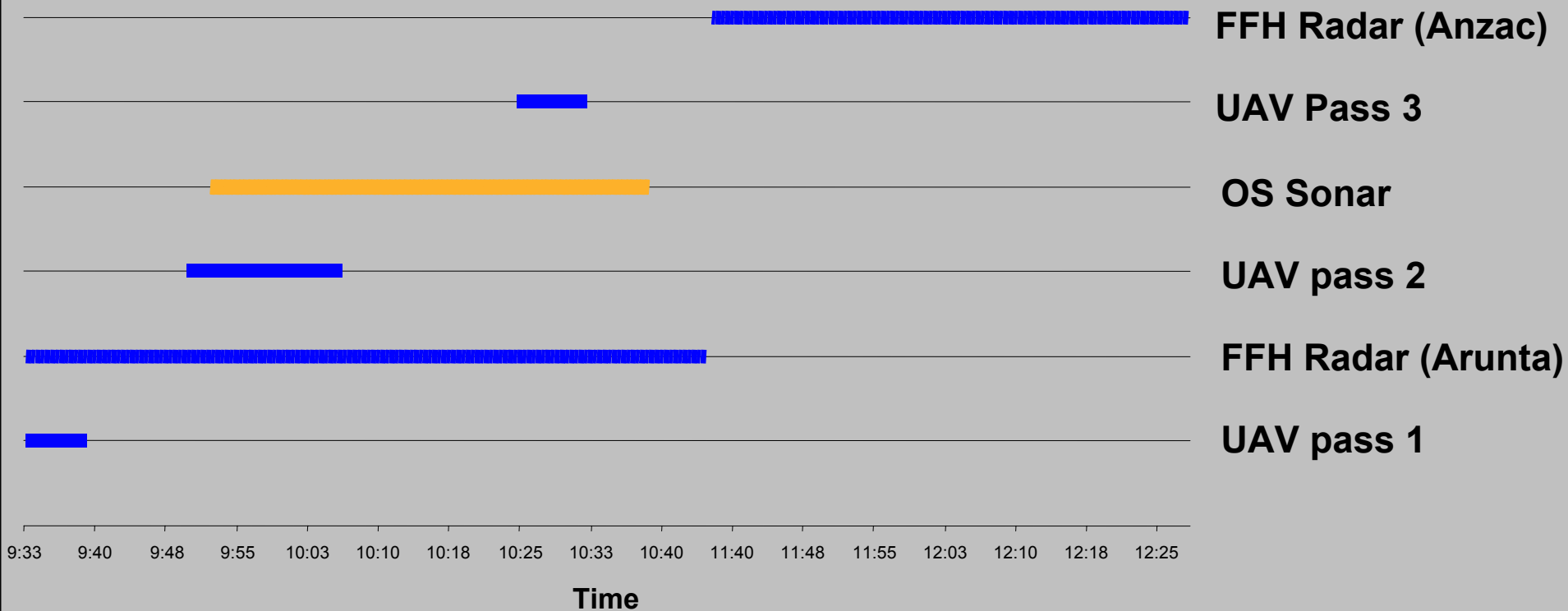
Percentage of Vessels with Solutions





Multiple Sensor Sources

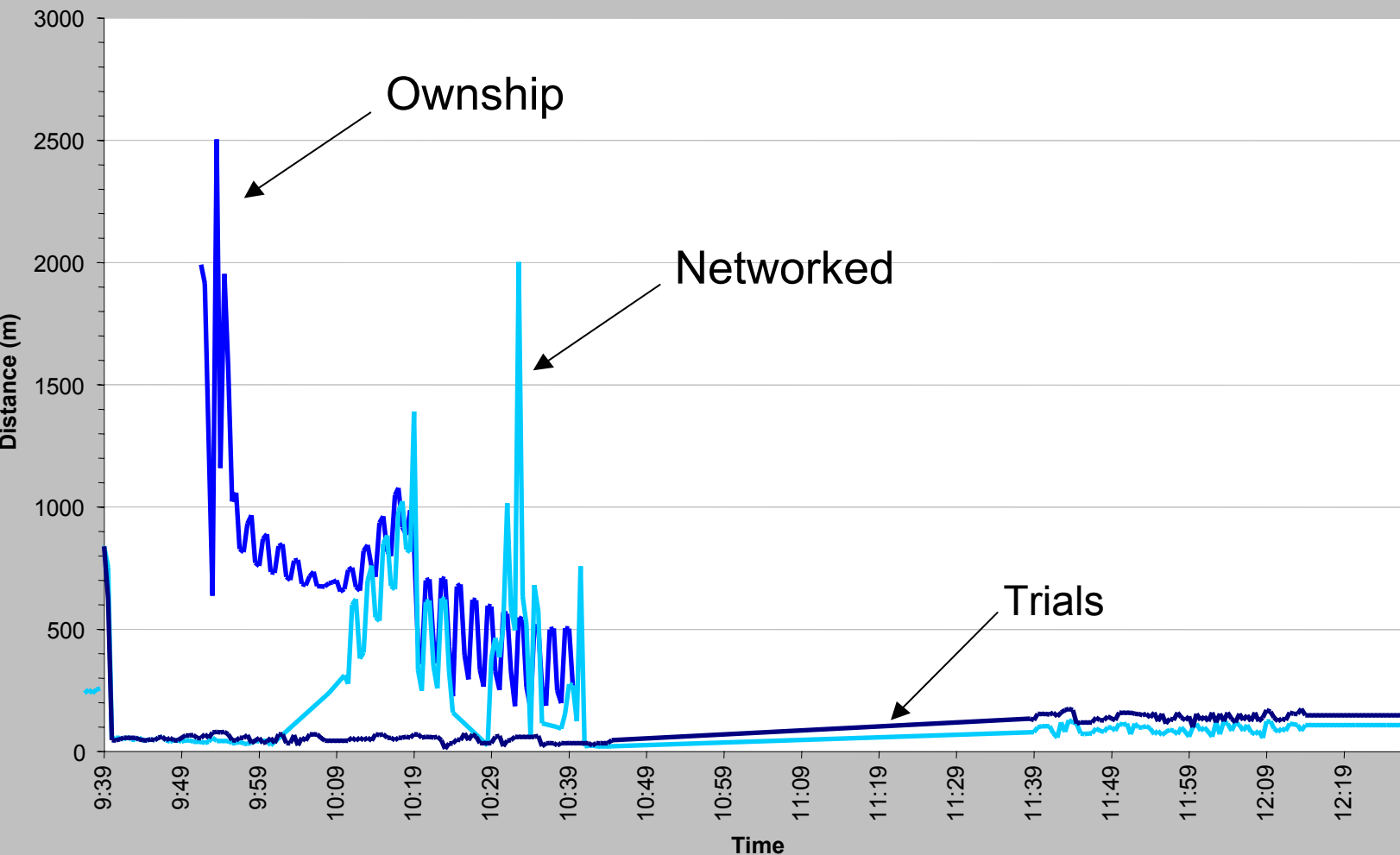
Detection Source Timeline: Merchant 1





Average Position Error

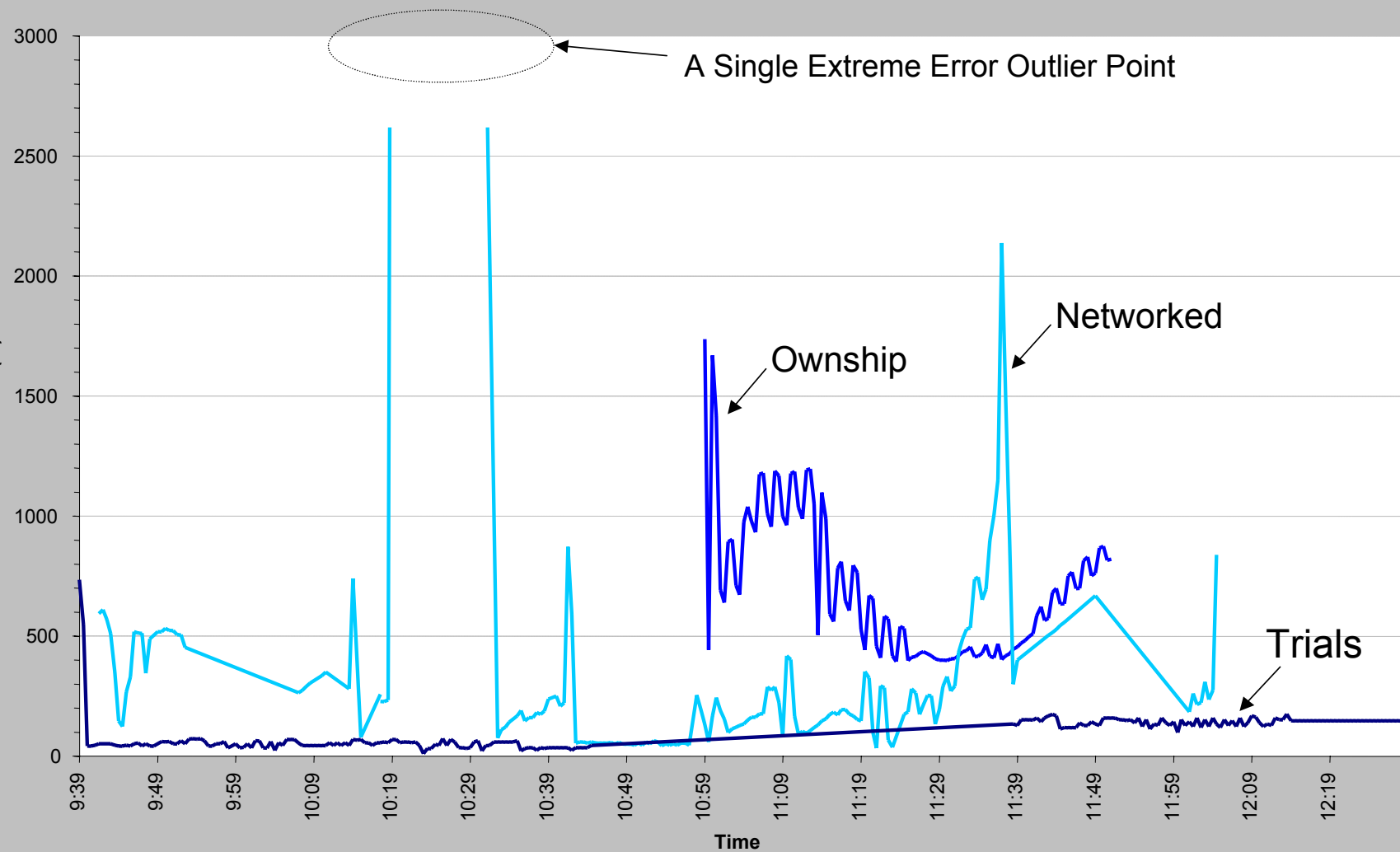
Average Positional Error of Constructed Tracks for Merchant1





Position Error Merchant 2

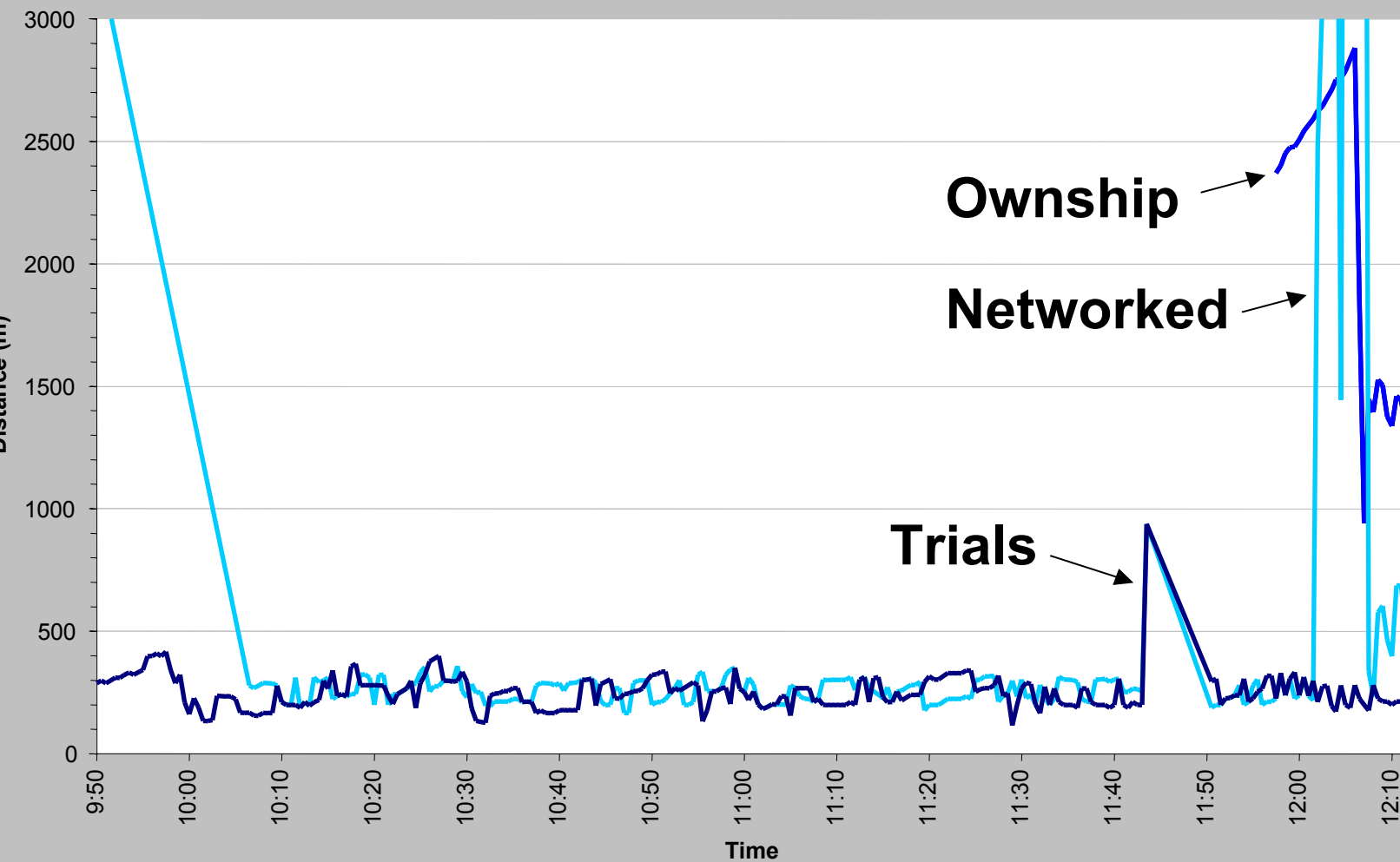
Average Positional Error of Constructed Tracks for Merchant 2





Priority Contacts 1

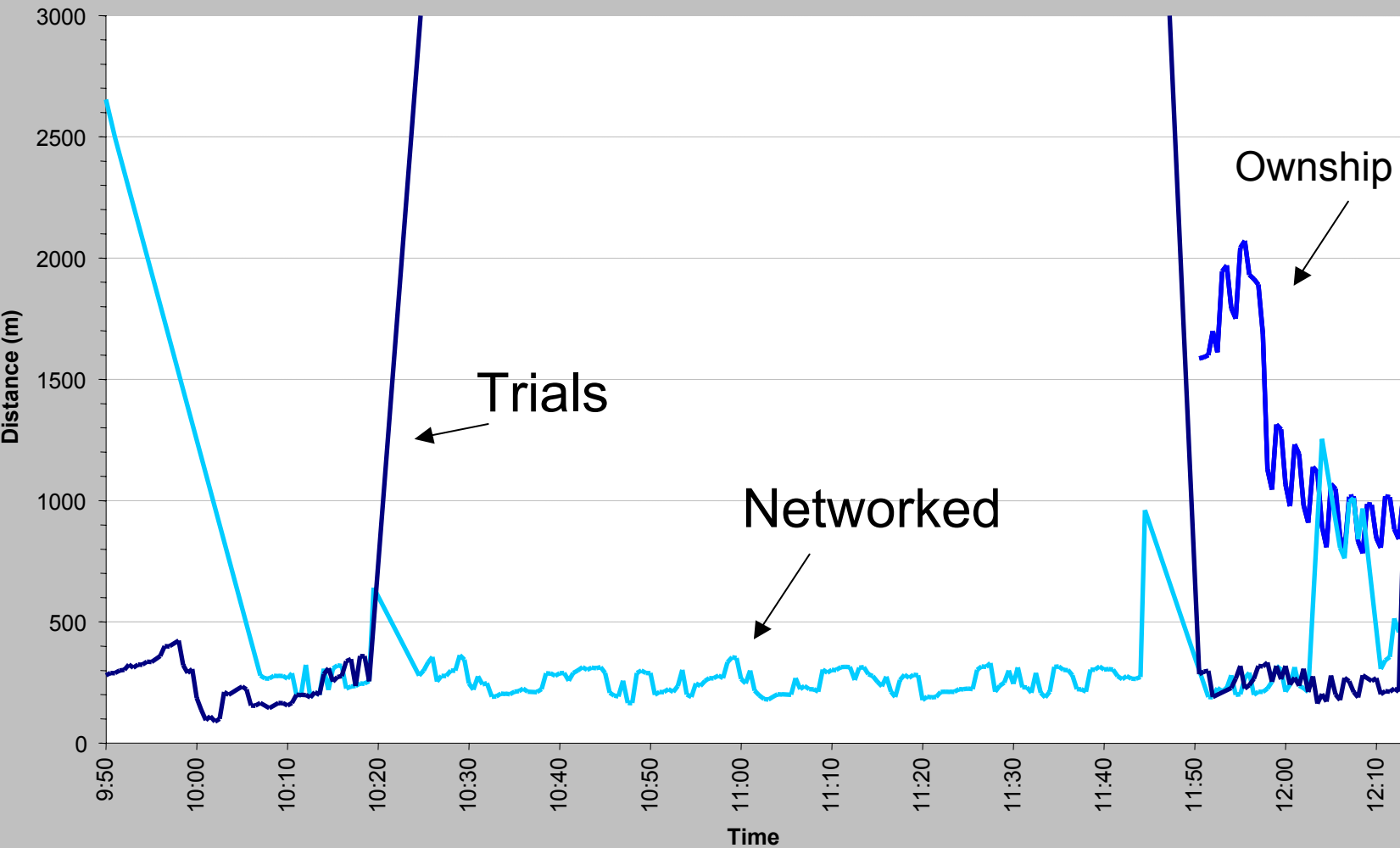
Average Positional Error of Constructed Tracks for FFG1





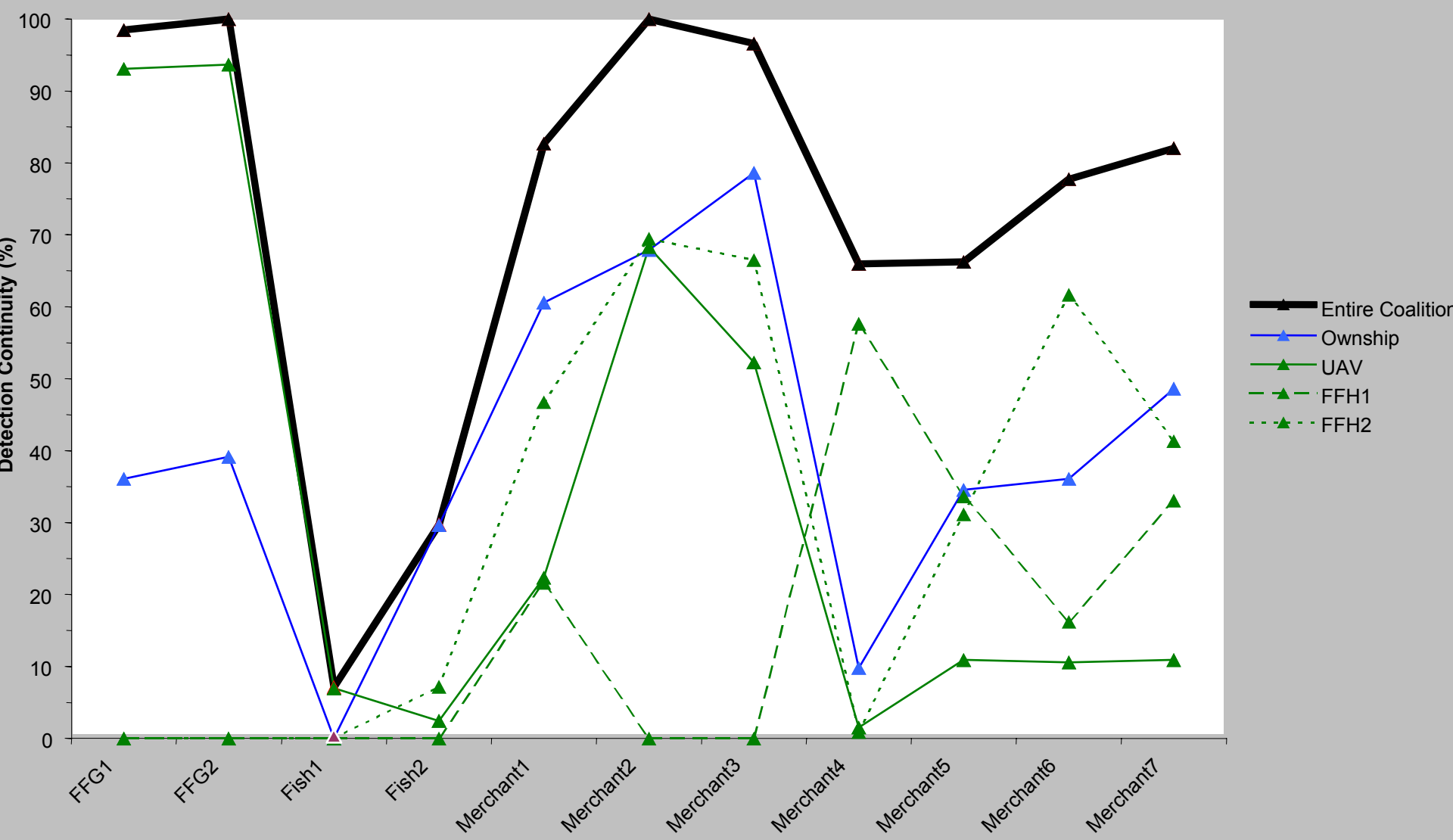
Priority Contacts 2

Average Positional Error of Constructed Tracks for FFG2



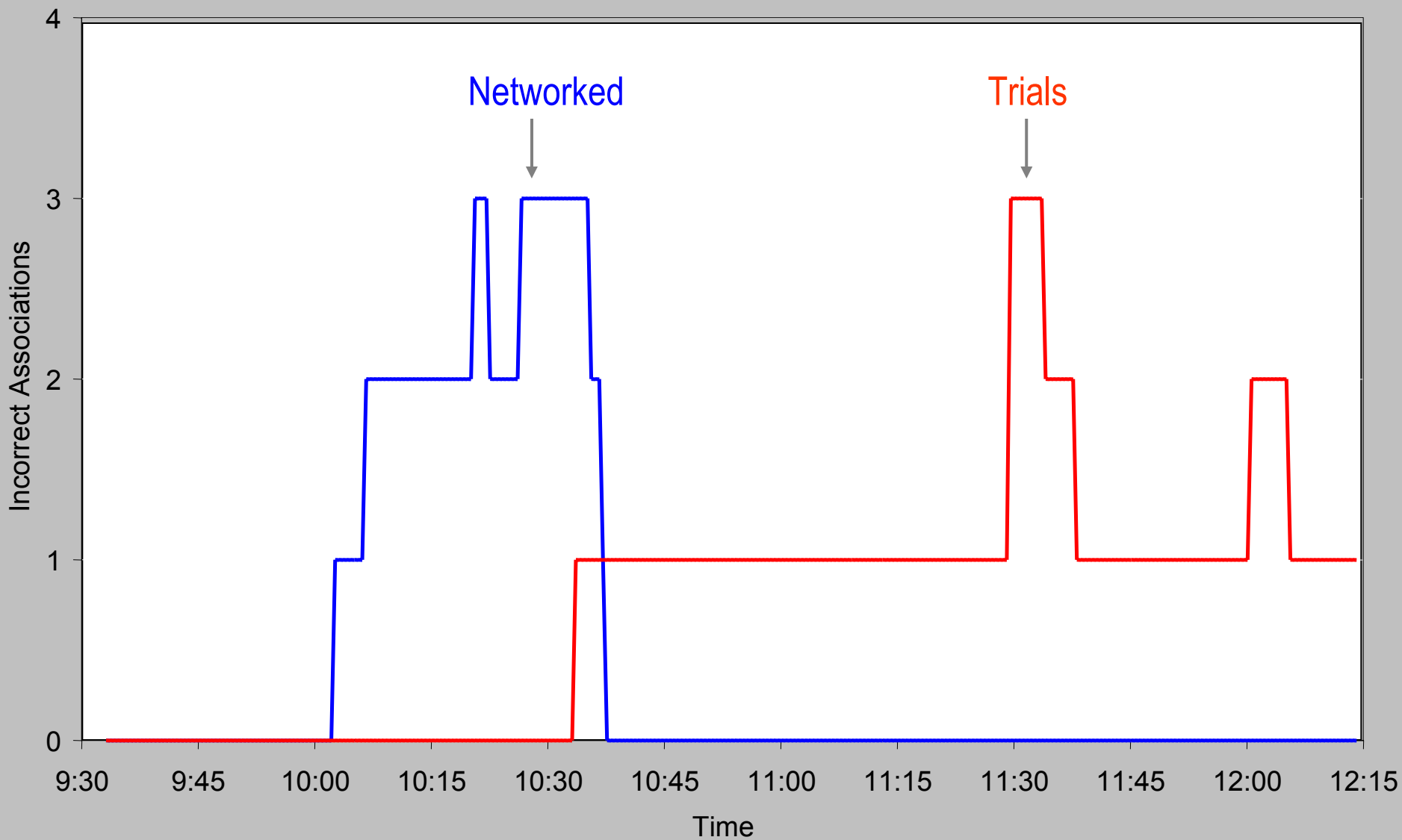


Track Continuity: Shared v Unique



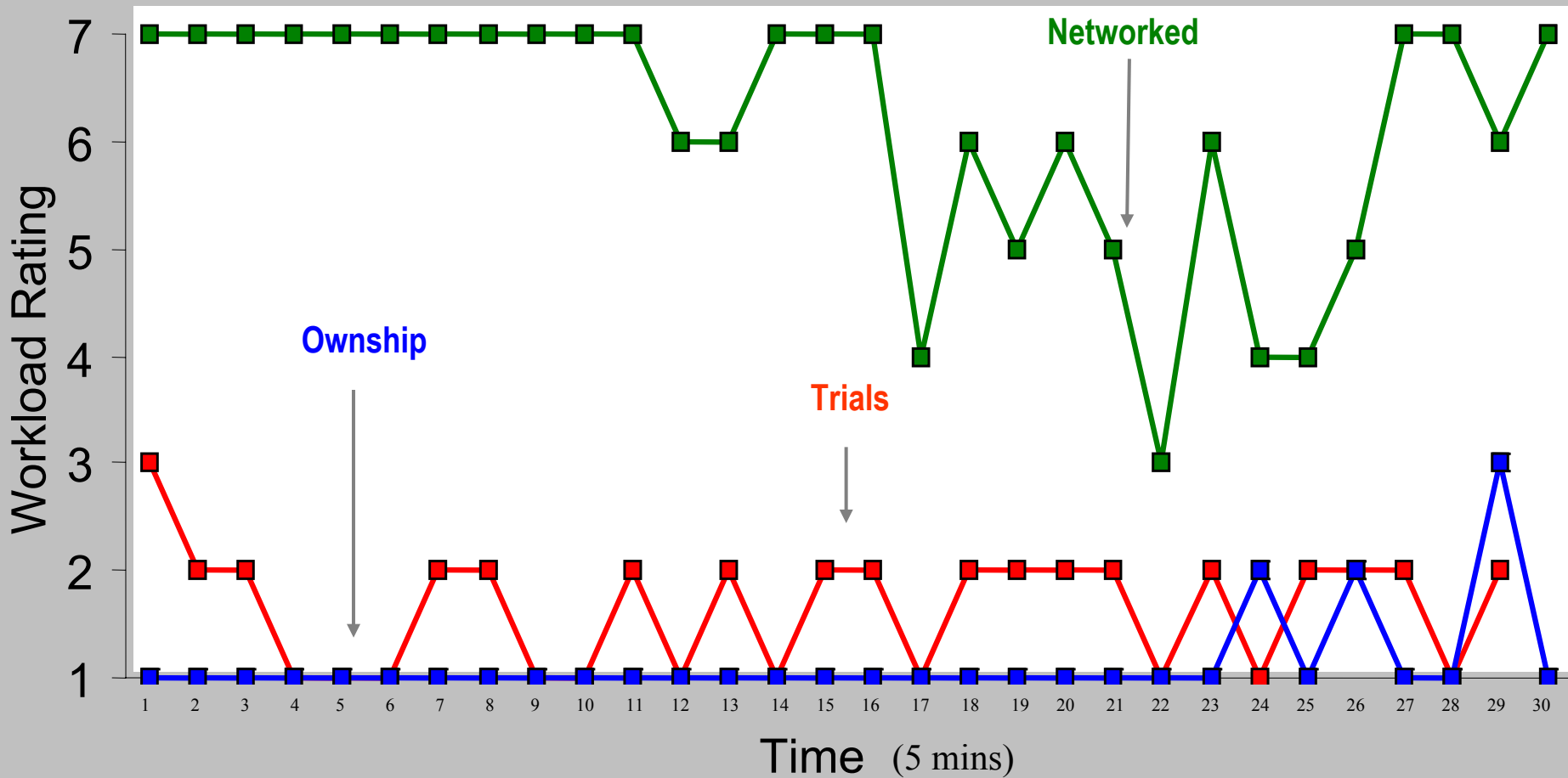


Operator Performance Comparisons – eg. Incorrect Associations (Error)



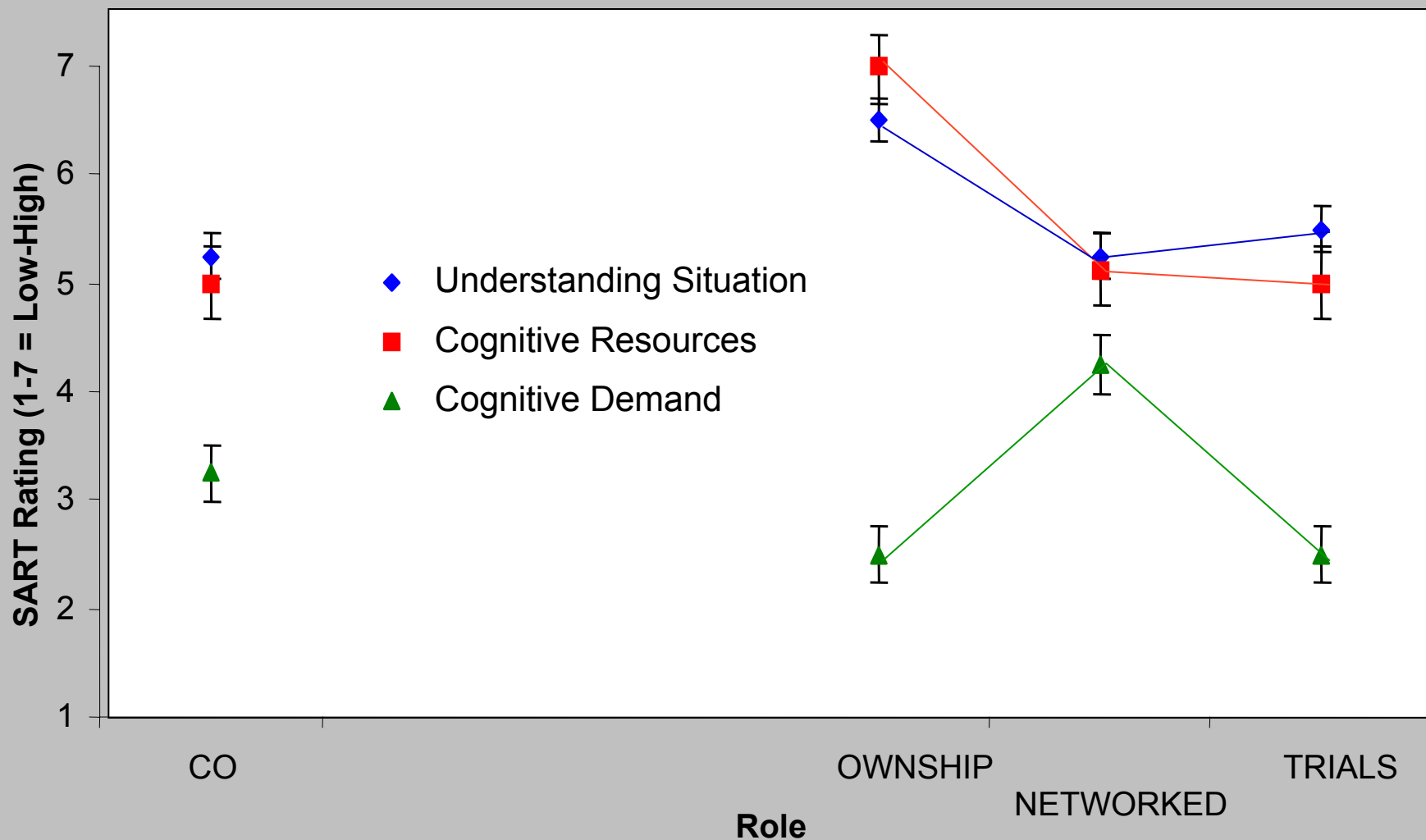


Moment-to-Moment Operator Workload (Developed at SPAWAR)





Subjective Situation Awareness (SART)



“Field of View” in NCW

Ownship

The screenshot displays a Networked Centralized Warfare (NCW) interface. At the top, it shows system parameters: "Horizon 3 - HEADING 150° COURSE 150° SPEED 4 kts DEPTH 17 m LATITUDE 8°39'27" S LONGITUDE 149°8'45" E TIME 10:13:39 AM CST".

The main display features a radar plot with concentric range rings and a central "Field of View" (FOV) circle. A yellow arrow points from the "Ownship" text to this FOV circle. The radar shows several tracks, with one track labeled "ARU:F2R0" highlighted in green. The track summary table on the right lists various tracks with their IDs, bearings, ranges, and ownership status.

ID	Bearing	Range	Depth	Class	Ownership
OS:CA1	253	-	-	-	Ownship
OSLEP	081	-	-	-	Ownship
OS	000	-	150	4	Ownship
S1	253	11,507	21.0	5	Ownship
S2	005	16,154	522	15.5	Ownship
OS:F1	083	-	-	-	Ownship
OS:CA3	081	-	-	-	Ownship
S3	063	10,071	320	15.6	Ownship
OSLEP#1	111	-	-	-	Ownship
OSLEP#2	113	-	-	-	Ownship

Below the radar plot, there are several control panels:

- Track Summary:** A table listing track details and buttons for "Selected Tracks" and "Member Tracks".
- Visibility:** Controls for "Members", "History", "Eligible", and "Lines".
- Map Controls:** Includes "Range", "Ownship", "Grid", "Map", "HDG", and "Platform".
- ARU:F2R0 Control:** A detailed control panel for the selected track, including "Track Disposal" and "Associate Using" options.
- S1 (S1) Control:** A control panel for another track, including "Track Disposal" and "Associate Using" options.

The interface is titled "Networked" at the bottom right.



Concluding Remarks

- ❑ Since our previous ICCRTS (Tynan et al, 2002) we have developed and conducted a number of simple exploratory experiments
- ❑ We have developed and proven a useful set of system metrics
- ❑ We have introduced and continue to develop a useful set of Human / operator metrics
- ❑ The challenge now is to address the actual operational benefits of NCW

