# Creating and Capturing Expertise in Mixed-Initiative Planning



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### Why capture expertise?

"By three methods we may learn wisdom: First, by reflection, which is noblest; Second, by imitation, which is easiest; And third, by experience, which is bitterest."

- Confucius

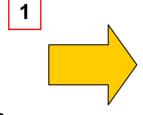
# Capture, Develop, Provide Experience

- <u>Challenge</u>: Is it really possible to institutionalize the thought processes of a military commander?
  - Prior efforts attempted to model and recreate the *reasoning* of military decision makers.
  - However, many of the decisions made by human thinkers are founded in intuition and not readily modeled.
- Our Answer: Augment the same recognition processes used by humans.
  - Mixed-initiative decision-making:
    - Both the humans and the system are driving the process.
  - People and machines learn from each other.
  - Perform at a higher level of expertise together.



# **Case-Based Reasoning**







#### user case



User enunciates objectives and situation





The experience is retained for future use



5

#### new plan

The new plan is then implemented





Case is reused and revised, adapted to the present











Most similar case is retrieved from past experiences









#### DEEP.

#### Distributed Episodic Exploratory Planning in one sentence:

DEEP enables planners to cooperate with other Air Operations Centers by using the experience of the past adapted to present situations, allowing for intuition-like mixed-initiative planning.

- New AOC ConOps
  - Smaller, separate AOCs
  - Supporting/ed relationships
  - Complex, ever-evolving ops environment

- Technology
  - Black Board Systems
  - Episodic Memory
  - Multi-Agent Systems





#### DEEP

Plan. Learn. Together.





## **Our Focus: Capturing Experience**

- How do we collect experience in a way that is:
  - Understandable by a computer?
  - Amenable for mixed-initiative planning?
  - Supportive of drawing conclusions from knowledge?





#### Three Main Areas...

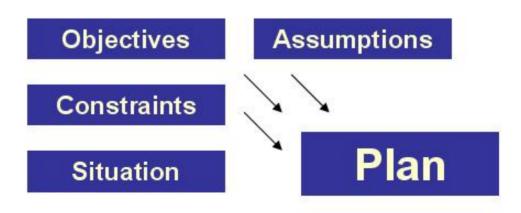
- Context of the situation
- Decision made by planner
- Outcome of that decision





#### The Context.

- We need to capture:
  - What needs to be accomplished (Objectives)
  - Details about the world (Situation)
  - How that space is bound (Constraints)
  - Assertions based on evidence (Assumptions)
- With this information, a decision (Plan) can be formed...

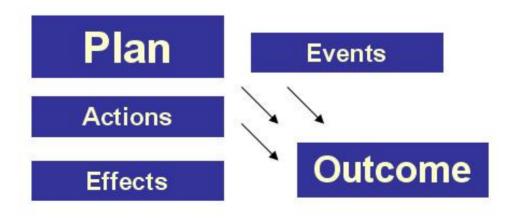






## The Experience.

- Based on the decision (Plan), capturing the implementation of that decision requires:
  - What was done to realize the decision (Actions)
  - What was done by others in the environment (Events)
  - How both of those affected the situation (Effects)
- Now we can ask: are our Objectives met? (Outcome)







### **Developing Experience**

- In order to encapsulate this knowledge within a computer, we can adapt previous research in plan representation
  - Core Plan Representation, developed by the ARPA Rome Lab Planning Initiative (APRI).
  - Site: http://projects.teknowledge.com/CPR2/Reports/CPR-RFC4/
- However, CPR was designed to represent plans, not whole experiences.





#### From Plans to Experiences









- Event
  - What really happened when we tried the plan?
- Assumption
  - What if something's very existence is assumed?
- Outcome
  - How do we know if we are successful?
- Cost
  - How do we measure the value of what is expended?
- Location
  - Is the question 'where?' always geospatial?





# **Forming Analogies with Experience**

- Some Approaches...
  - K-Nearest Neighbor: are there characteristics that are very similar? How many?
  - Semantic Similarity: is there a meaning that is very similar?
     What taxonomy/ontology will answer that?
  - Structural Mapping: are there higher-order relationships at work that form an analogy? Is there 'systematicity'?
  - Many are Called, Few are Chosen: will a first pass with feature matching allow for deeper analysis?
  - Multi-Constraint Theory: are the features, relationships, and purpose of these items the same? Is it 'coherent'?





## **Summary and Future Work**

- DEEP seeks to provide intuition-like planning by utilizing experience in a mixed-initiative environment.
- Future efforts will include:
  - Episodic Memory rather than Case-Based memory
  - Semantic and Structural analogy algorithms
  - Measuring trust/confidence in assumptions using CBR
  - Capturing a world state with enough richness for analogies
  - Capturing 'war stories' and lived history for new cases