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Opportunities for Next Generation BML: Semantic C-BML

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Abstract

Battle Management Language is an unambiguous language to facilitate the command and control of forces and equipment in a military environment and to provide information for situational awareness. Coalition Battle Management language (C-BML) is a standardization effort to define BML in a Coalition environment to support information exchange among a range of simulation systems and command and control (c2) Systems. A SISO Product Development Group (PDG) was formed in the spring of 2006 to implement the standardization process. The group has concluded the first phase of development; that phase is focused on the formalization of syntax.

Recent coalition experiments have shown that complex XML schemas can impede development and testing speed. This paper demonstrates that an ontology-based model can provide better readability and allow users to generate necessary XML components. A semantically enriched C-BML can support processing C-BML expressions based on semantic constraints. This paper presents an analysis of the applicability of the current standards of semantic representation languages including Resource Description Framework (RDF) and Web Ontology Language (OWL) to a C-BML Ontology. We explore ontological alignment of C-BML Ontology with upper level ontologies for time. Based on recent experiments of the NATO Modeling and Simulation Group technical activity 085, we present use-cases and benefits of having ontological reasoning as a means of processing C-BML documents.
1. Introduction

Battle Management Language was developed to represent and exchange digitized Command and Control (C2) information among C2 and simulation systems. The language makes use of a grammar called the C2 Lexical Grammar (C2LG)[1]. Since its development, BML has been in a number of applications and scenarios ranging from proof of concept for military applications, testing interoperability of C2 and simulation Systems for use in real-time C2 operational environment. In the fall of 2006 Simulation Interoperability Standards Organization formed a Product Development Group to oversee the development of a standard Language that can be used in a coalition environment [2].

In a world where alliances and coalitions are increasingly significant to military operations, there is need for a language that can work not only across multiple environments but also harness the power of semantic BML for meaningful interoperability [3]. C-BML is based on a significant body of research [4].

Recent coalition experiments [23] have shown that working with a complex XML schema limits the speed of developing, integrating and testing C2 systems and simulation systems. Full compliance with a complex schema requires a system to parse and process for every element in the schema regardless of whether or not most elements in the schema are used. In the recent MSG-085 experiments, most elements in a complex schema (Phase 1 draft schema of C-BML) did not prove necessary. A formal ontology-based model, combined with procedures to create and extend XML syntax, enhances readability and helps with an efficient prototyping and testing process. Such an ontology captures entities, relationships from a data model and allows users to focus on and even reason with necessary components. In addition, there has been research to show a process to create XML schemas from an ontology [24]. This allows users to creating a workable, non-complex schema that’s appropriate for their use and yet compliant with the standard.

This paper addresses possibilities for an ontology-based approach to C-BML. Section 2 describes the current state of the standardization process of C-BML. Section 3 explores the benefits of having semantics formalized as part of the C2ML standardization process. Sections 4 and 5 review the current state-of-the-art and standards in the Semantic Web and ontologies. Section 6 demonstrates how a C-BML ontology can use existing upper level ontologies to map entities. Section 7 explores how this ontology can help C-BML applications. Section 8 shows how reasoning can be used in a C-BML ontology to identify logical inconsistencies and derive inferences. The final sections make concluding remarks and address future work.

2. Status of SISO Coalition Battle Management Language

Phase 1 of the SISO C-BML Product Drafting Group (PDG) has finalized a formal schema for C-BML composites and guidelines on using the composites to create C-BML expressions (such as Plans, Requests, Orders and Reports). The underlying data model
definition is in the form of a XML schema. Its vocabulary is based on the Joint Consultation Command and Control Information Exchange Data Model (JC3IEDM). The C-BML Phase 1 effort also has specified the interdependence of C-BML with the SISO Military Scenario Definition Language.[6]

The next Phase of the C-BML standard is focused on developing the semantic framework for C-BML. The semantic framework should be able to expand on the data model and XML schemas from Phase 1 to create a semantic layer for C-BML that can capture the entities, their properties and relationships.

3. Semantic Requirements for Next-Generation BML

The main goal of the Semantic Web is to be able to structure and link data in a machine-readable knowledge representation. A knowledge representation system can also make use of a classifier to dynamically infer new classes/concepts and expand an ontology. Reference [15] provided an early discussion on building an ontology for C-BML. It noted that a C-BML ontology is needed for the following reasons:

i) An ontology formalizes the definition and meaning of common terms
ii) It formalizes the doctrinal rules for Orders and Reports
iii) It eases interoperability because of shared vocabulary and meaning
iv) It allows performing powerful reasoning on operational semantics

[16] describes the integration of C-BML Phase 1 and MSDL. The experiment observes that integration between a simulation system (JSAF) and a C2 system had irregularities that could have been solved by automated rules. These rules can be very easily incorporated into an ontology, while a purely syntactic C-BML would need an overlay system that raises a new set of integration issues. All entities in C-BML are structured around the “five Ws”- Who, What, When, Where, and Why. Who is conceptually any object (OBJECT_ITEM in JC3IEDM schema space). This maps to a class or concept in an ontology. The rest of the Ws can be mapped to attributes of this concept (or other concepts).

The current standard for knowledge representation is Resource Description Framework (RDF). All resources are identified with a URL, essentially all “things” can be represented in RDF. This makes it a feasible basis for a C-BML ontology. The current standard for Ontology and rule specification is Web Ontology Language (OWL). It is based on Description Logic; [17] demonstrates that Description Logic (and therefore OWL) is capable of reasoning through semantics that can be reduced to set-theory operations. Based on C-BML experimentation efforts to define the Phase 1 XML Schema, no relationships or rules have been established that are beyond set theory relationships. Therefore, OWL should be sufficient as a language for C-BML. Reference [19] supports this by outlining reasons why OWL is suitable for C-BML.

C-BML Phase 1 has identified the vocabulary and the construct for defining valid BML expressions in a coalition environment. Adding a semantic layer to it has the following advantages:
a) Common vocabulary and understanding: Although the schema for C-BML has been formalized, it is still quite likely that elements in the XML document might have different interpretations across systems. Having an ontology will formalize what each element means and how they are related to each other.

b) Allowing extensions: Formalizing a C-BML ontology will make it possible for other languages to use and even extend C-BML without affecting the semantic consistency of the elements in C-BML. This will be useful for efforts such as GeoBML[18] that apply BML to specialized contexts. This result will enrich the applications that are created in the C2 environment.

c) Within coalition C2 environment, there are a number of domain assumptions that are assumed but are not captured in an XML schema- for example, relationships between units and areas. A formalized C-BML ontology will make explicit these domain assumptions.

4. The Semantic Web

The Semantic Web is a collaborative effort based on W3C standards to capture semantics in a machine understandable way. The goal of the Semantic Web is to have standards and mechanisms that make is possible for systems to have not only data but also the meaning and relationships of data (knowledge representation, structured data and linked data). The semantic data can be represented in a number of ways, the most popular of which are the Resource Description Framework (RDF) and the Web Ontology Language (OWL) standards. RDF is based on representing resources using a Uniform Resource Identifier (URI) and linking them through a triplet of a Subject, Predicate and Object. The OWL standard can be used to create and capture a rich, complex representation of Knowledge that can be used for reasoning, checking for consistencies and making inferences and implicit assertions.

Knowledge Representation and Semantic web standards have evolved to make it possible to capture and represent semantic data. The current prevalent standards for knowledge representation are RDF, RDF Schema (RDFS) and OWL. The most basic element in the semantic web is a URI. The URI can be used to identify any piece of information irrespective of its complexity. RDF defines a framework to define a triplet consisting of <subject> <predicate> <object>. The subject and the object are URIs while the object can be either a literal or a URI. Defining a triplet allows a machine to not only understand the type of information but also the relationships within the information. For example:

<http://...Unit:UnitA><http://...UnitRelationship:hasAsCommander> <http://...Unit:UnitB>

The above example tells the semantic process that there are two Units of type Unit that have a relationship called “hasAsCommander”. The three main components of RDF are: Resources, Properties and Classes. Resources are anything that can be identified by a URI or a literal. Properties are relationships that may exist among resources. Classes are groupings of similar resources. RDF has a schema (RDFS) that allows for content created using RDF to be serialized to XML. RDF is a flexible, scalable way to define data and their relationships.
5. Ontologies
Ontologies are a way of knowledge representation using concepts and relationships between them. OWL is based on RDF but adds richness to definitions and relationships. For example, OWL allows for definitions of relationships between classes (complement) and property inferences (symmetric, transitive). OWL representation makes it possible to make inferences using Description Logic. This helps in the enrichment of knowledge by making implicit knowledge explicit. The high level abstract Ontology representation in OWL is through annotations, axioms and facts. Facts are simple assertions about entities. Axioms are assumed knowledge in the Ontology. Annotations are machine-readable meta-data of an ontology. An ontology is like a highly enriched Data Dictionary that makes it possible to have a common vocabulary in a domain.

6. Higher Level Ontologies for C-BML
Ontologies are designed to be reusable [20]. C-BML can benefit by reusing existing, applicable ontologies. In this section we demonstrate a process of mapping C-BML concepts to an existing ontology for time called OWL-Time. OWL-Time was design to be an upper level Ontology to represent time in different forms. The following example maps a C-BML When (one of the ‘5Ws’ of C-BML) to entities in OWL-Time [7]. This process can be repeated for other applicable C-BML entities and upper-level Ontologies.

OWL-Time has at its core the class “:TemporalEntity”. This class has two subclasses:

a) :Instant – This can be used to represent a point in time without any interior points
b) :Interval - This can be used to represent a period of time

C-BML defines a When element as a description of a timeframe in which an action is to occur (Order or Request) or when an action or event has occurred [5].

OWL-Time can express facts about time instants and intervals and perform temporal associations, assertions and inferences. It is designed to work across time zones and as demonstrated next is capable of capturing time in C-BML. In C-BML, When is defined in terms of the following composites: TaskWhenLight, TaskWhen, EventStart, EventEnd and ReportedWhen. These composites use a number of lower level elements. Some of them use JC3IEDM codes and cannot be mapped to an element in OWL-Time. Such elements are: jc3iedm:ActionTaskTimingDayCode, jc3iedm:ActionTaskTimingHourCode, jc3iedm:DateTimeTypeFix18 and eight others. These are codes that qualify the time in a C-BML environment. There are two elements in the C-BML specification that capture time applicable to OWL Time. They are jc3iedm:DurationType19 and jc3iedm:DateTimeTypeFix18. jc3iedm:DurationType19 is of type integer. This captures the duration of time and can be mapped to the class :DurationDescription in OWL-Time. C-BML requires that Duration be of type integer whereas DurationDescription can capture integers along with qualifiers as to whether the duration corresponds to seconds, minutes all the way until years. DatetimeTypeFix18 is a string literal specified as a chronological point measured using Coordinated Universal
Time (UTC). The ISO notation used is “YYYYMMDDHHMMSS.SSS” to represent time in years, months, days, hours, minutes, and seconds/milliseconds. DatetimeTypeFix18 can be mapped to the DateTimeDescription class which is a super set of the ISO notation in that it can additionally capture dayOfWeek and dayOfYear. An example mapping from C-BML TaskWhenLight to OWL-TIME follows:

C-BML TaskWhenLight Schema

![Diagram showing mapping from TaskWhenLight to OWL-TIME]

Figure 1: Mapping from TaskWhenLight to OWL-TIME
It should be noted that the OWL-Time has many other elements that may not be of interest to the C-BML standard and could be considered as overhead. But, using an existing W3C standard ontology like OWL-Time has the advantage of rich expressiveness and the power of reasoning through the ontology in addition to the possibility of richer Time expressions if C-BML needs it in the future.

**Upper Level Ontology for “Where”:** In C-BML a *Where* is a Geographic feature to represent points, lines, areas and features. There are a few Geographic Ontologies that provide knowledge representation for geographic information. The most applicable
standard for C-BML appears to be the W3C Geographic Vocabulary GEO OWL[8] based on Geo RSS [www.georss.org]. The top class of GEO OWL is “geometry”. A “:geometry” can be of type Point, LineString, Polygon or envelope (They are modeled after the elements in Geographic Markup Language).

Fig 2: The definition of "AtWhereLightType" in C-BML Phase1 specification

Fig 3 shows a definition of “AtWhereLight” in the C-BML Phase 1 specification. The most frequently used Location type is a “SpecificLocation” which in turn is a Point, Line, Surface or “CorridorArea”. Ontologically, Point and Line map to the corresponding items in Geo OWL and Surface can be mapped to Area and “CorridorArea” can be mapped to a Polygon in Geo OWL. When the C-BML Ontology is formalized, like the When, there will be elements in Where that cannot be mapped to elements in Geo OWL. But elements such as Point, Line, Surface and “CorridorArea” can be mapped to elements in Geo OWL.

7 How can Ontologies help C-BML?

[9] notes that operational BML lacks clearly delineated rules governing its use concerning syntax and semantics. This fact is amplified in a coalition environment. It has already been noted that in the increasingly coalition and interoperability-oriented C2 operations, BML would need to have a formalized, common vocabulary and semantics [10]. Having a C2 ontology would allow for seamless, meaningful exchange of digitized C2 information across C-BML compliant systems. Also, the process of semantic formalizations could raise important discussions where agreement in doctrine interpretation may be lacking. [11] notes that there is no trivial mapping from Syntax to semantics. Therefore, it cannot be assumed that Grammar and XML Schema (Syntax) implicitly define necessary semantics.
8. Reasoning on C-BML

Ontologies capture explicit knowledge in the form of axioms and facts. Ontology reasoning uses knowledge reasoning and first-order logic reasoning to derive implicit knowledge from the explicit knowledge and the properties of entities and relationships. RDFS Schemas define relationship inferences through properties such as rdfs:subclassOf, rdfs:subProperty that allow a reasoner to make inferred relationships. Knowledge can be inferred through equality, reflexivity, and transitivity. Most reasoners use First-Order Predicate logic to derive inferences and expand the Knowledge base, although there has been recent work that suggest probabilistic reasoners such as ELOG [12] or Pronto [13] can also be used. Additionally, abductive reasoning is another form of reasoning that arrives at possible hypothesis based on observations. This is particularly interesting in the context of C-BML because frequently used C-BML expressions are Reports. Reports are observations, typically made on units, objects, or areas. With a formalized ontology, these Reports (observations) can be fed to an abductive reasoner to suggest possible hypotheses. These can be helpful to a C2 operator to understand why a particular observation might be important. An example of using reasoning in semantic C-BML to detect semantic errors is illustrated below:

Consider a General Status Report in C-BML. This provides status information on a perceived Executer (Unit/Organisation) at a particular time and place. There can be multiple General Status Reports on the Executer pertaining to the same time and place. It is quite possible (although semantically unreasonable) that these reports provide different locations for the same Executer at the same time. A C-BML implementation would not be able to detect this inconsistency without an additional layer of “unformalized” programming. An ontology with the following rule can detect this inconsistency.

A visualization of a OWL ontology focused on the Executer and its relationship to “Reported Location” and “Reported Time” can be found below:

![Figure 3: A visualization of a OWL Ontology definition focused on the Executer and its relationship to ReportedTime and ReportedLocation](image-url)
A human readable Semantic Web Rule Language (SWRL) representation of the rule is shown below:

\[
(\text{Executor}(x), \text{hasAsReportedTime}(x, t1)) \\
\land (\text{Executor}(x), \text{hasAsReportedTime}(x, t1)) \\
\Rightarrow (\text{hasAsLocation}(x, l1) = \text{hasAsLocation}(x, l2))
\]

This rule is applicable to an Ontology that has an entity called Executer with two object properties- “hasAsReportedTime” and “hasAsLocation”. The rule states that for any object “x” of an Executer if that Object has a time “T1” and a new instance of a Report also has the same object “x” with the same reported time “T1”, then the location for that Executer should also be the same.

Another example of the use of reasoning in a C-BML Ontology is the use of inferences to derive “new knowledge”. This is illustrated in the simple examples below:

Example 1:

Consider the axioms:
ObjectProperty (a:isAUnit domain(a:Tasker) range(a:Unit))
ObjectProperty (a:isAsubordinateOf domain(a:Taskee) (a:Tasker))

The axioms represented by these Object properties are:
- A Tasker should be a Unit (as opposed to a Equipment)
- A Taskee is subordinate to a Tasker

Now consider an Order that has a Tasker as: “1060: 1st Battalion Commander” and a Taskee as: “1062: Company A”. Using the two axioms, we can assert the knowledge:

“1060: 1st Battalion Commander’ is a Unit who is a commanding officer to ‘1062: Company A’”

Example 2:

Axiom: ObjectProperty(a:isAfterTask domain(a:Task) range(a:Task)

allows us to use the transitivity of the “isAfterTask” property so that with the assertions:

Assertion1: Task1 isAfterTask Task2,
Assertion2: Task2 isAfterTask Task3
The inference is derived:
Inference: Task1 isafterTask Task3
Note: This inference can be derived in the Ontology even if the two tasks are in separate C-BML Orders
9. Future Work

The evolution of BML to date has been incremental. A number of NATO Modeling and Simulation Group (MSG) 085 experiments [21] have provided needed feedback. An evolving standard should be able to work through new changes and the MIP Change Proposal (CP) Framework in the MIP Information Model (MIM) is being explored as a framework to preserve MIP compliance [22]. A semantic C-BML should be able to align with the MIM CP. Also, work has been done to extend OWL to work with axioms and assertions based on probability like PR-OWL [14]. Future work can explore the applicability of PR OWL to C-BML based on use cases.

10. Conclusions

C-BML continues to evolve, to better support C2-simulation interoperation in the coalition environment. Developing a semantically enriched C-BML addresses avenues of interest both in doctrinal formalization and operational efficiency. An ontology based C-BML standard can be used to capture the full expressivity of a data model while allowing users to create and implement a required subset of the ontology as a XML schema. This will help in faster development time and testing time of C-BML implementations. A semantically enriched C-BML system can be used to pre-process C-BML documents to make sure that data is not only syntactically valid but also maintain semantic integrity. In addition, a semantic C-BML can have Task/Plan specific rules that can be used to generate abductive hypotheses based on Reports. Prevalent Semantic Web standards such as RDF, RDFS and OWL are suitable to create the domain Ontology for C-BML.

References:


