

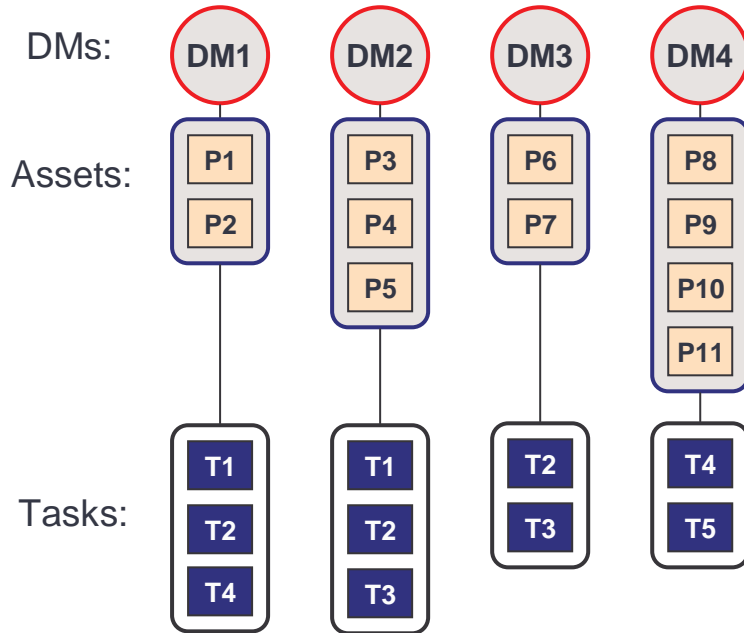
Application of **Network Optimization** to Design of Organizational Structures

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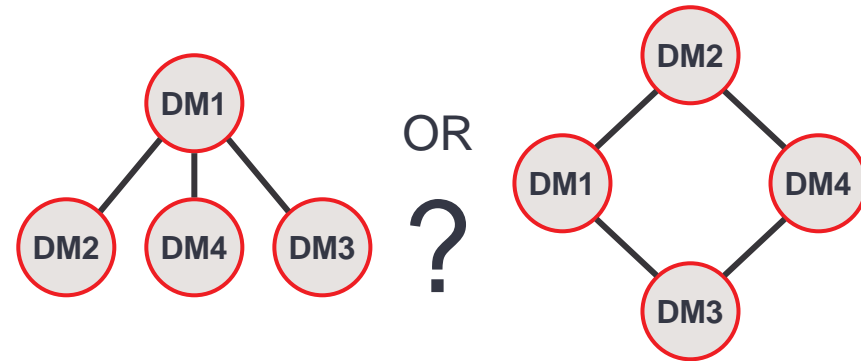
8-th International CCRTS, June, 2003
Track 3: Modeling and Simulation

Motivation: Example

Organization



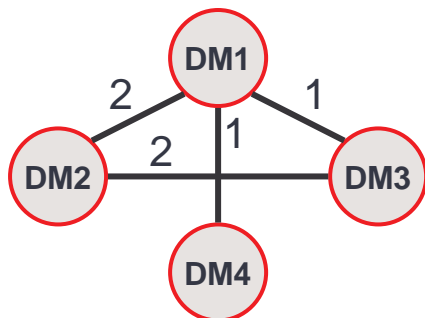
Structure



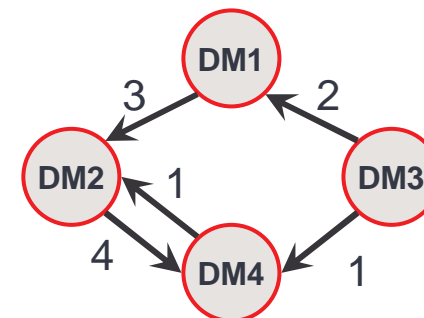
- Need to know the meaning of the network
- Need to optimize the processes
- What to communicate, and when**

Network of communication requirements due to:

Synchronization

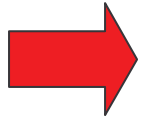


Task Information Flow

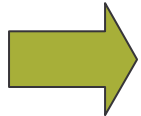


How to build a network to support this communication?

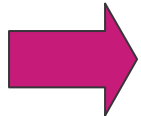
Overview



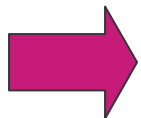
Networking: examples of *structures* and *flow* types



Information **flow**, **delay** models, and *optimal* flow *routing*



Network design problem



Example of network generation

Networking?

Structure Types

- Communication structure
- Management – overhead com-n, subordinate tasking, overseeing
- Distributed optimization
- ...

Communication Types

- Information flow – “what I know/found”
- Requests – “what I need”
- Decision exceptions
- ...

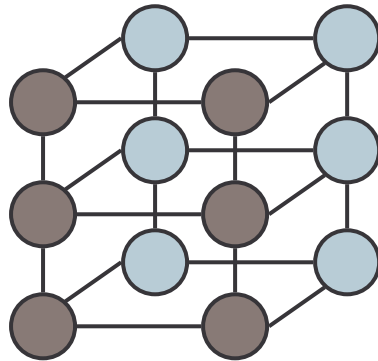
Flow Pattern

- Stochastic
- Deterministic

- **Known** agent-agent communication requirements (i.e., processes & com-n under ROE)
- **Unknown** (i.e., determined by task allocation, events, etc.)

Examples of Structures

Mesh or Hypercube



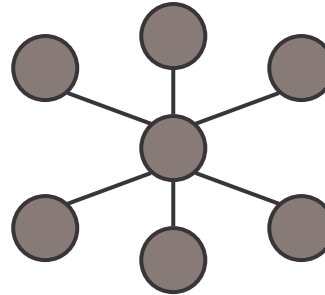
Pro: enabling multiple 2-node communication; redundancy for communication

Con: multiple connection needed; must use “smart” routing

Network constraints:

- Required/available Bandwidth
- Topology limitation
- Connectivity
- Overhead
- Cost
- Throughput
- Robustness

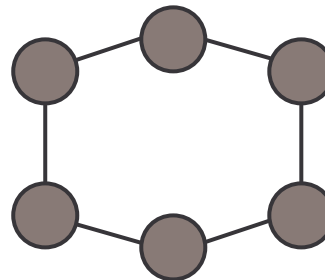
Star



Pro: when communication with few remote nodes is needed

Con: sensitive to central node operability

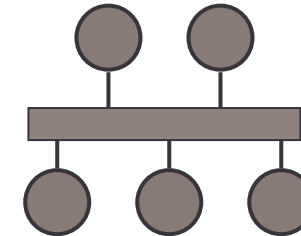
Ring



Pro: tight routing rules, easy to implement

Con: high overhead on links – slow transmission

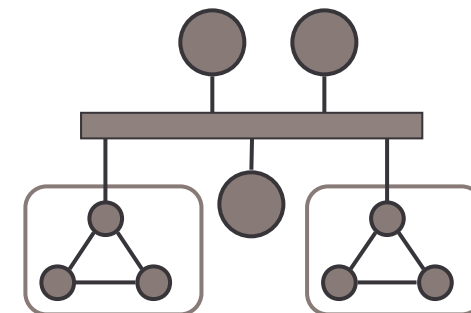
Bus network



Pro: individual node failures do not affect the flow

Con: might communicate at the same time – need priority routing

Heterarchy/Hybrid

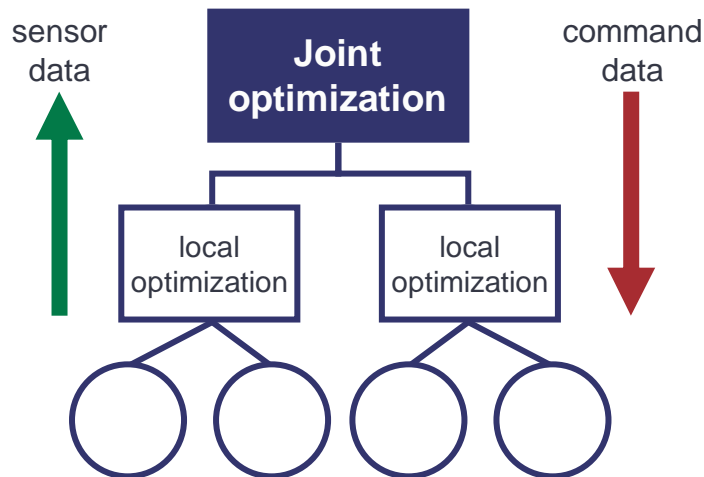


Pro: utilize good points of all structures for mission specifics

Hierarchy versus Heterarchy

Hierarchy

- *Distributed Optimization*
- *Hierarchical Command*



Pro:

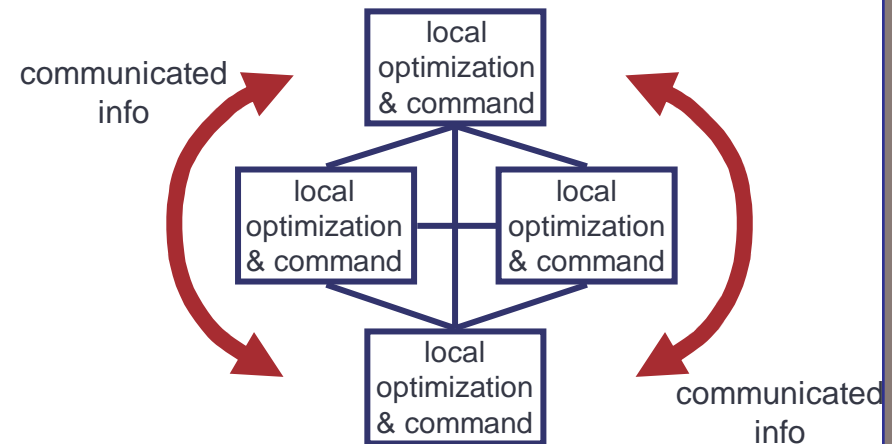
- Reduce complexity
- Limited functionality of individual cells

Cons:

- ❖ Lack of flexibility
- ❖ Slow response time
- ❖ High sensitivity
- ❖ Low fault-tolerance

Heterarchy

- *Distributed Optimization*
- *Heterarchical Command*



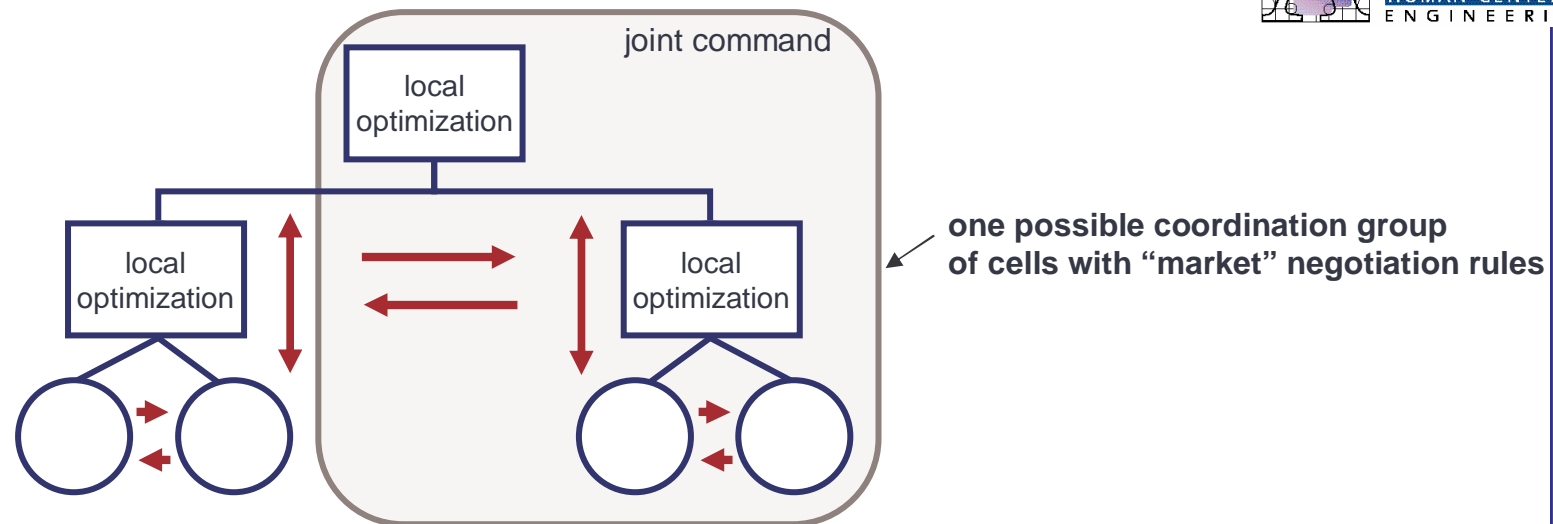
Pro:

- Flexibility & adaptability
- Improved fault tolerance
- Independent operations

Cons:

- ❖ Difficulty in designing local objectives: possible mismatch with global objective
- ❖ Lack of global information
- ❖ Sensitivity of collaboration rules

Hybrid Structures



Idea:

- ❑ Construct a structure that utilizes the benefits of both *hierarchy* and *heterarchy*

Result:

- Architecture with hierarchical structure which changes according to an environment
- Different communication/command/control rules that enable this change

Method/design:

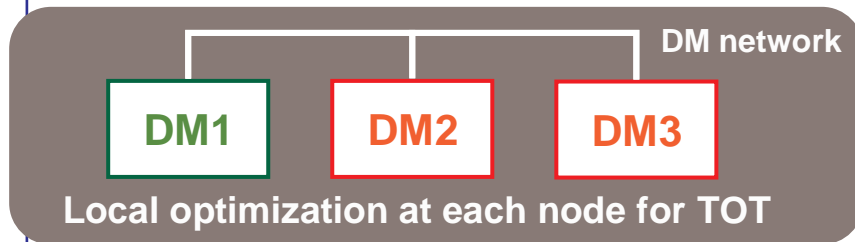
- ❖ Overcome structural rigidity and lack of flexibility by requesting/negotiating structural change (e.g., request supervision over rarely utilized resource)
- ❖ Communication among cells in the same level (horizontal)
- ❖ Communication among cells in different levels of current hierarchy (vertical)

Example: Task Assignment

Centralized global controller

Global controller - optimization

- Select Target & team TOT
- Select DMs/assets to prosecute targets



Target communication:
Controller accumulates the task information to send request to DMs for target prioritizing

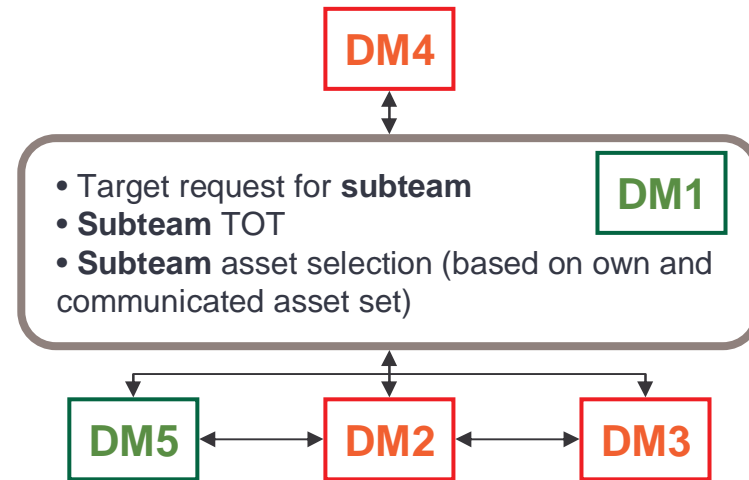
DM communicates sensor data

Allocation communication:
Controller uses asset/target priorities to determine asset/target allocation

DM computes asset priorities over requested or sensed targets

➤ Flat structure control

Decentralized heterarchical controller



- Target request for **subteam**
- **Subteam** TOT
- **Subteam** asset selection (based on own and communicated asset set)

Each DM executes functions of the global controller over its sub-network

Communication:

Superior: aggregated sensor data and selected assets & their priority

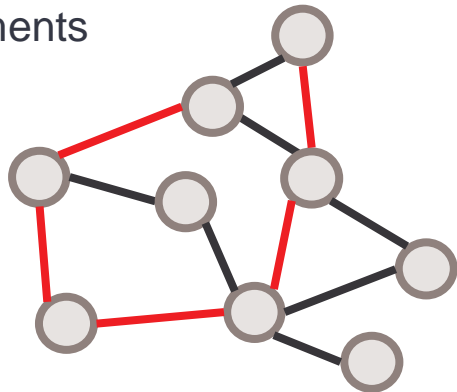
Subordinates: target request, asset selection

- Communicated information is minimized
- Optimization is distributed
- Complexity is lower

Examples of Flow Problems

- **Known Communication Requirements**
- **Unknown agent network**

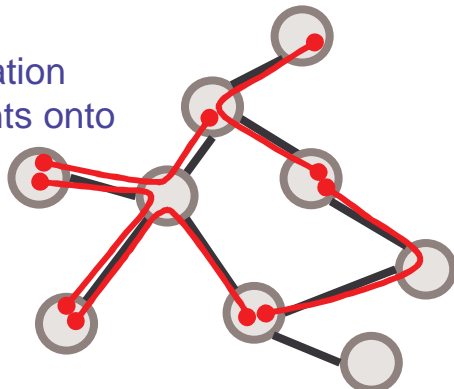
Input: network of communication requirements



Constraints: physical, topology, cognitive

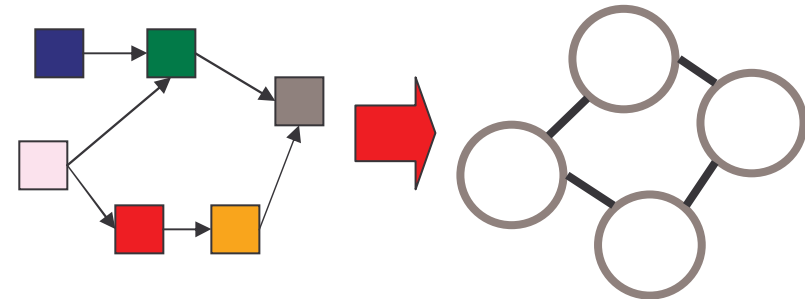
Output: agent network, information routing

Map the communication requirements onto constraints



- **Unknown Communication Requirements**
- **Known agent network**

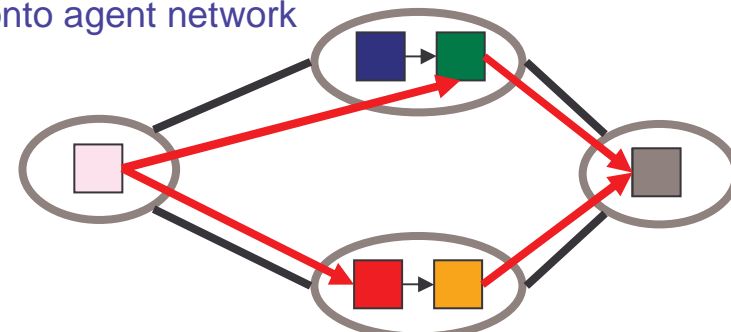
Input: task graph with flow requirements; agent communication network



Constraints: physical, topology, cognitive

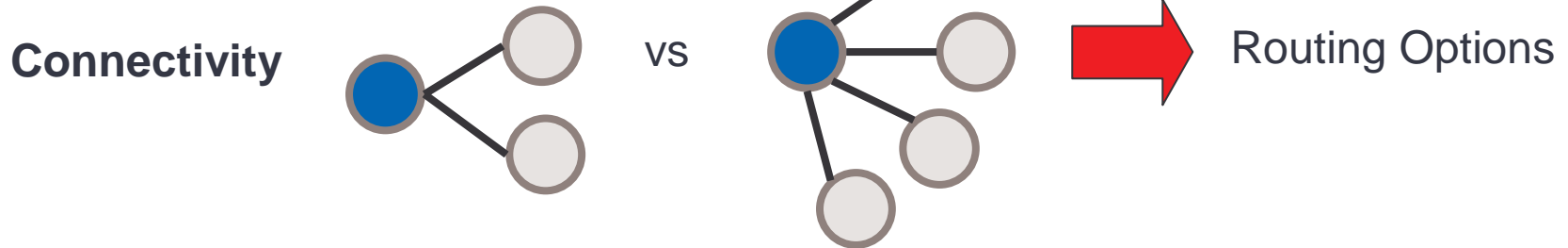
Output: agent network, information routing

Map the task graph onto agent network



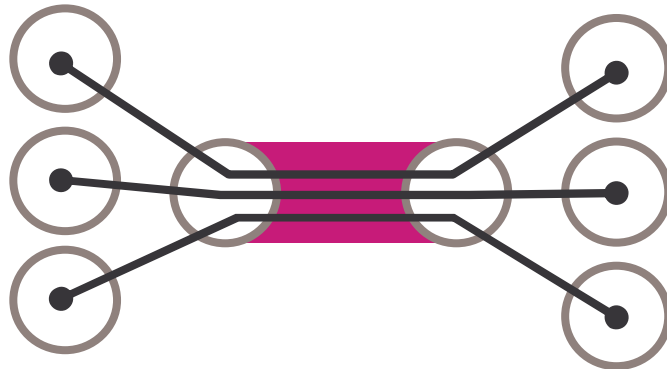
Network Constraints

Static Constraints

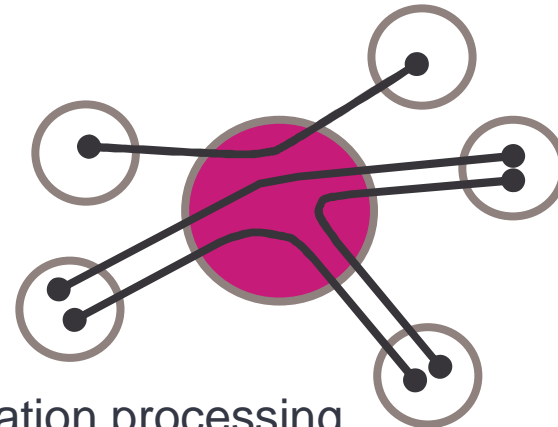


Dynamic Constraints

Link Overhead



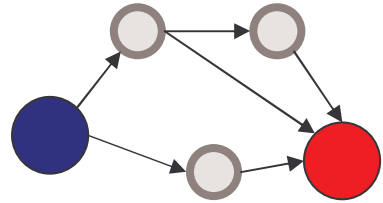
Node Overhead



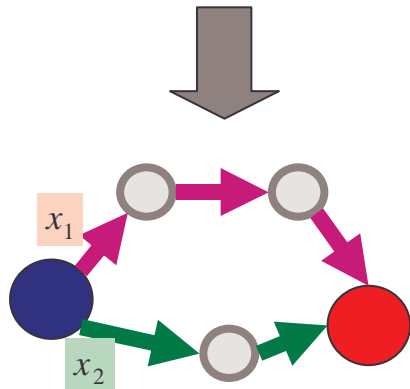
 Delays in communication and information processing

Routing & Network Architecture

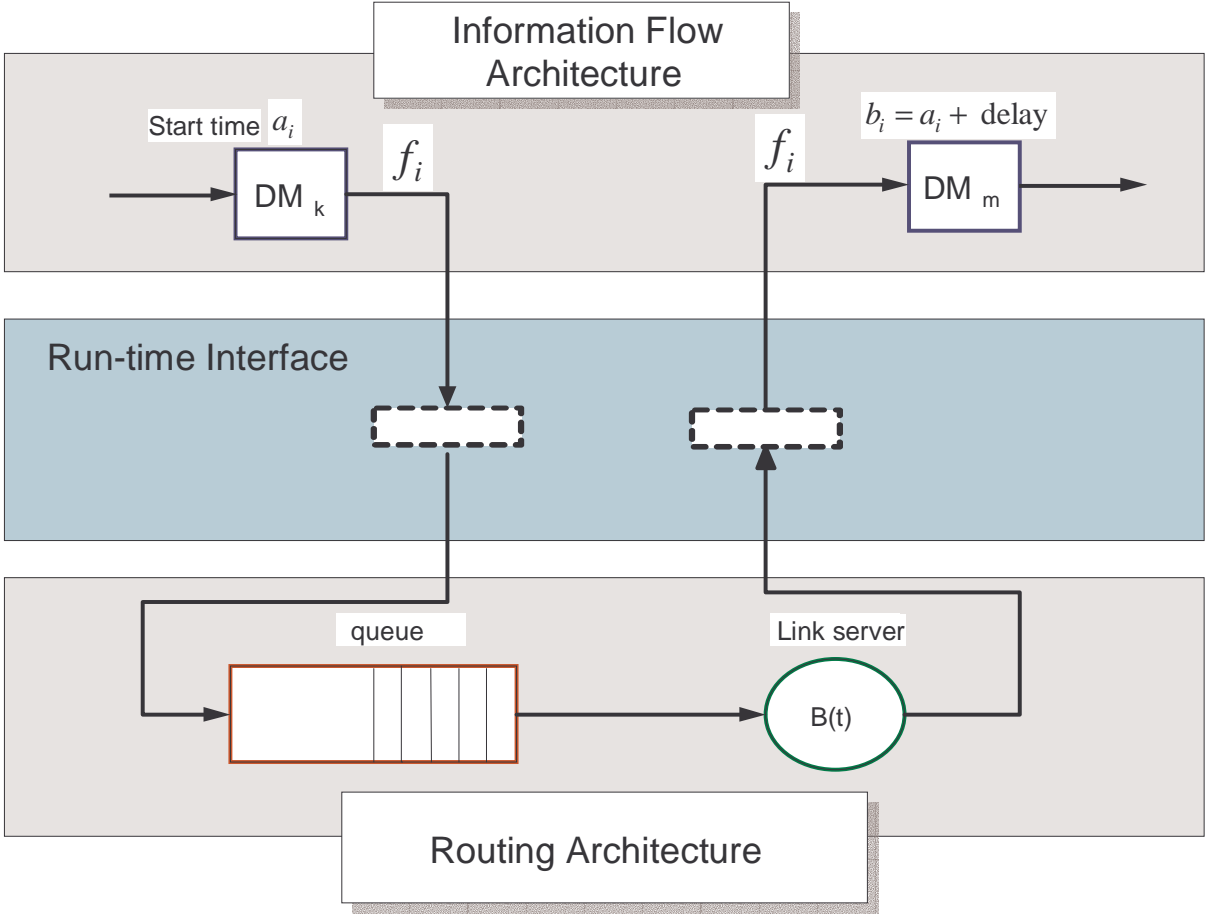
Routing:



Need to communicate from blue to red f_i units of information

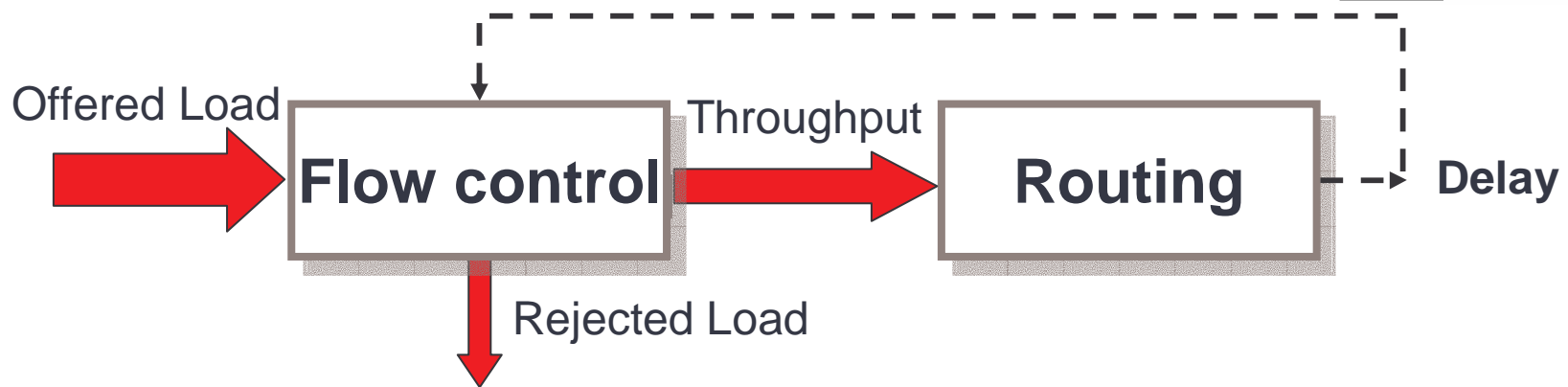


$$f_i = x_1 + x_2$$



Information is **split** to smaller portions to be communicated via different routes

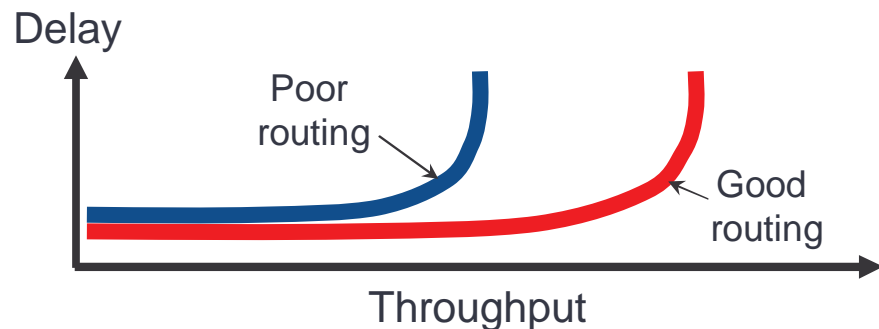
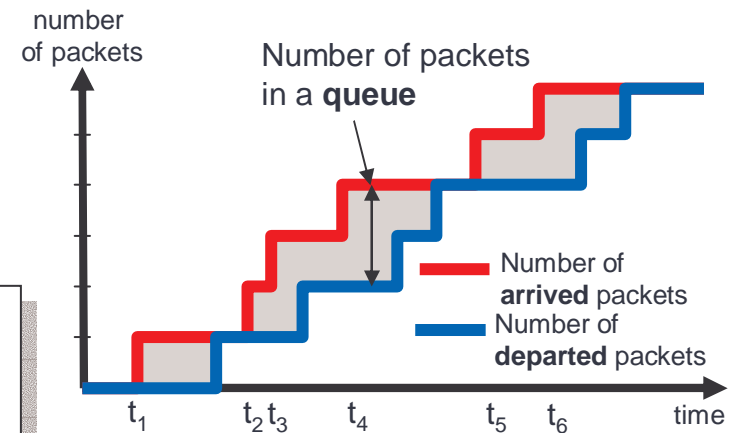
Controlling Information Flow



As the routing algorithm is more successful in keeping delay low, the flow control algorithm allows more traffic into the network

Routing algorithm performance measure:

1. **Throughput** = (offered load) – (rejected load) (**quantity**)
2. **Average packet delay** (**quality**)



Effects of good routing:

- (a) High offered load: **increase** throughput for the same average delay
- (b) Low offered load: **decrease** average delay

Network Design Problem

Given:

- A **traffic matrix** giving the input traffic flow from each agent to every other agent

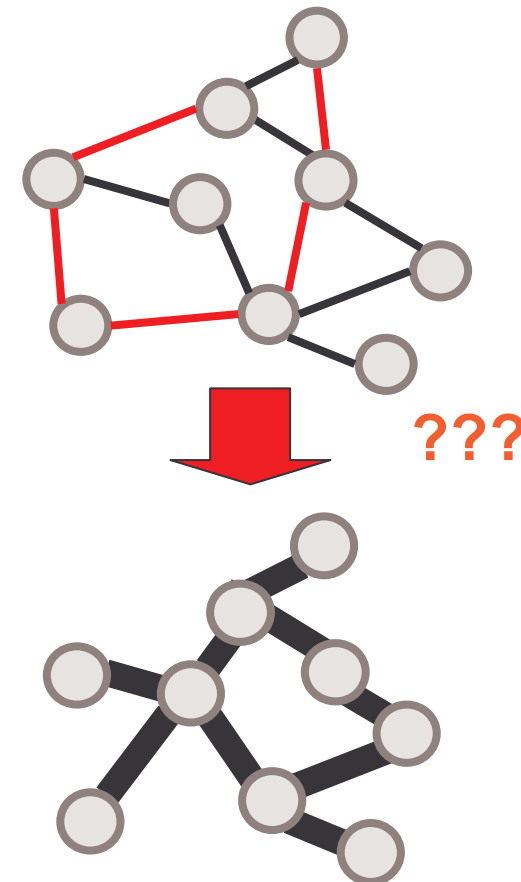
Want to design:

✚ The **topology of communication network** to service the communication requirements:

- location of the nodes
- the choice of links, and the capacity of each link
- info routing strategy

Design objectives:

- Keep the **average delay** per message below a given level (for the given nominal traffic demands and assuming some type of routing algorithm; use M/M/1 delay model)
- Satisfy some **reliability** constraints to guarantee the integrity of the network service in the face of a number of link and node failures
- Minimize the combination of **capital investment** and **operating costs** while meeting above objectives



Heuristic for Topology Generation



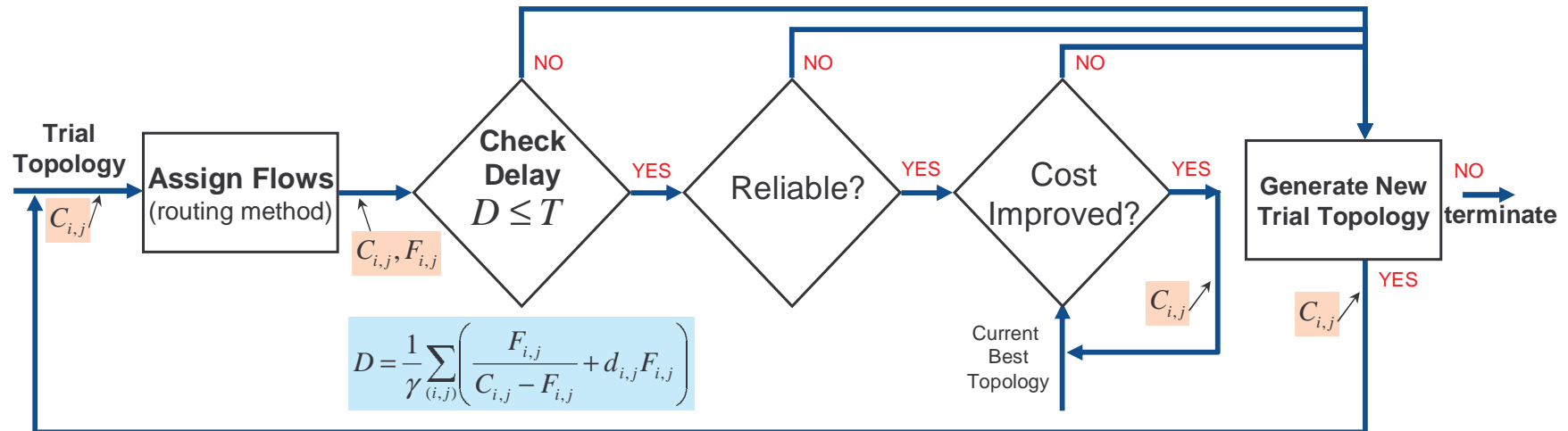
Routing algorithms:

- Optimal
- Shortest first derivative length
- Shortest path
- Shortest hops, etc.

flow assignment

Construction algorithms:

- Optimal
- Least cost, etc.



$$D = \frac{1}{\gamma_{(i,j)}} \left(\frac{F_{i,j}}{C_{i,j} - F_{i,j}} + d_{i,j} F_{i,j} \right)$$

Example

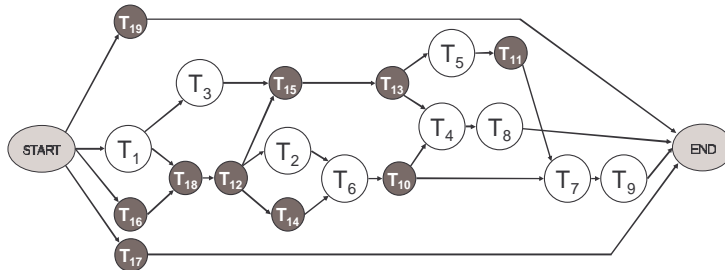
Given:

- Organization consisting of decision-makers (DMs) and assets/platforms
- Mission consisting of communicating tasks (task-graph)
- DM-task allocation and communication requirements due to:
 - ✓ task information flow
 - ✓ synchronization in multi-DM task processing

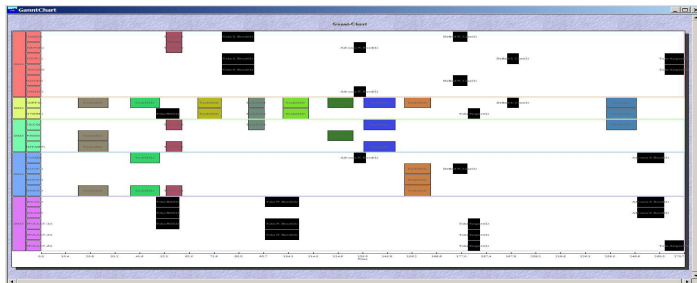
Want to design:

- ✚ The *topology of communication network* to service the communication requirements

Task Graph:



Gantt-Chart:



Communication due to simultaneous task processing: $[F_{k,m}^S(\hat{T})]$

	DM1	DM2	DM3	DM4	DM5
DM1	0	5.2	7.1	18.8	5.1
DM2	5.2	0	57.59	37	18.28
DM3	7.1	57.59	0	20.1	0
DM4	18.8	37	20.1	0	11.6
DM5	5.1	18.28	0	11.6	0

Communication due to inter-task information flow: $[F_{k,m}^I(\hat{T})]$

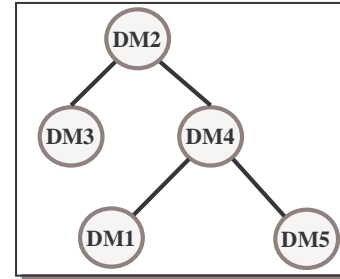
	DM1	DM2	DM3	DM4	DM5
DM1	0	15	5	5	5
DM2	20	0	20	25	15
DM3	15	20	0	15	10
DM4	10	15	0	0	15
DM5	10	10	0	5	0

Total Communication Rate Matrix:

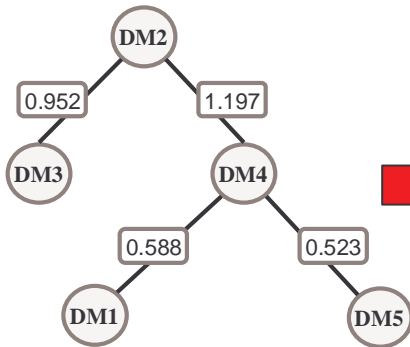
	DM1	DM2	DM3	DM4	DM5
DM1	0	0.075511	0.045232	0.088969	0.037756
DM2	0.094202	0	0.290045	0.231767	0.124407
DM3	0.082614	0.290045	0	0.13121	0.037382
DM4	0.10766	0.194385	0.075137	0	0.099436
DM5	0.056446	0.105716	0	0.062054	0

Example – Hierarchical Structure

Assume fixed network topology:



Communication Network
fixed structure \Rightarrow fixed routing
(unique path among nodes)

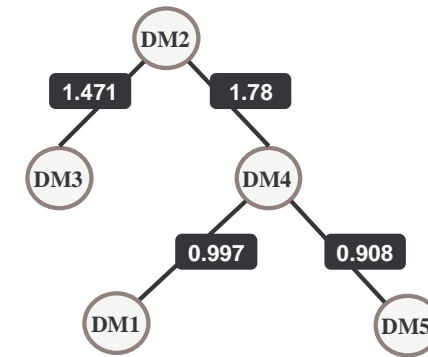


 - DM-DM communication rates

Optimal Link Capacities
found according to fixed routing:

$$C_{k,m} = \lambda_{k,m} \left(1 + \frac{1}{\hat{T}_D \gamma} \frac{\sum_{(r,u)} \sqrt{p_{r,u}} \lambda_{r,u}}{\sqrt{\lambda_{k,m} p_{k,m}}} \right)$$

Capacity Network
minimizing average packet delay



 - Link capacities

Fixed Routing (next DM ID)

Current DM	Destination DM				
	DM1	DM2	DM3	DM4	DM5
DM1	-	4	4	4	4
DM2	4	-	3	4	5
DM3	4	2	-	4	2
DM4	1	2	3	-	5
DM5	4	2	2	4	-

Network Cost:

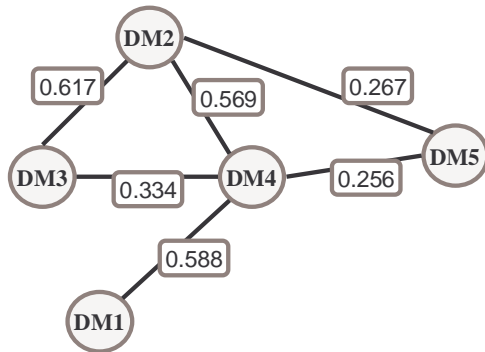
$$\sum_{k,m=1}^D p_{k,m} C_{k,m} = 5.156$$

Example – Networked Structure

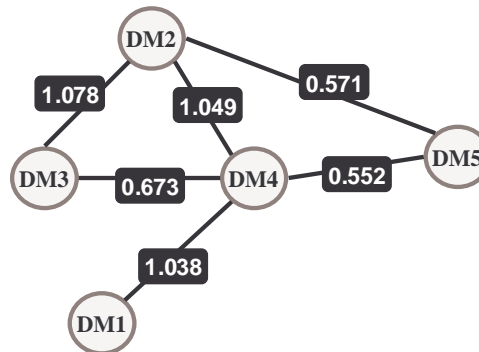
Delay function for link $k \rightarrow m$ to minimize:
(based on Little's theorem)

$$d_{k,m}(\lambda) = \frac{\lambda}{C_{k,m} - \lambda}$$

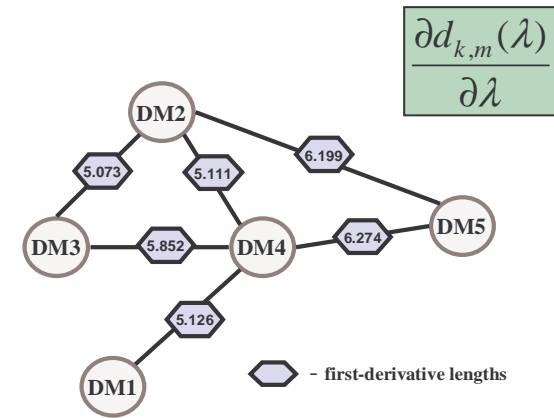
Communication Network
(with some routing)



Capacity Network
minimizing average packet delay



Network of First-Derivatives



Network and routing are optimal!

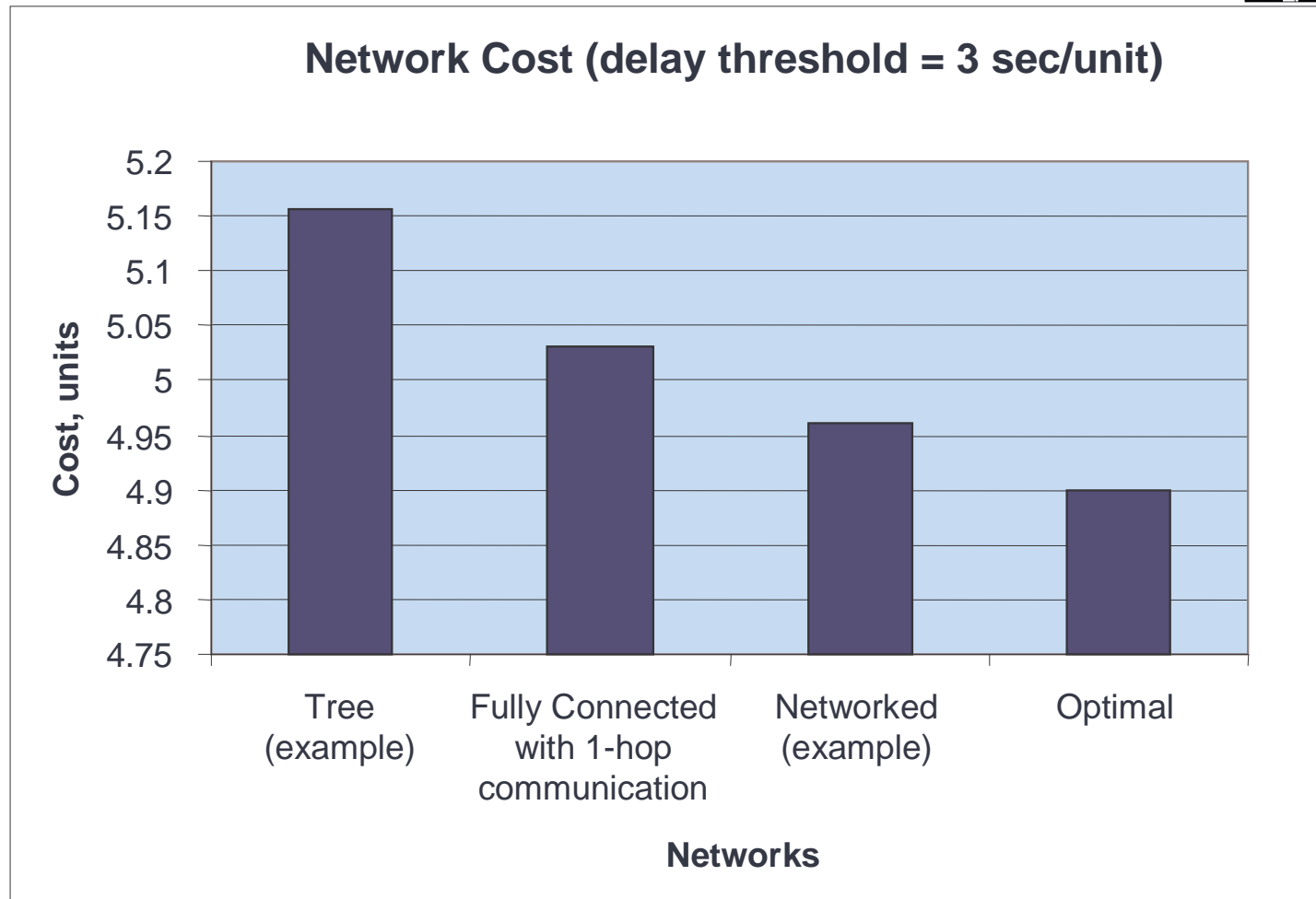
Why?

Network Cost:

$$\sum_{k,m=1}^D p_{k,m} C_{k,m} = 4.961$$

Theorem:
The routing of information is optimal \Leftrightarrow routing is performed according to shortest paths in derivative length

Example – Benefits of Networks



Network optimization allows to:

- decrease the cost of its construction while maintaining the same delay rate
- decrease delay while maintaining the same network cost

Conclusions

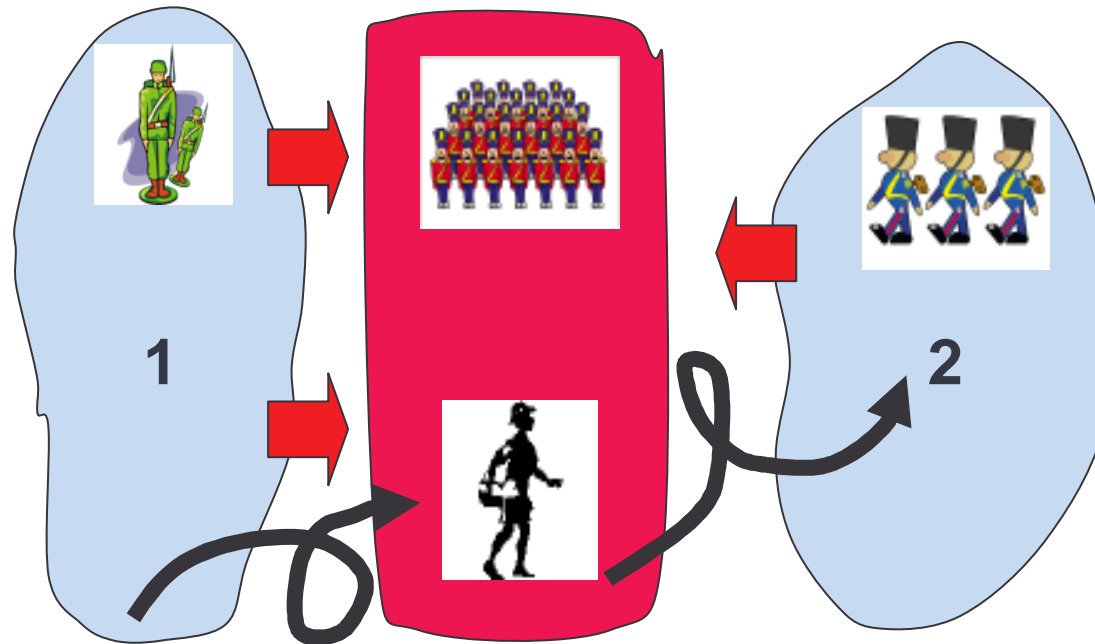
- Efficient *routing of information* among agents in the network allows to **minimize system delays**

- We presented the methodology to *construct networks* of communicating agents to sustain required communication while optimizing **delay/cost** and satisfying **reliability**

- ✚ Applications:
 - Information routing
 - Topology design
 - Training and adaptation applications

Distributed Algorithm Problem

How to synchronize?



Constraints:

If only **one blue** army attacks – **red** wins

If **both blue** attack – **blue** win

Communication:

Via messenger

Problem:

Messenger is either caught or goes through, but the sending army does not know that

Message:

Army 1: “Let’s attack at 12pm on Sunday; please acknowledge if you agree”

Army 2: “We agree; send the acknowledgement if you receive our message”

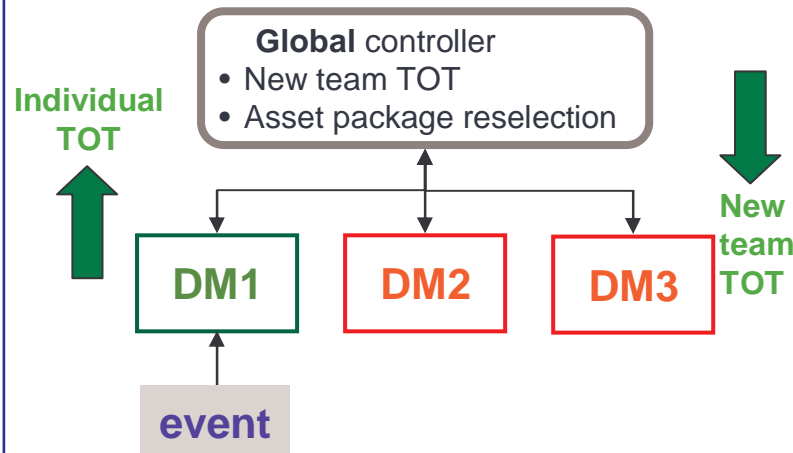
Example: Asset Synchronization

Trigger for communication:

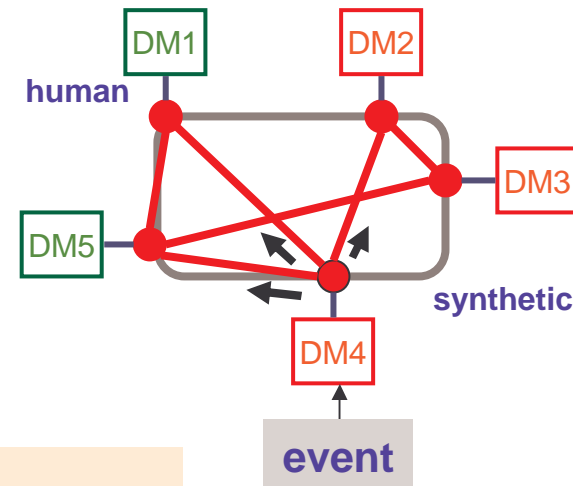
Event, i.e.:

asset is killed, obstacle appears, new TOT is set, etc.

Centralized



Decentralized Networked



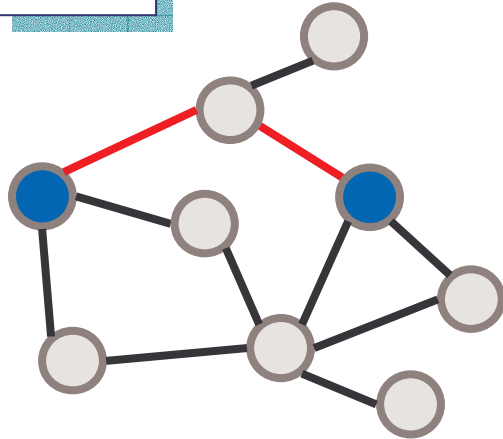
Communication:
New TOT via communication network

- Optimal solution
- Sensitivity of structure (to global controller functioning)

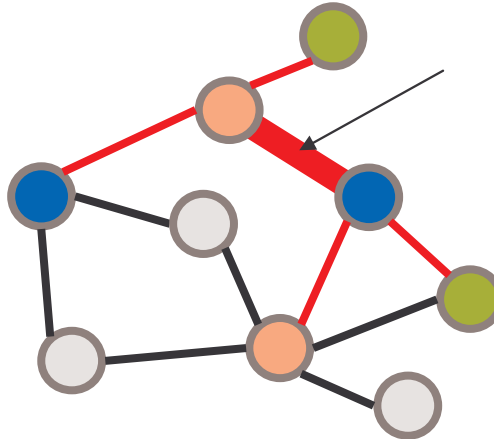
- Robustness
- Multiple cycles before converging is pair-wise communication
- Teaming ("market") reduces the cycle

Routing: Overhead

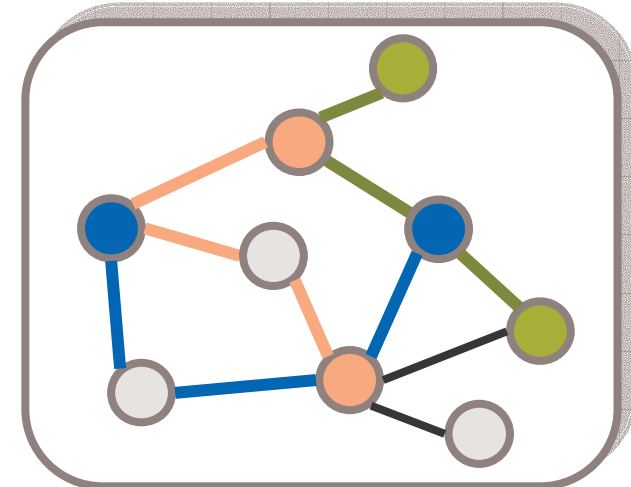
Link



Shortest Path:

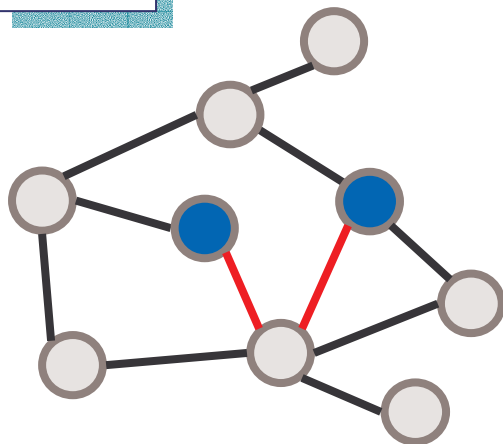


Alternative:

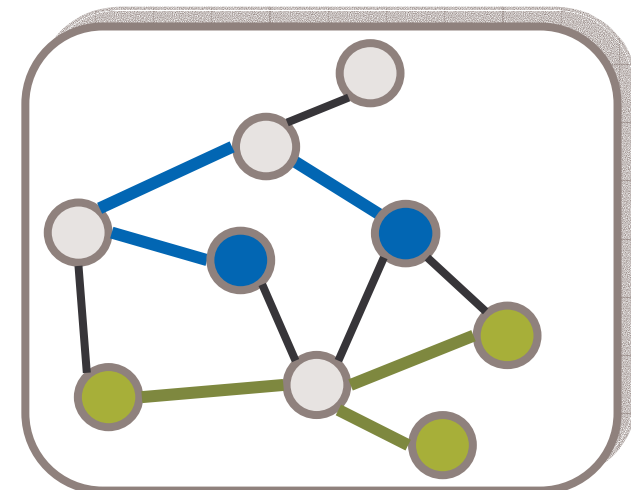
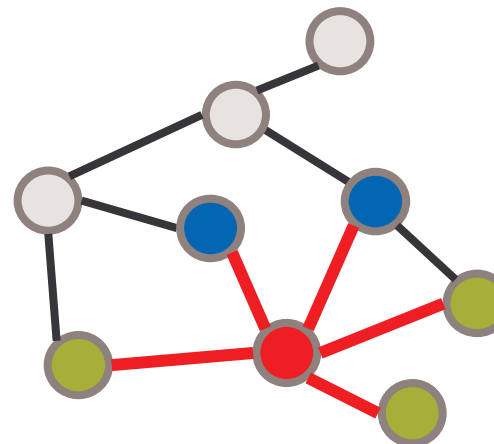


Pro: small overheads
Con: longer paths

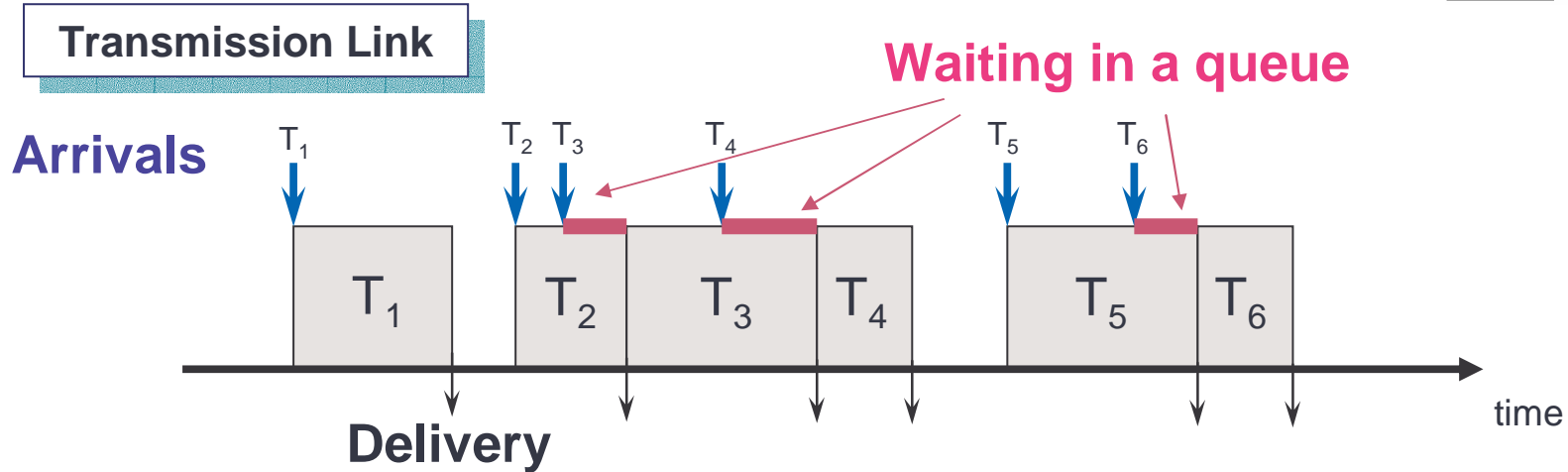
Node



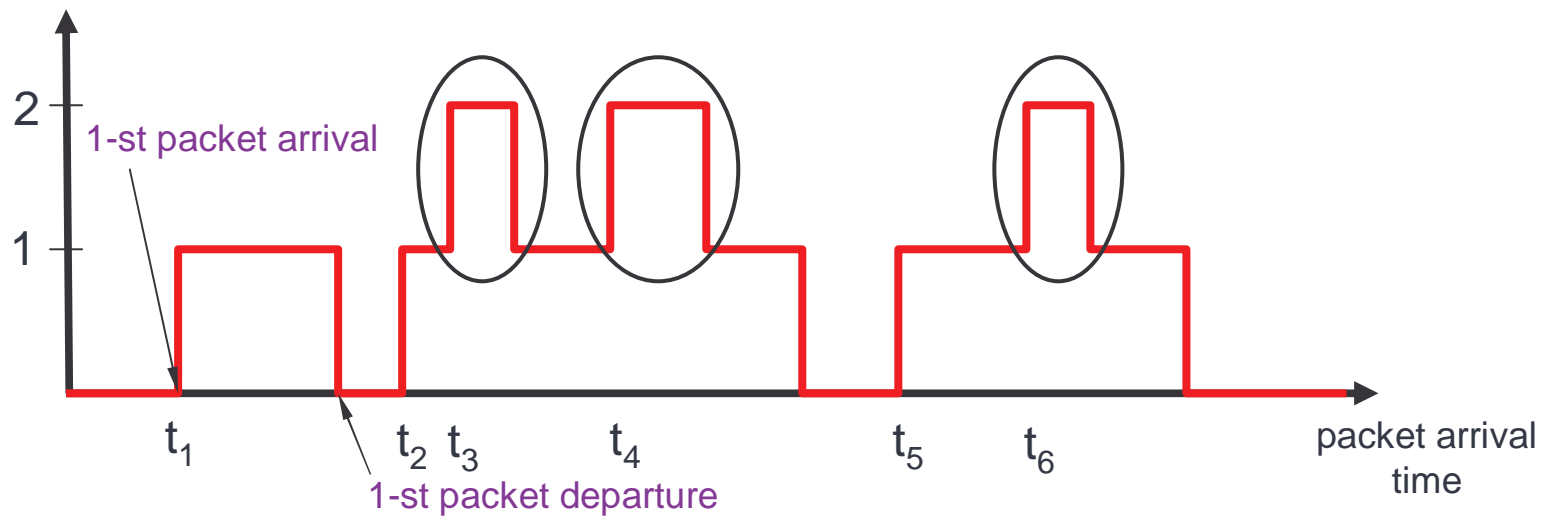
Shortest Path:



Delay Model (single channel)



Number of packets waiting for transmission



Delay Model – Little’s Theorem

$N(t)$ Number of packets in the system at time t

T_i Time to transfer i -th packet

Little’s theorem:

$$N = \lambda \cdot T$$

average number of packets in queue =
(average arrival rate) • (delay time)

Time average arrival rate over $[0, t]$

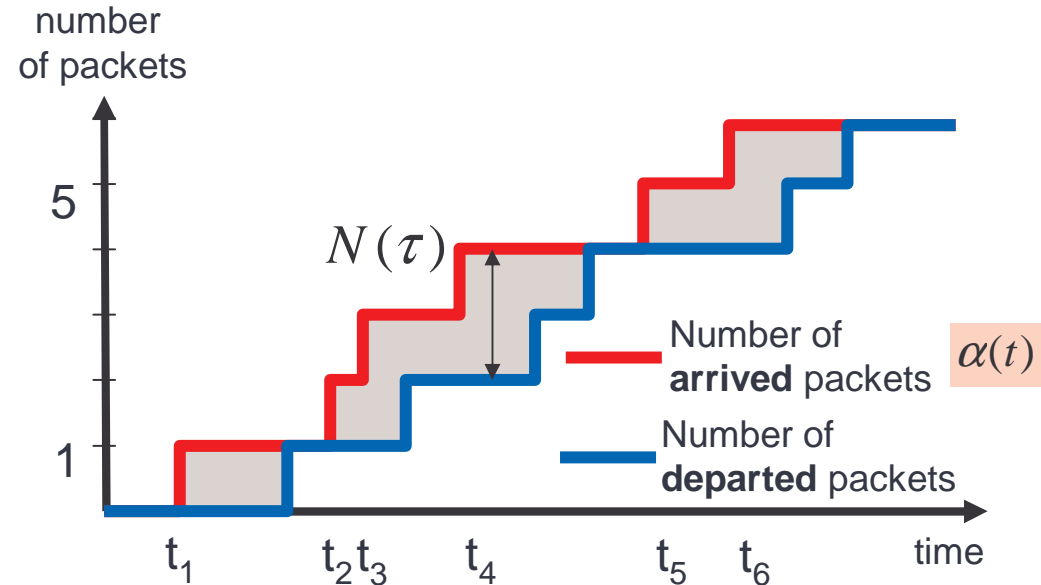
$$\lambda_t = \frac{\alpha(t)}{t} \xrightarrow{t \rightarrow \infty} \lambda$$

Time average of packet delay over $[0, t]$

$$T_t = \frac{\sum_{i=0}^{\alpha(t)} T_i}{\alpha(t)} \xrightarrow{t \rightarrow \infty} T$$

“Typical” (average) number of packets in the system observed up to time t

$$N_t = \frac{1}{t} \int_0^t N(\tau) d\tau \xrightarrow{t \rightarrow \infty} N$$



Delay Model – M/M/1

Utilize **M/M/1** queuing model:

- single server (one transmission channel)
- “memoryless” arrival (Poisson) – average number of arrivals per unit time (packets/sec) = λ
- “memoryless” transfer (Poisson) – average number of packets transferred per unit time = μ

Note: definition of Poisson transfer rate only mean that probability to transfer **n**-th packet in **s** units of time or less is equal to

$$P\{s_n \leq s\} = 1 - e^{-\mu s}$$

Also, average number of packets is equal to

$$N = \frac{\lambda}{\mu - \lambda}$$

Application to information flow and routing:

channel capacity = C (bits/sec)

information arrival rate = λ (packets/sec)

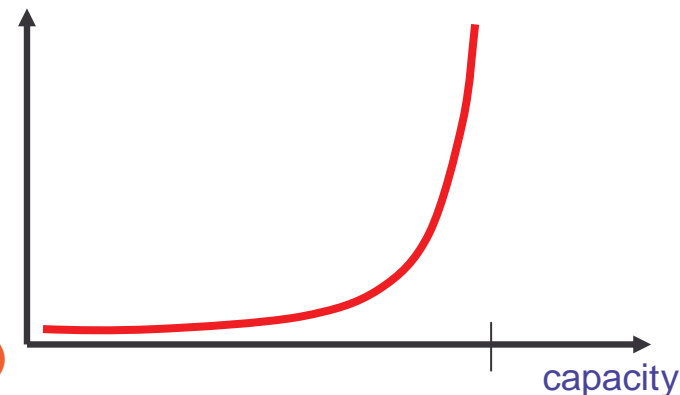
average packet length = L (bits)

average delay per packet (wait + transfer) is **proportional** to average packet length and **inversely proportional** to marginal capacity

$$T = \frac{L}{C - \lambda L}$$

info flow (bits/sec)

Average delay



Optimal Routing Problem

Input: agent communication requirement network

Need: communication routing (**who talks through whom**)

Objective: minimize overall communication delays

Network communication delay modeling:

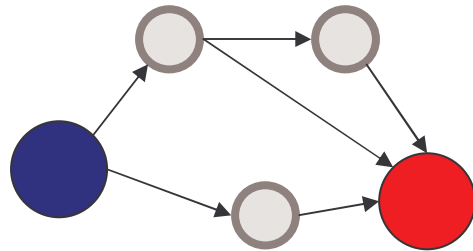
Accumulated (over all packets) delay at a single channel ($i \rightarrow j$) with flow $F_{i,j}$ and capacity $C_{i,j}$ is equal to

$$D_{i,j}(F_{i,j}) = \frac{F_{i,j}}{C_{i,j} - F_{i,j}}$$

Aggregated network delay:

$$D = \sum_{(i,j)} D_{i,j}(F_{i,j})$$

Optimal Routing Idea

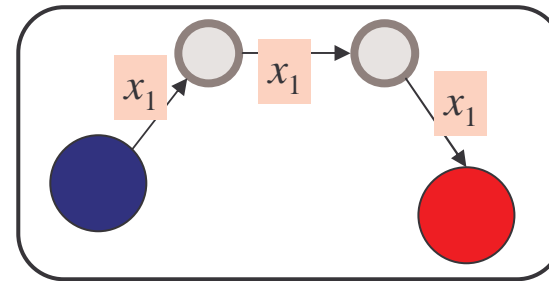


Need to communicate from **blue** to **red** f_w units of information

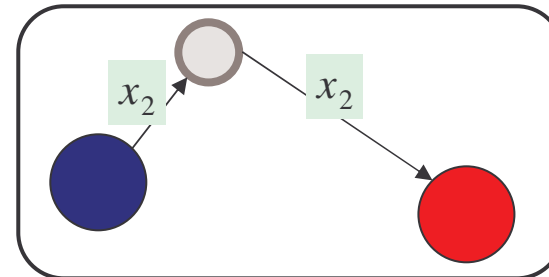
Information is **split** to smaller portions to be communicated via different routes

$$f_w = x_1 + x_2 + x_3$$

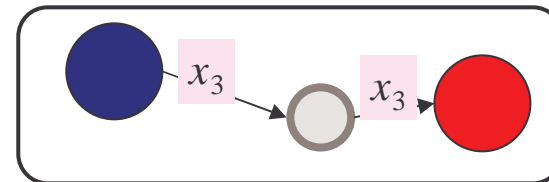
$$F_{i,j} = \sum_{\substack{\text{all paths } p \\ \text{containing link } (i,j)}} x_p$$



x_1



x_2



x_3

$$\begin{aligned} & \min \sum_{(i,j)} D_{i,j} [F_{i,j}] \\ & \text{subject to } \begin{cases} \sum_{p \in P_w} x_p = f_w, \text{ for } \forall w \in W \\ x_p \geq 0, \text{ for } \forall p \in P_w, w \in W \end{cases} \end{aligned}$$

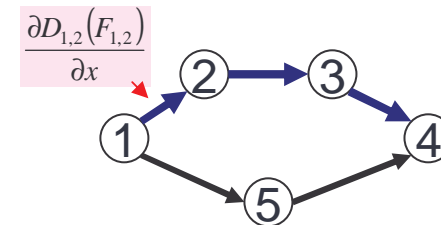
Optimal Routing Solution

Using Lagrangian relaxation, we find:

1. Optimal path flow is positive only on paths with **minimum first derivative flow**

$$\frac{\partial D_{i,j}(F_{i,j})}{\partial x}, F_{i,j} = \sum_{\substack{\text{all paths } p \\ \text{containing link } (i,j)}} x_p$$

$$\frac{\partial D_{1,2}(F_{1,2})}{\partial x} + \frac{\partial D_{2,3}(F_{2,3})}{\partial x} + \frac{\partial D_{3,4}(F_{3,4})}{\partial x} \leq \frac{\partial D_{1,5}(F_{1,5})}{\partial x} + \frac{\partial D_{5,4}(F_{5,4})}{\partial x}$$

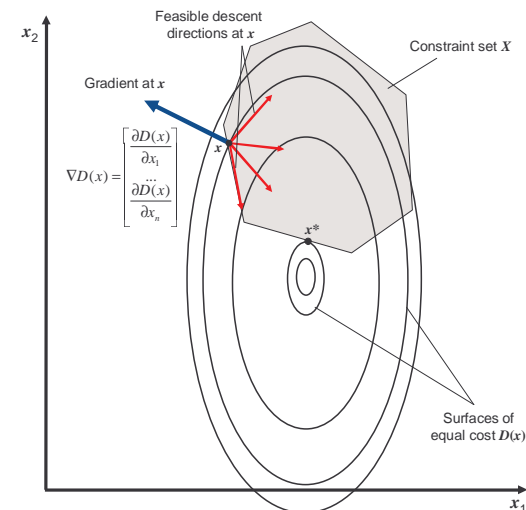


2. The optimal paths between any two communicating agents, among which the information flow is split, must have **equal first derivative length**

Consequence:

Can use optimization methods, such as

- Feasible directions
- Frank-Wolfe (flow deviation) method
- Projection methods



Problem Formulation

Routing

$$\min \sum_{(i,j)} \frac{F_{i,j}}{C_{i,j} - F_{i,j}}$$

subject to

$$\begin{cases} \sum_{p \in P_w} x_p = f_w, \text{ for } \forall w \in W \\ x_p \geq 0, \text{ for } \forall p \in P_w, w \in W \end{cases}$$

- **Objective:** minimize **delays**
- **Constraints:** flow conservation
- **Fixed:** **capacities**
- **Manipulate:** flow routing

Capacity Assignment

$$\min \sum_{(i,j)} p_{i,j} C_{i,j}$$

subject to

$$\begin{cases} \frac{1}{\gamma} \sum_{(i,j)} \frac{F_{i,j}}{C_{i,j} - F_{i,j}} \leq T \\ C_{i,j} \geq 0, \text{ for } \forall i, j \end{cases}$$

- **Objective:** minimize **network cost**
- **Constraints:** flow conservation, delay below threshold
- **Manipulate:** **capacities, flows**

Solution to *capacity assignment* problem

Optimal cost:

$$\min_{F_{i,j}} \sum_{(i,j)} p_{i,j} F_{i,j} + \frac{1}{T\gamma} \left(\sum_{(i,j)} \sqrt{p_{i,j} F_{i,j}} \right)^2$$

Optimal capacity:

$$C_{i,j} = F_{i,j} \left(1 + \frac{1}{T\gamma} \frac{\sum_{(m,n)} \sqrt{p_{m,n} F_{m,n}}}{\sqrt{F_{i,j} p_{i,j}}} \right)$$

PROBLEM!!!!!!!!

Tend to get networks with **low connectivity** (few links with large capacities) – violate **reliability**