



# Using Autonomics to Exercise Command and Control of Networks in Degraded Environments

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#### Introduction: Architectural Complexity

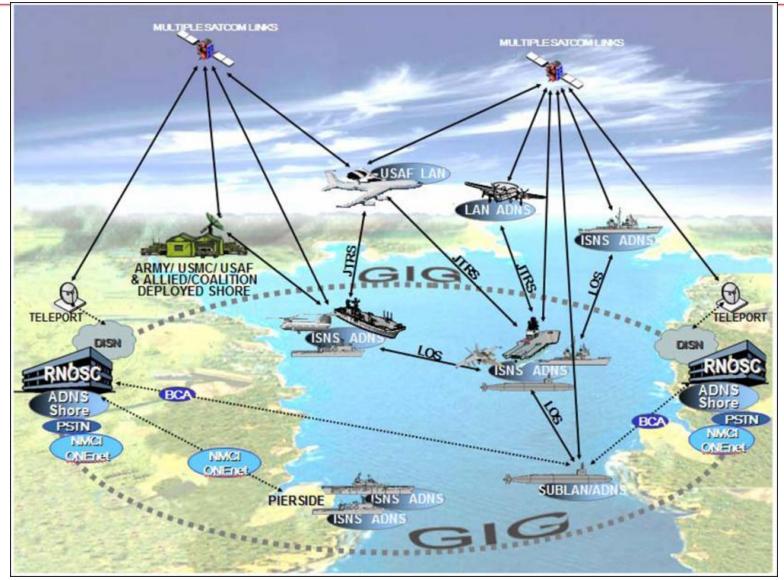
- ▼ Increasingly Complex Infrastructure
  - Satellite, Wireless, Wired
  - Manned, Unmanned
  - Mobile, Immobile
  - Sea Surface, Underwater, Land, Air
  - High heterogeneity
  - Cloud Computing, Virtual Machines, SoA



▼ Timely delivery of data and decision support essential



#### **Teams ⇔ Networks** → **C2** ⇔ **Network Control**





#### ▼ Decision Support System for Infrastructure Management

- Collect data from the infrastructure
- Analyze performance metrics and system requirements
- Effect changes to meet requirements/improve performance
- Decrease system failure/inefficiency and human labor

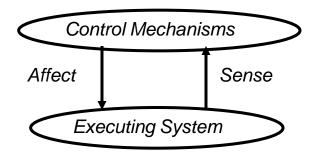
#### **▼** Functional areas:

- Self-configuration
- Self-healing
- Self-optimization
- Self-protection



#### **Autonomics (2)**

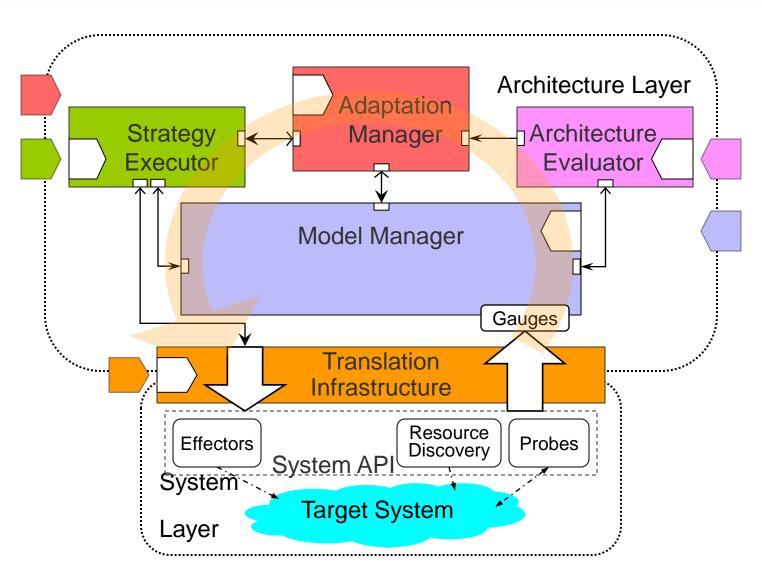
#### Move from open-loop to closed-loop systems



- ▼ Software Architectures for dynamic self-adaptation
  - Rainbow: a framework in which architectural models can be used to adapt systems
  - Stitch: a language to define self-adaptation strategies
  - Analysis: Using model checkers to analyze properties of architecture-based adaptation



### Rainbow Framework (Garlan, 2010)



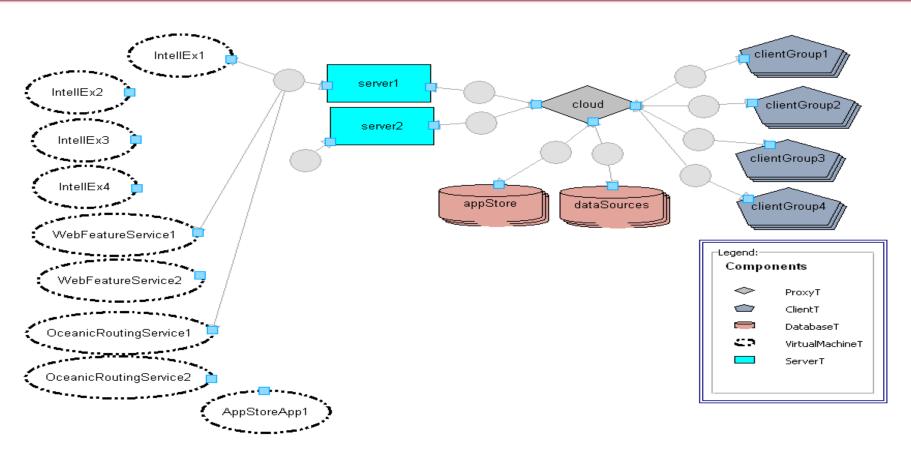


# Investigate: Autonomics in Degraded Environments

- ▼ Autonomics for C2 will encounter DIL connectivity
  - Elements moving in and out of network
  - Environmental/Situational changes in available communication
- ▼ DIL environments present challenges
  - Limited information
  - Limited ability to exert control
- ▼ Also opportunities
  - Autonomics can react faster
  - Autonomics meant to respond to changing environments

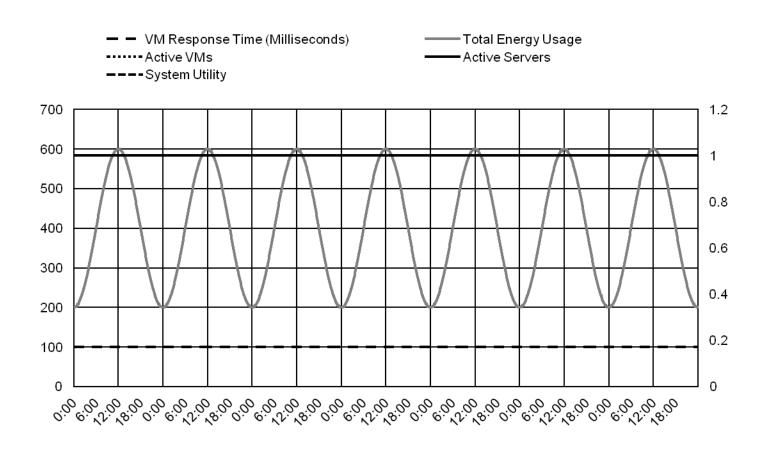


### **Experimental Setup: Cloud-like System**



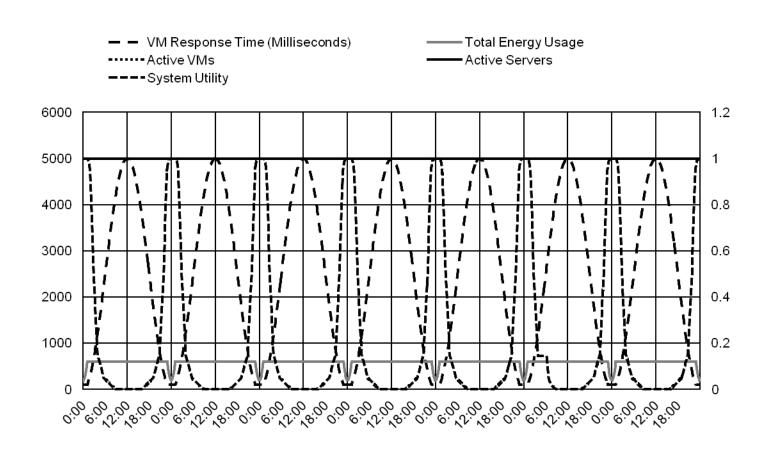


#### **Experimental Setup: Environment Optimal**



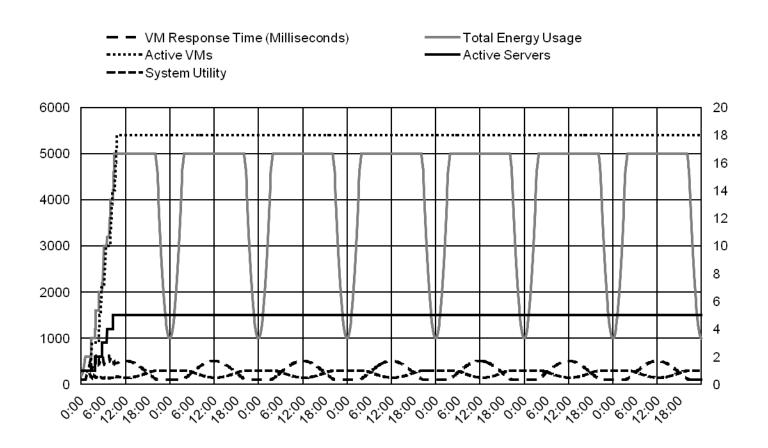


#### **Experimental Setup: Environment Overloaded**



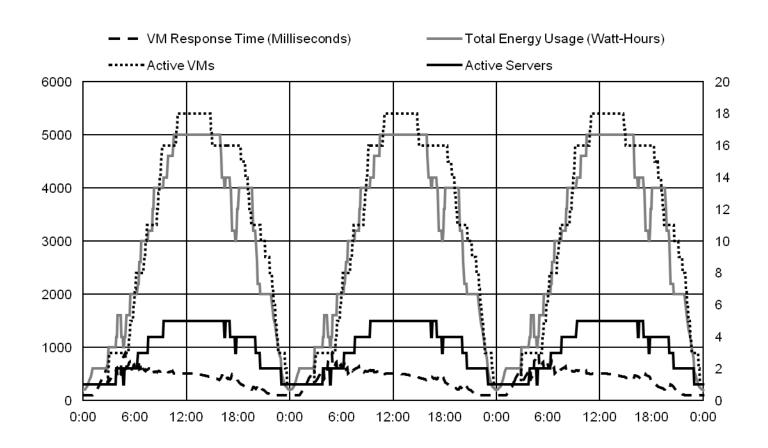


# **Experimental Setup: Example of Autonomic Response**



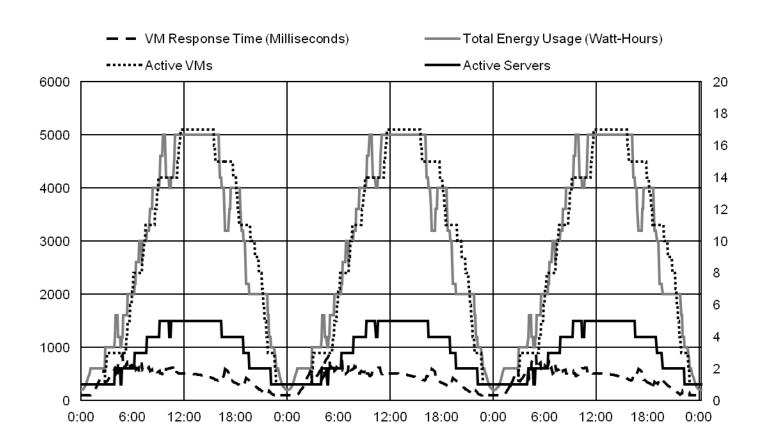


# Results: DIL Effects on Autonomics (Baseline – 5 minute update intervals)



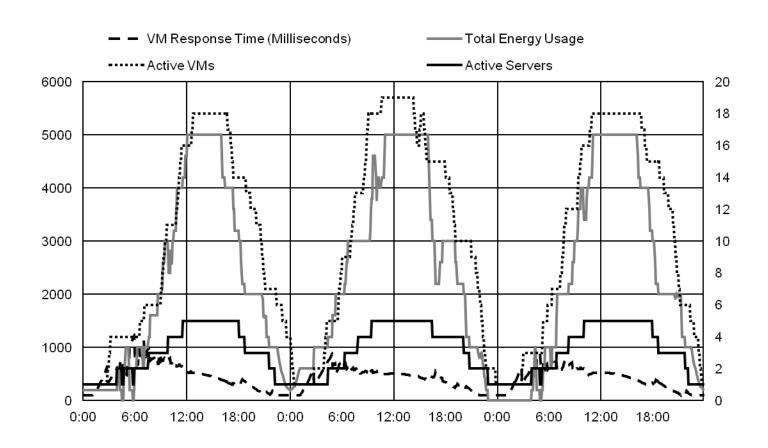


## **DIL** (10 minute intervals)



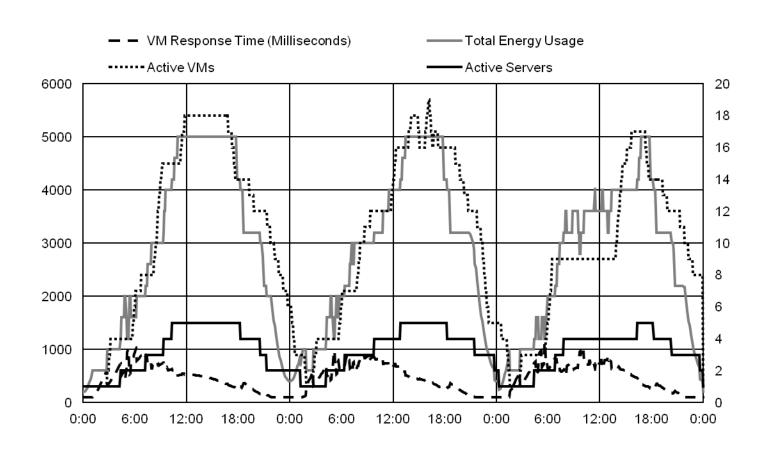


## DIL (15 minute intervals)



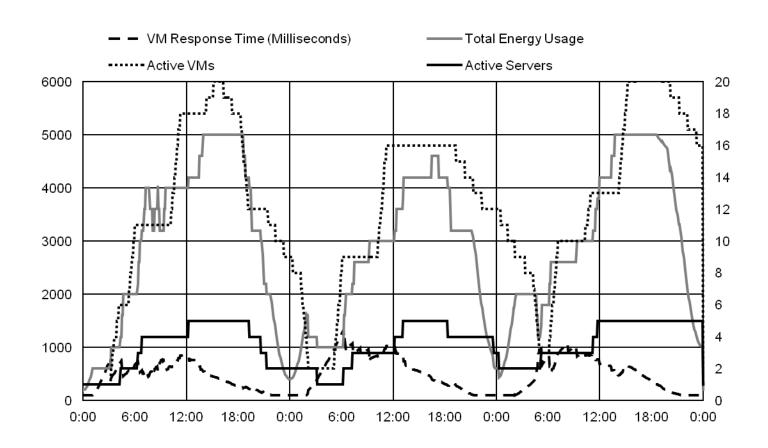


### DIL (30 minute intervals)



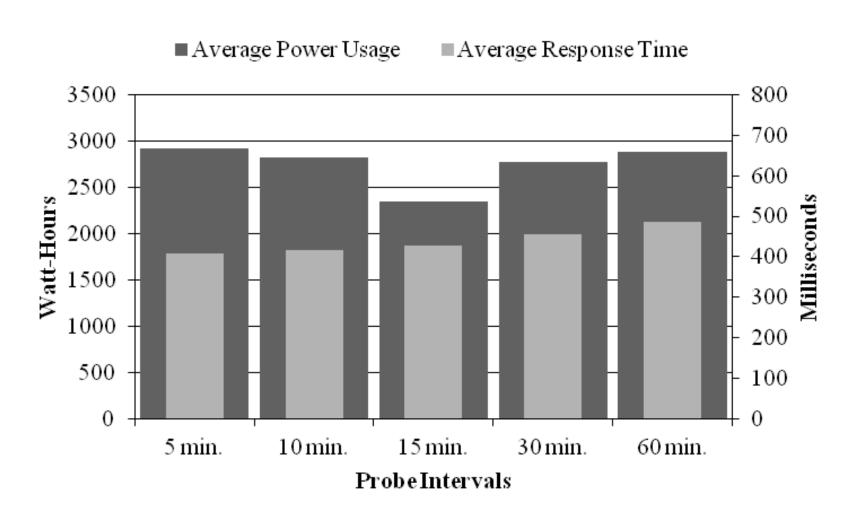


### DIL (60 minute intervals)





# DIL – Average Power Usage and Response Time





#### **Discussion & Future Work**

- ▼ DIL negatively impacts autonomic performance
  - Begins with degraded ability to manage (up to 15 min intervals)
  - Ends with destabilization
- ▼ Challenge is in timing events
  - Too late in responding to events
  - Responding to events that have already passed
- ▼ Ways forward
  - Machine learning for prediction of future states
  - Distributed autonomics



#### **End and Thank you!**

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