

Air Force Institute Of Technology



Modeling and Measuring Network Centric Warfare (NCW) with the System Effectiveness Analysis Simulation (SEAS)

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Overview



- **Defining NCW**
- **Problem Statement**
- **Modeling NCW with SEAS**
 - **SEAS**
 - **Kosovo Scenario**
 - **Measures of Effectiveness**
- **Analysis**
- **Conclusions**



Defining NCW



Network Centric Warfare

The conduct of military operations through the utilization of **networked information systems**, which supply the warfighter with the **right information** at the **right time** in the **right form** to the **right person** being put to the **right use**, in order to **achieve desired effects** across the **Physical, Information, and Cognitive Domains** of warfare.



Problem Statement



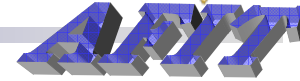
Simulation and Analysis Facility (SIMAF) Task

- *Use the Systems Effectiveness Analysis Simulation (SEAS) to conduct Network-Centric Warfare (NCW) modeling*
 - *Develop an NCW scenario*
 - *Propose and validate or refute selected measures of effectiveness applied to NCW operations*

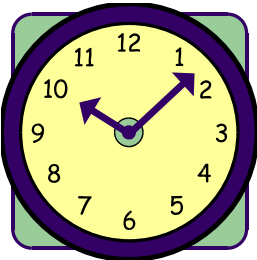
(from Air Force Institute of Technology
RESEARCH PROPOSAL, 15 February 2005)



The SEAS Simulated Environment

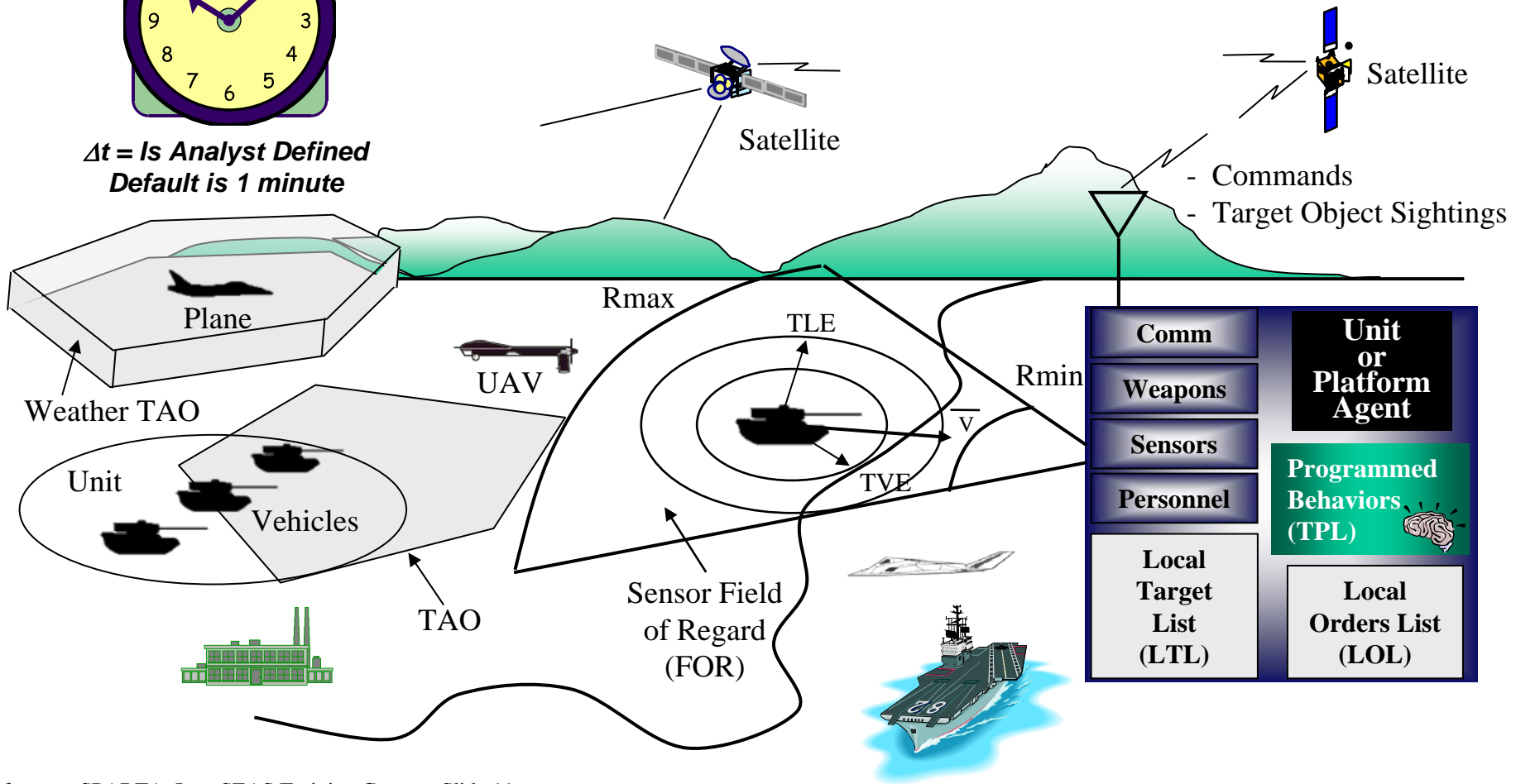


SEAS is a time step simulation



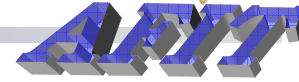
$\Delta t = 1s$ Analyst Defined
Default is 1 minute

Agents execute parallel threads of user defined tactical programming language (TPL) that controls their behavior

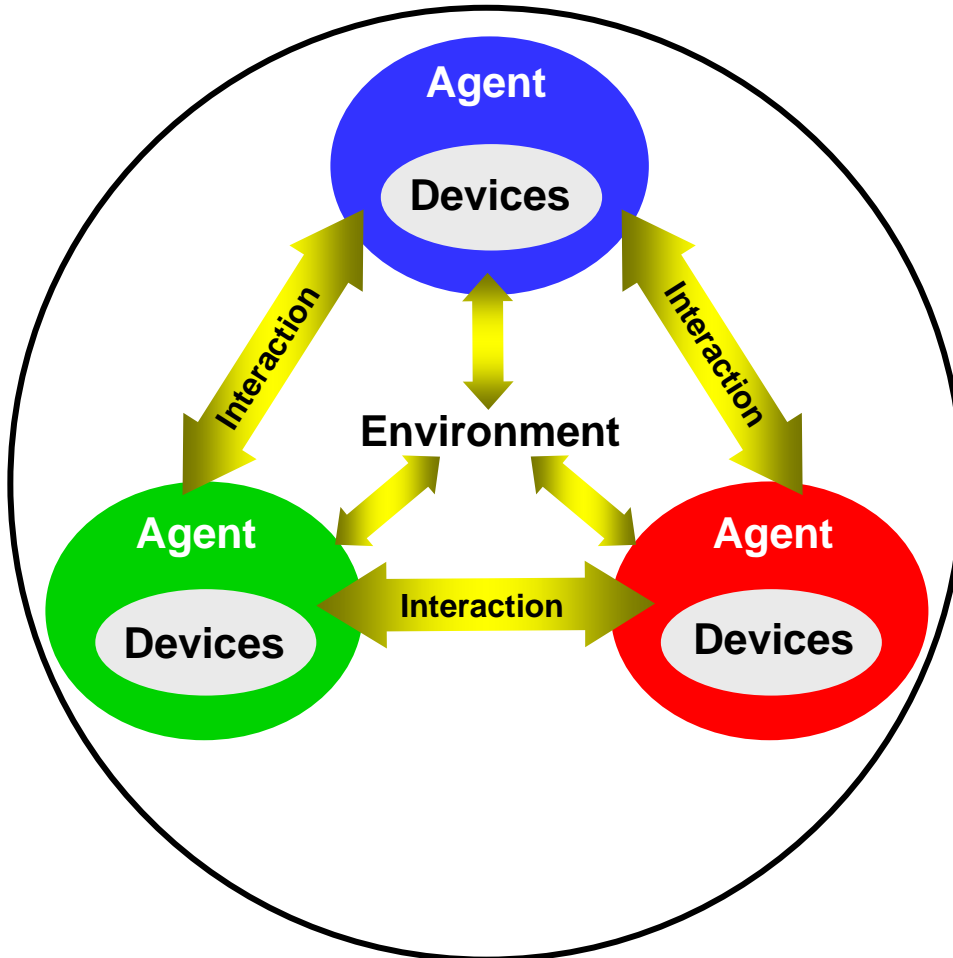




SEAS Modeling Constructs



Agents, Devices, Environment



Agents Interact

- Units
- Platforms (vehicles, planes, sats)



Through Devices

- Weapons
- Sensors
- Comm



With each other and the Environment

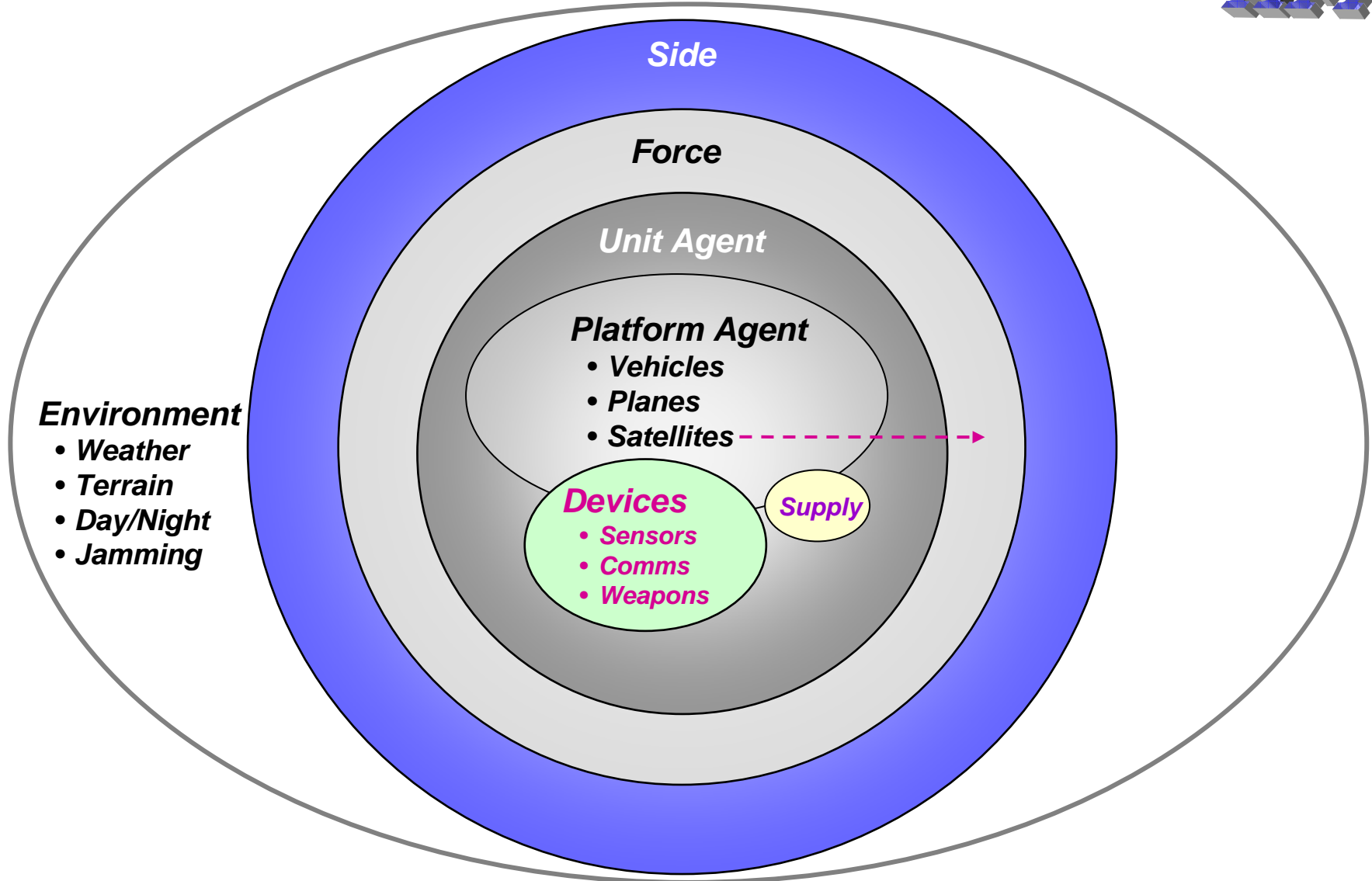
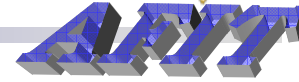
- Events
- Locations
- Terrain
- Weather
- Jamming
- Day/Night



To Emerge Combat Outcomes

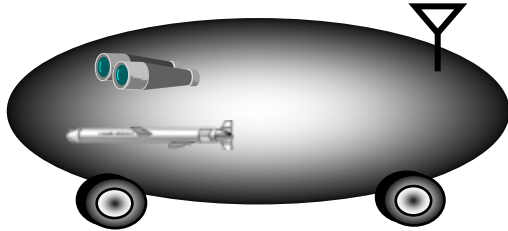


SEAS Object Hierarchy





What a SEAS Agent Might Say



I am a SEAS agent.

- I can **move** around my environment.
- I can **sense** things in my environment.
- I can **talk** to other agents in my environment.
- When I **use up resources** I can get more.
- I can **kill** other agents.

I will do what I am told by my superiors unless my local programming over rides those orders. You can program me to be compliant or truculent, an observer, a killer, or even a leader/controller of other agents.

When I see an enemy or someone tells me about an enemy I remember and forward predict his position until the information for that target is too old. Its important for me to keep track of enemy positions because I might be ordered to 1) do nothing, 2) move toward them, 3) move away from them, 4) tell others about them, 5) kill them or some combination of the above.

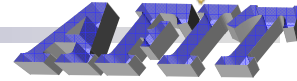
I can also decide to do any of these things on my own as well as provide other services to fellow agents like; tell them where to go, tell them what targets to attack, etc.

When I move or shoot I use resources that must be replenished after awhile or I won't be able to move and or shoot.

I am basically a pretty aggressive guy and if I see an emeny agent and I am within range I will try and kill him unless you tell me not to.

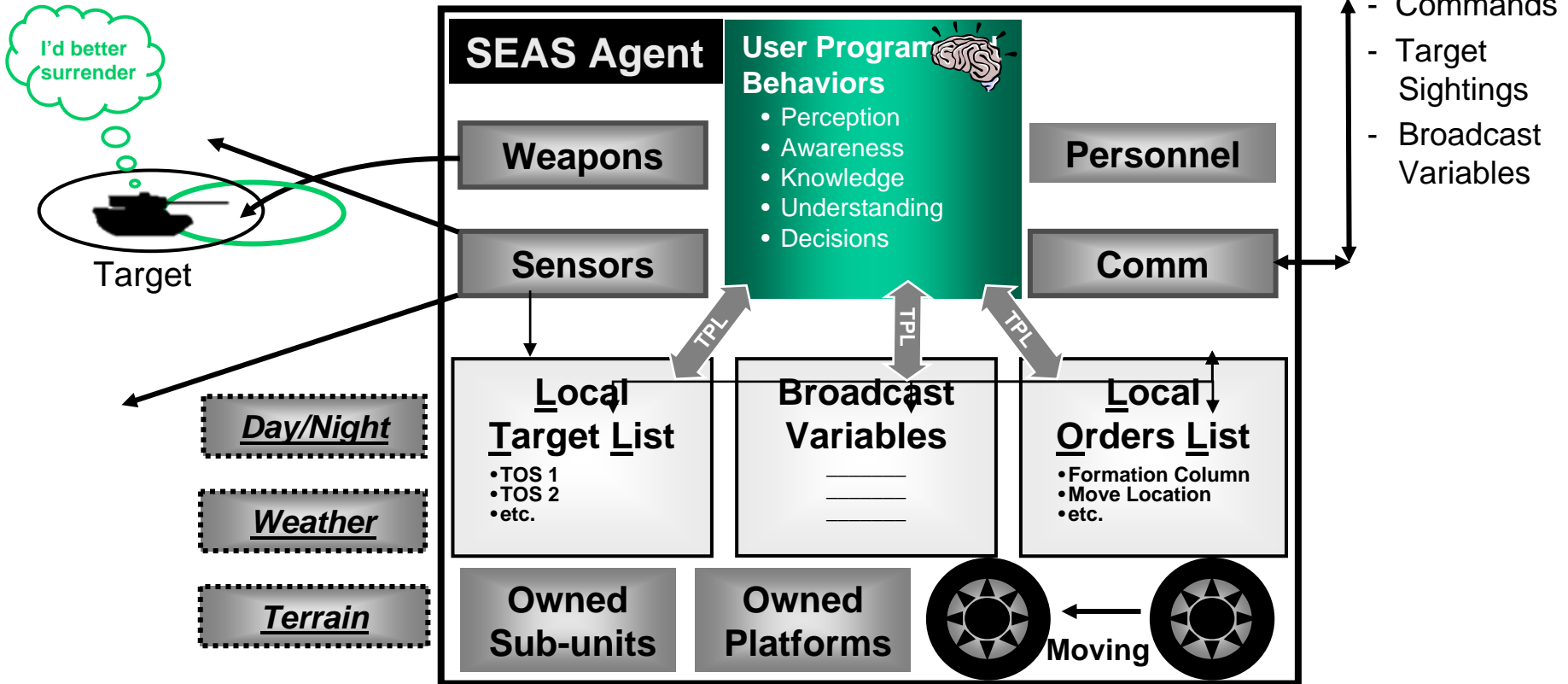


Conceptual View of a SEAS Agent



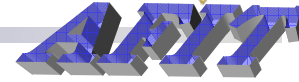
- There are four key concepts that apply to agent actions and interactions in SEAS;
 - The local target list (LTL)
 - The local orders list (LOL)
 - The target interaction range (TIR)
 - The broadcast interval (BI)

- Cognitive Domain
- Information Domain
- Physical Domain
- Action
- Effect
- Device
- Environment

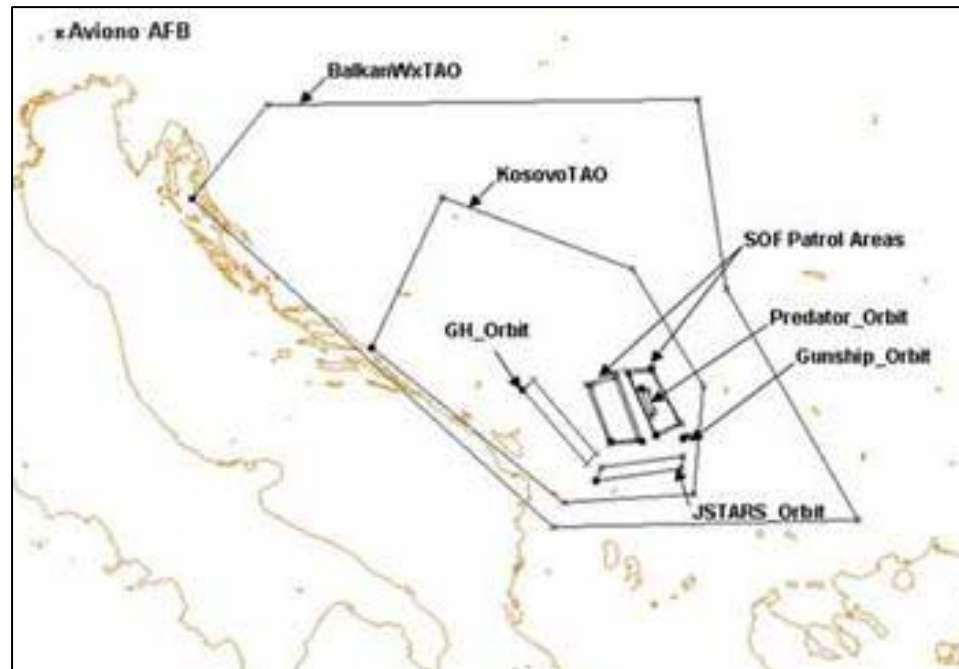




Kosovo Scenario - Overview

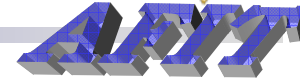


- Kosovo Scenario - created by Space and Missile Center Developmental Planning (SMC/XR)
 - Programmed to represent operations in Kosovo conflict during 1999

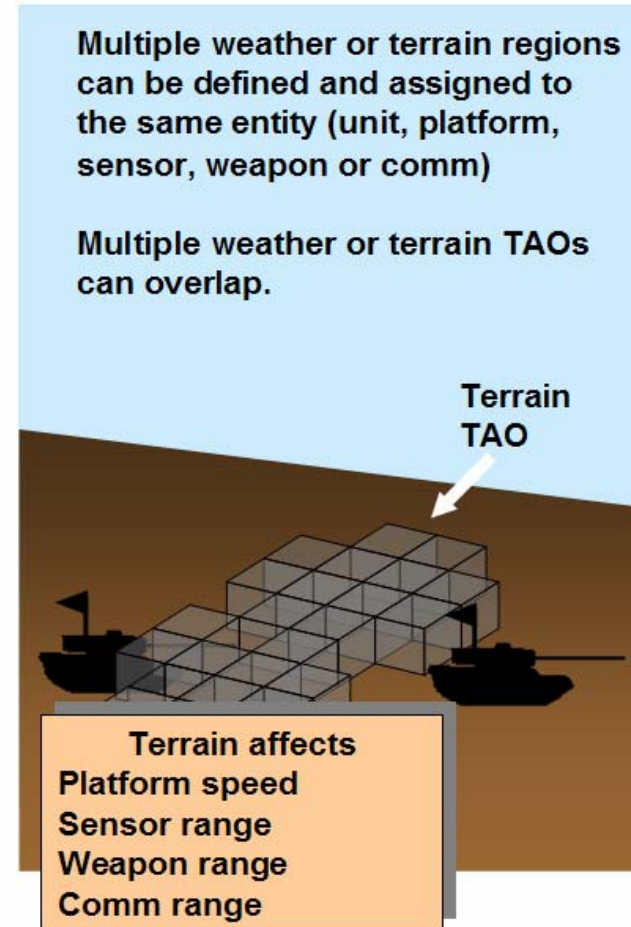
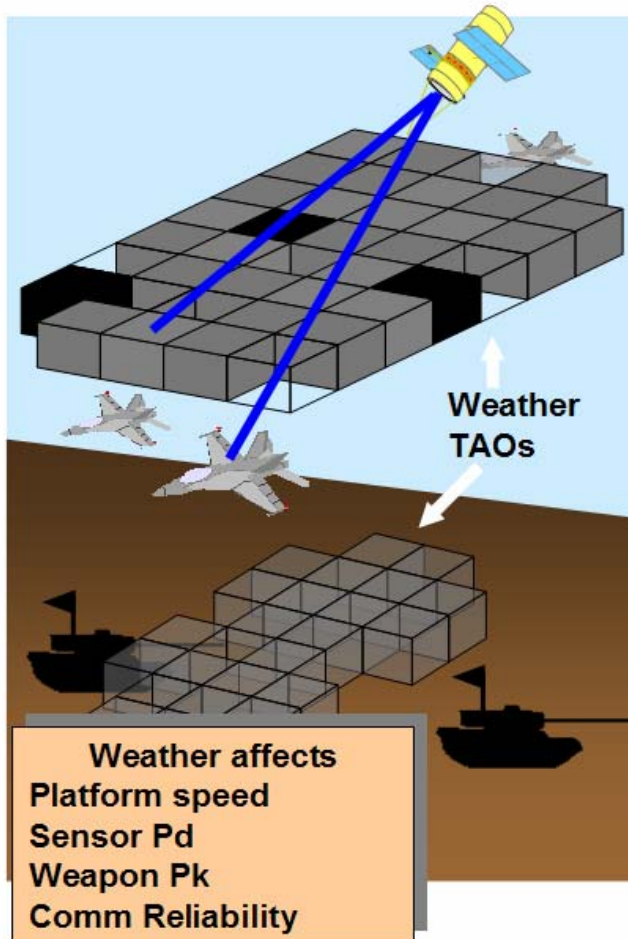




Kosovo Scenario – Weather/Terrain Objects Overview

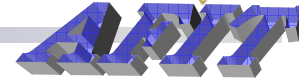


- **Weather** affects Platform speed, Sensor Pd, Weapon Pk, and Comm Reliability
- **Terrain** affects Platform speed, Sensor range, Weapon range, and Comm range

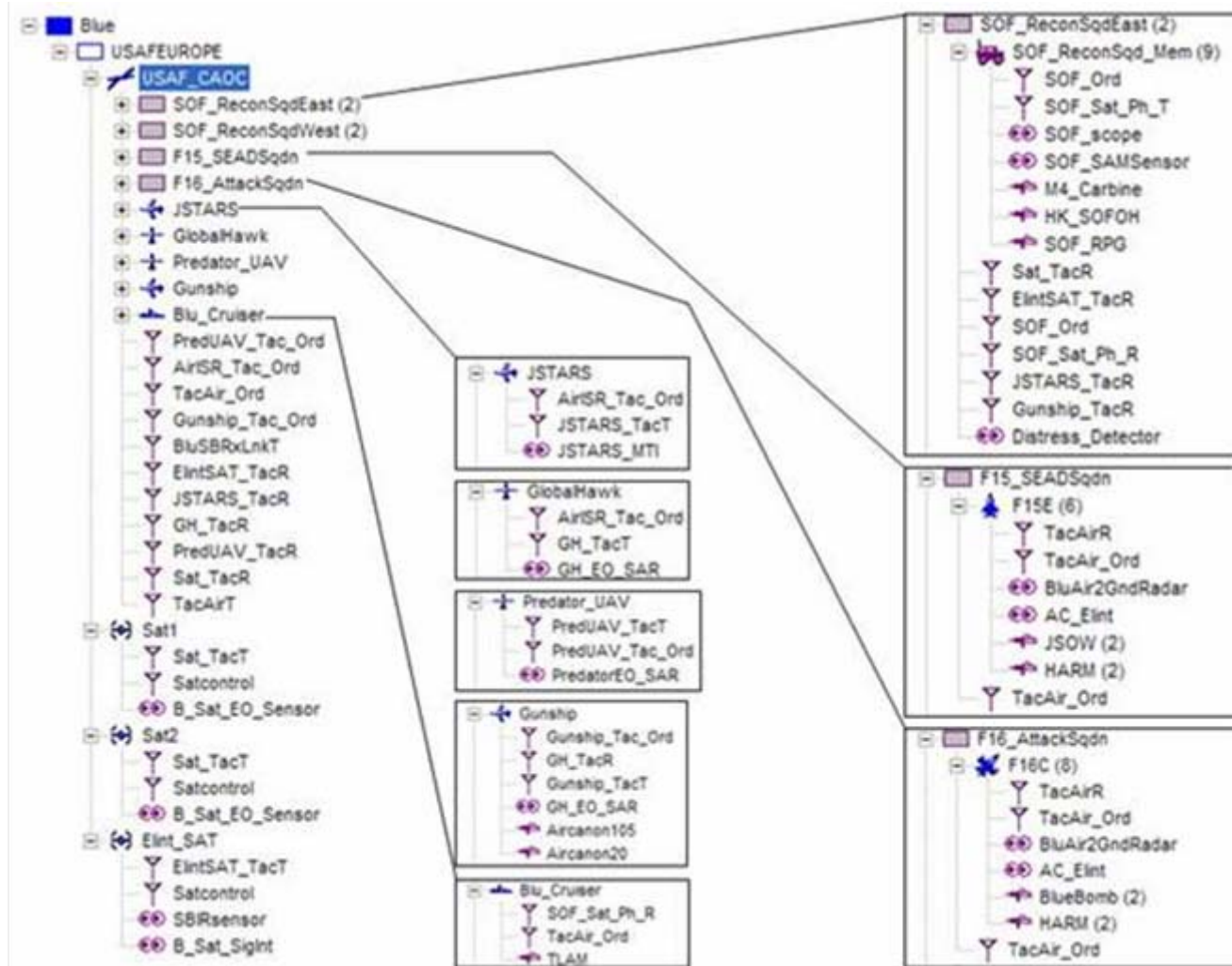




Kosovo Scenario

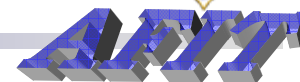


➤ Blue USAFE Force

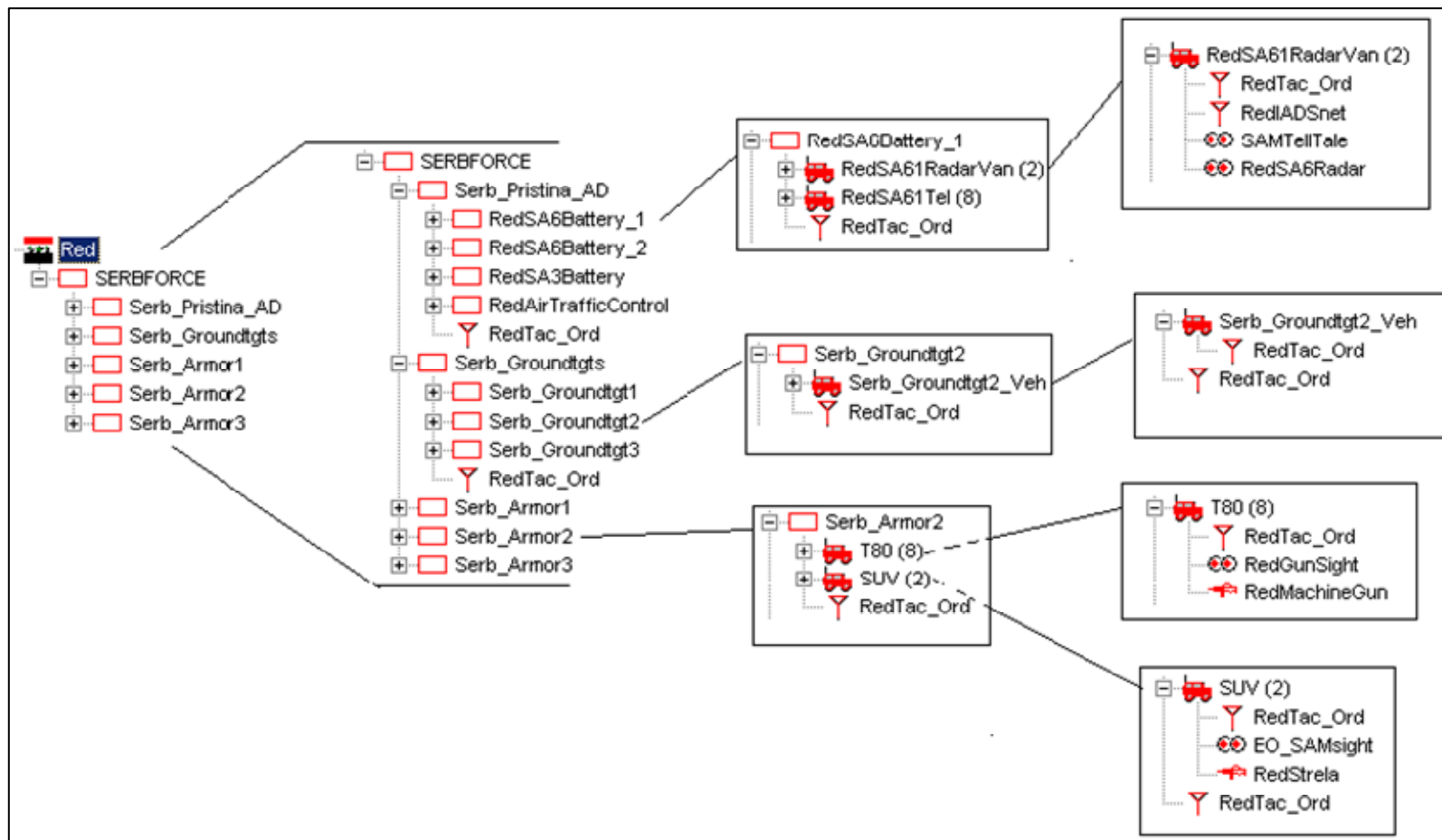




Kosovo Scenario

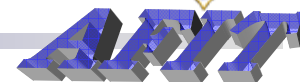


➤ Red Serbian Force

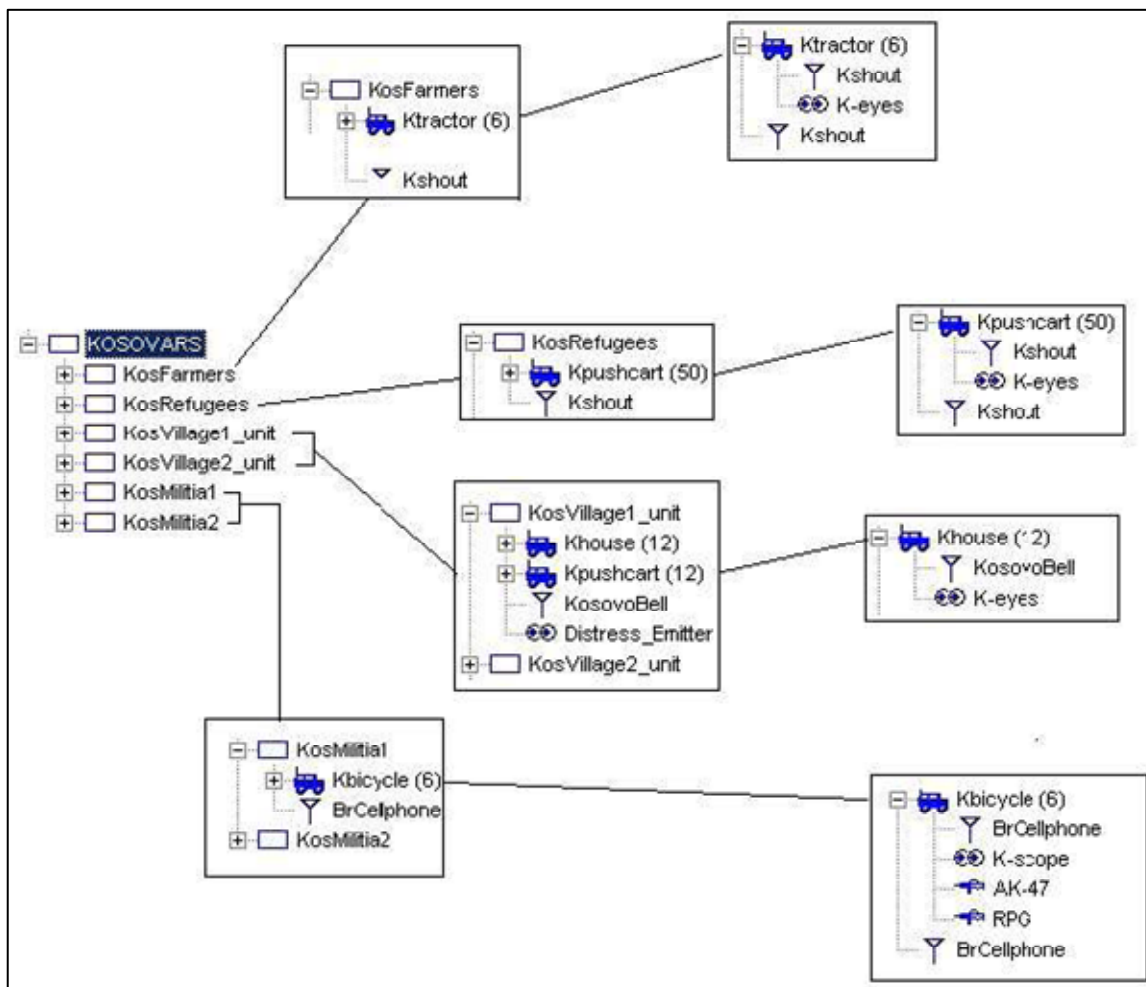




Kosovo Scenario

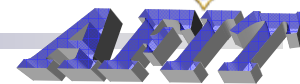


➤ Brown Kosovar Force





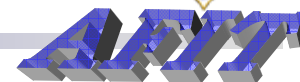
Measures of Effectiveness



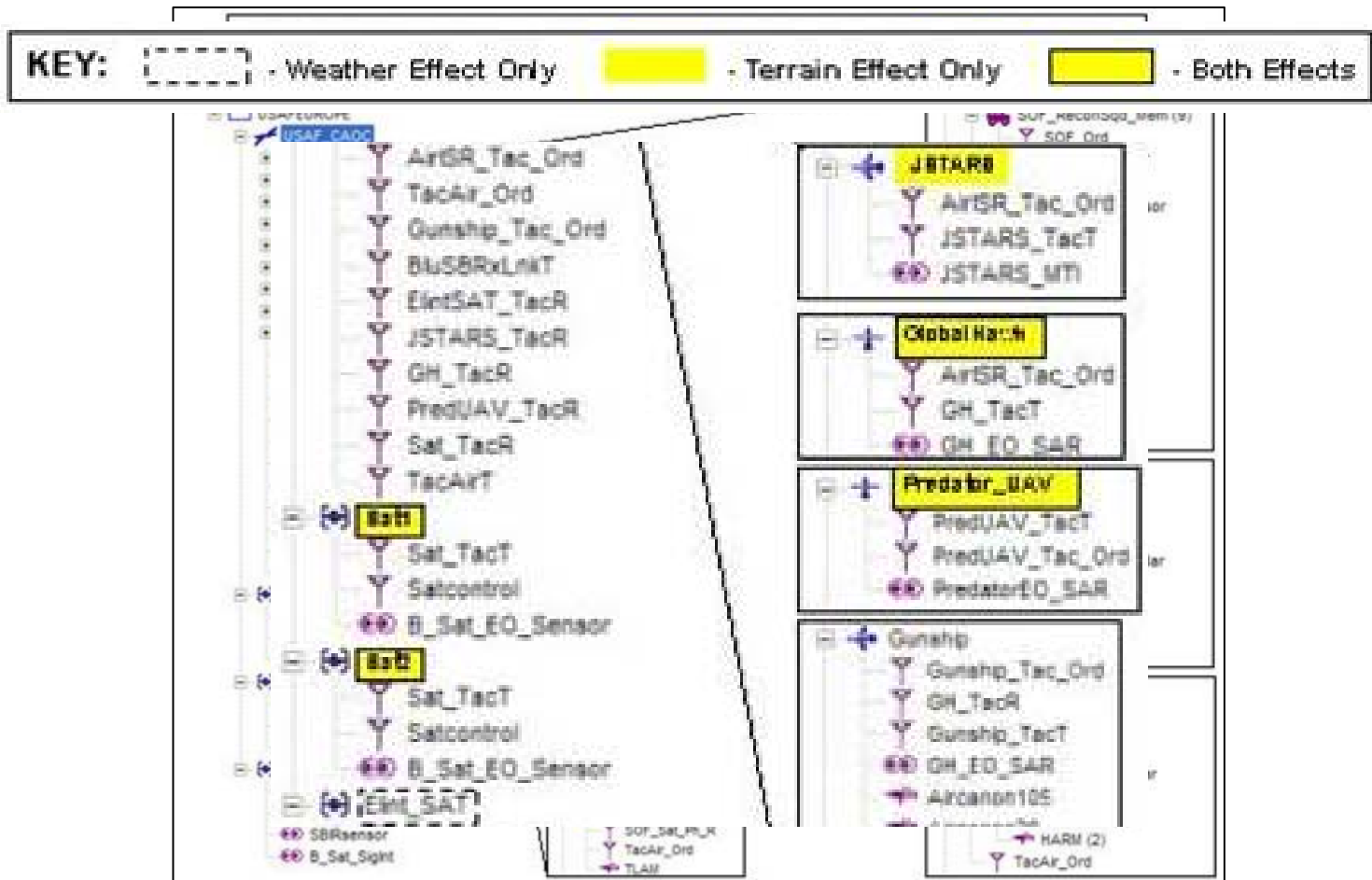
- Physical Domain
 - Target Detection Distance
- Information Domain
 - Communication Channels Message Loading
- Cognitive Domain
 - Effect on the Kill Chain



Analysis Overview



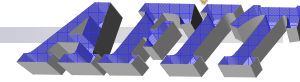
➤ Used coded Blue Force chart as guide for focusing analysis





Analysis – Physical Domain

Target Detection Distance



- Performed Paired-t Test to compare average of detection distance outputs over *30 runs*

Satellites Paired-t Test Detection Distance Analysis

Satellite #1

| <i>Difference Between Baseline and:</i> | $\bar{Z}(n)$ | 95 % Confidence Interval | Statistical Difference? | Percentage Change from Baseline: |
|--|--------------|--------------------------|-------------------------|----------------------------------|
| Full Effects | 178.30 | (166.38, 190.23) | Yes | -13.75 |
| Terrain Only | 174.57 | (165.88, 183.26) | Yes | -13.46 |
| Weather Only | 15.91 | (3.18, 28.63) | Yes | -1.23 |

Satellite #2

| <i>Difference Between Baseline and:</i> | $\bar{Z}(n)$ | 95 % Confidence Interval | Statistical Difference? | Percentage Change from Baseline: |
|--|--------------|--------------------------|-------------------------|----------------------------------|
| Full Effects | 176.66 | (164.02, 189.30) | Yes | -13.80 |
| Terrain Only | 164.00 | (154.65, 173.35) | Yes | -12.81 |
| Weather Only | 18.05 | (0.36, 35.75) | Yes | -1.41 |



Paired-*t* Test Results for F-15's



F-15 Squadron Paired-*t* Test Detection Distance Analysis

F-15E#1

| <i>Difference Between Baseline and:</i> | $\bar{Z}(n)$ | 95 % Confidence Interval | Statistical Difference? | Percentage Change from Baseline: |
|--|--------------|--------------------------|-------------------------|----------------------------------|
| Full Effects | -0.44 | (-6.19, 5.31) | No | 1.05 |
| Terrain Only | -6.56 | (-11.71, -1.41) | Yes | 15.78 |
| Weather Only | 1.56 | (-4.75, 7.87) | No | -3.75 |

F-15E#4

| <i>Difference Between Baseline and:</i> | $\bar{Z}(n)$ | 95 % Confidence Interval | Statistical Difference? | Percentage Change from Baseline: |
|--|--------------|--------------------------|-------------------------|----------------------------------|
| Full Effects | 0.38 | (-8.22, 8.97) | No | -0.92 |
| Terrain Only | -2.15 | (-8.45, 4.16) | No | 5.20 |
| Weather Only | 3.07 | (-2.83, 8.97) | No | -7.42 |

All 6 F-15's Together

| <i>Difference Between Baseline and:</i> | $\bar{Z}(n)$ | 95 % Confidence Interval | Statistical Difference? | Percentage Change from Baseline: |
|--|--------------|--------------------------|-------------------------|----------------------------------|
| Full Effects | 0.49 | (-3.39, 4.37) | No | -1.18 |
| Terrain Only | -3.07 | (-7.05, 0.91) | No | 7.38 |
| Weather Only | 0.62 | (-2.99, 4.23) | No | -1.49 |



Paired-*t* Test Results for JSTARS and Global Hawk



JSTARS and Global Hawk Paired-*t* Test Detection Distance Analysis

JSTARS

| <i>Difference Between Baseline and:</i> | $\bar{Z}(n)$ | 95 % Confidence Interval | Statistical Difference? | Percentage Change from Baseline: |
|---|--------------|--------------------------|-------------------------|----------------------------------|
| Full Effects | 0.21 | (-2.09, 2.51) | No | -0.33 |
| Terrain Only | 0.28 | (-2.48, 3.05) | No | -0.44 |
| Weather Only | -0.63 | (-3.05, 1.79) | No | 0.98 |

Global Hawk

| <i>Difference Between Baseline and:</i> | $\bar{Z}(n)$ | 95 % Confidence Interval | Statistical Difference? | Percentage Change from Baseline: |
|---|--------------|--------------------------|-------------------------|----------------------------------|
| Full Effects | -0.06 | (-0.18, 0.05) | No | 0.24 |
| Terrain Only | -0.06 | (-0.12, 0.00) | No | 0.24 |
| Weather Only | 0.13 | (0.03, 0.23) | Yes | -0.53 |



Analysis – Information Domain

Standard Comm Output from SEAS



- **SEAS standard output comm file tracks information on three types of channels:**
 - "_Sit_" = situation report (i.e. target sighting)
 - "_Var_" = broadcast variable (user-defined; e.g. target priority, delay time)
 - "_Ord_" = orders (commands)
- **For each channel type, SEAS tracks:**
 - *Add* = number of messages *added* per time step
 - *Cur* = number of messages *broadcast* (currently held on the channel) per time step
 - *Rem* = number of messages *removed* per time step



Analysis – Information Domain

Standard Comm Output from SEAS



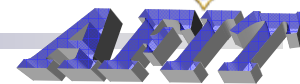
➤ Example of Communications raw data from SEAS

| Run | #1 | | | |
|------|-----------------|-----------------|-----------------|--|
| Time | JSTARSQ_Sit_Cur | JSTARSQ_Sit_Add | JSTARSQ_Sit_Rem | |
| 8 | 0 | 0 | 0 | |
| 9 | 0 | 0 | 0 | |
| 10 | 0 | 0 | 0 | |
| 11 | 4 | 4 | 0 | |
| 12 | 4 | 0 | 0 | |
| 13 | 4 | 0 | 0 | |
| 14 | 4 | 0 | 0 | |
| 15 | 0 | 0 | 4 | |
| 16 | 0 | 0 | 0 | |
| 17 | 0 | 0 | 0 | |
| 18 | 0 | 0 | 0 | |
| 19 | 0 | 0 | 0 | |
| 20 | 0 | 0 | 0 | |
| 21 | 14 | 14 | 0 | |
| 22 | 14 | 0 | 0 | |
| 23 | 14 | 0 | 0 | |
| 24 | 14 | 0 | 0 | |
| 25 | 0 | 0 | 14 | |
| 26 | 0 | 0 | 0 | |



Analysis – Information Domain

Average Message Loading



- Calculated average number of messages handled by all channels over *10 runs* of the scenario

| Channel | BASELINE - No Effects | | Terrain Only | | Weather Only | | Full Effects | |
|---------------------|-----------------------|---------|--------------|---------|--------------|---------|--------------|---------|
| | Count | Average | Count | Average | Count | Average | Count | Average |
| JSTARSQ_Sit_Rem | 2262.00 | 0.51 | 2260.00 | 0.46 | 1077.00 | 0.48 | 3728.00 | 0.61 |
| GShipQ_Sit_Rem | 1985.00 | 0.43 | 1800.00 | 0.34 | 131.00 | 0.09 | 424.00 | 0.10 |
| GHQ_Sit_Rem | 3362.00 | 0.68 | 3197.00 | 0.56 | 180.00 | 0.16 | 833.00 | 0.15 |
| SBRQ_Sit_Rem | 22302.00 | 4.90 | 21321.00 | 4.11 | 5328.00 | 2.65 | 18781.00 | 3.23 |
| TacAirQ_Sit_Rem | 22302.00 | 4.90 | 21321.00 | 4.11 | 5328.00 | 2.65 | 18781.00 | 3.23 |
| GShip_OrdQ_Ord_Rem | 1.00 | 0.00 | 1.00 | 0.00 | 1.00 | 0.00 | 1.00 | 0.00 |
| Air_OrdQ_Ord_Rem | 3.00 | 0.00 | 3.00 | 0.00 | 3.00 | 0.00 | 3.00 | 0.00 |
| ImSatQ_Sit_Rem | 64.00 | 0.01 | 21.00 | 0.01 | 27.00 | 0.01 | 14.00 | 0.00 |
| ElintSATQ_Sit_Rem | 233.00 | 0.06 | 205.00 | 0.04 | 172.00 | 0.04 | 216.00 | 0.06 |
| SOF_OrdQ_Ord_Rem | 342.00 | 0.21 | 567.00 | 0.13 | 189.00 | 0.08 | 207.00 | 0.13 |
| SOF_Sat_PhQ_Sit_Rem | 336.00 | 0.05 | 131.00 | 0.04 | 512.00 | 0.05 | 311.00 | 0.06 |
| RTac_OrdQ_Var_Rem | 11342.00 | 2.14 | 13448.00 | 2.26 | 13367.00 | 2.19 | 11342.00 | 2.12 |
| RTac_OrdQ_Ord_Rem | 11198.00 | 1.93 | 7138.00 | 1.73 | 7118.00 | 1.86 | 11578.00 | 1.99 |
| RIADSQ_Sit_Rem | 827.00 | 0.18 | 1250.00 | 0.20 | 765.00 | 0.18 | 1205.00 | 0.25 |
| RSRTQ3_Sit_Rem | 371.00 | 0.20 | 367.00 | 0.09 | 369.00 | 0.11 | 353.00 | 0.20 |
| KSHQ_Sit_Rem | 218.00 | 0.04 | 303.00 | 0.04 | 264.00 | 0.04 | 237.00 | 0.04 |
| KSHQ_Ord_Rem | 283.00 | 0.05 | 310.00 | 0.05 | 256.00 | 0.05 | 249.00 | 0.05 |
| KBellQ_Sit_Rem | 3652.00 | 0.45 | 3635.00 | 0.42 | 9828.00 | 0.62 | 6742.00 | 0.78 |
| KBellQ_Ord_Rem | 24.00 | 0.00 | 24.00 | 0.00 | 24.00 | 0.00 | 24.00 | 0.00 |

- Useful in identifying channels seeing highest activity
- Provided comparison test between baseline and three degraded cases
- **Inactive time-steps (zero messages) skewed the averages**



Analysis – Information Domain

Active Time-Step Loading



- Next, calculated total number of messages and active average message loading for top five channels over *one simulation run*

Average Channel Loading for Active Time-Steps

BASELINE - NO EFFECTS CASE

| Channel | JSTARSQ_Sit | SBRQ_Sit | TacAirQ_Sit | RTac_OrdQ_Var | RTac_OrdQ_Ord |
|--|-------------|----------|-------------|---------------|---------------|
| Number of Active Minute Time-Steps | 196.00 | 324.00 | 179.00 | 513.00 | 1132.00 |
| Average Message Activity per Time-Step | 7.18 | 64.82 | 117.34 | 27.16 | 14.77 |

FULL EFFECTS CASE

| Channel | JSTARSQ_Sit | SBRQ_Sit | TacAirQ_Sit | RTac_OrdQ_Var | RTac_OrdQ_Ord |
|--|-------------|----------|-------------|---------------|---------------|
| Number of Active Minute Time-Steps | 352.00 | 293.00 | 187.00 | 525.00 | 882.00 |
| Average Message Activity per Time-Step | 10.43 | 58.02 | 90.91 | 23.60 | 14.88 |

- A slightly better metric than overall average message load because influence of zero message time-steps is removed



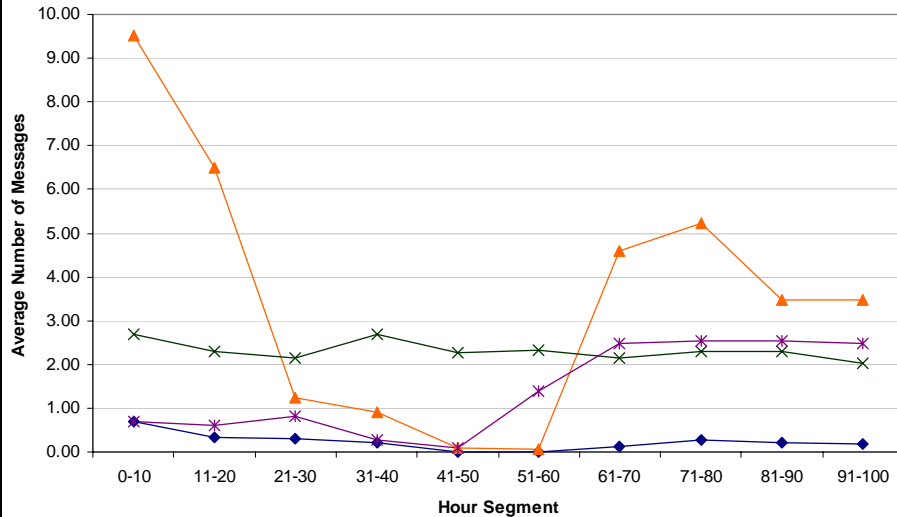
Analysis – Information Domain

Average Message Load Over Time

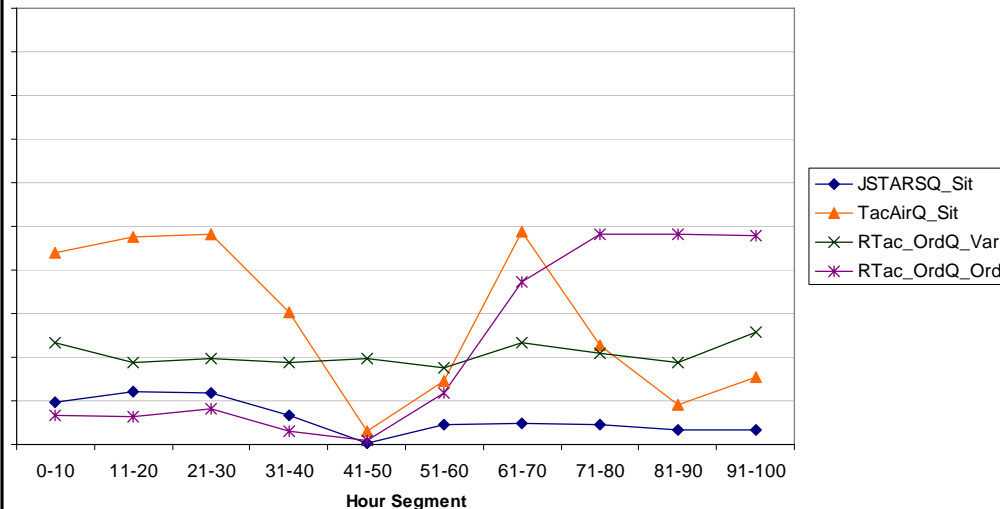


- Finally, calculated and plotted average message loading per 10-hour segment over *one simulation run*
- Provides most insight into communication channel activity

Baseline (No Effects) Case - Average Message Load per 10 Hours of Kosovo Scenario for Top Four Active Channels



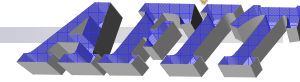
Full Effects Case - Average Message Load per 10 Hours of Kosovo Scenario for Top Four Active Channels



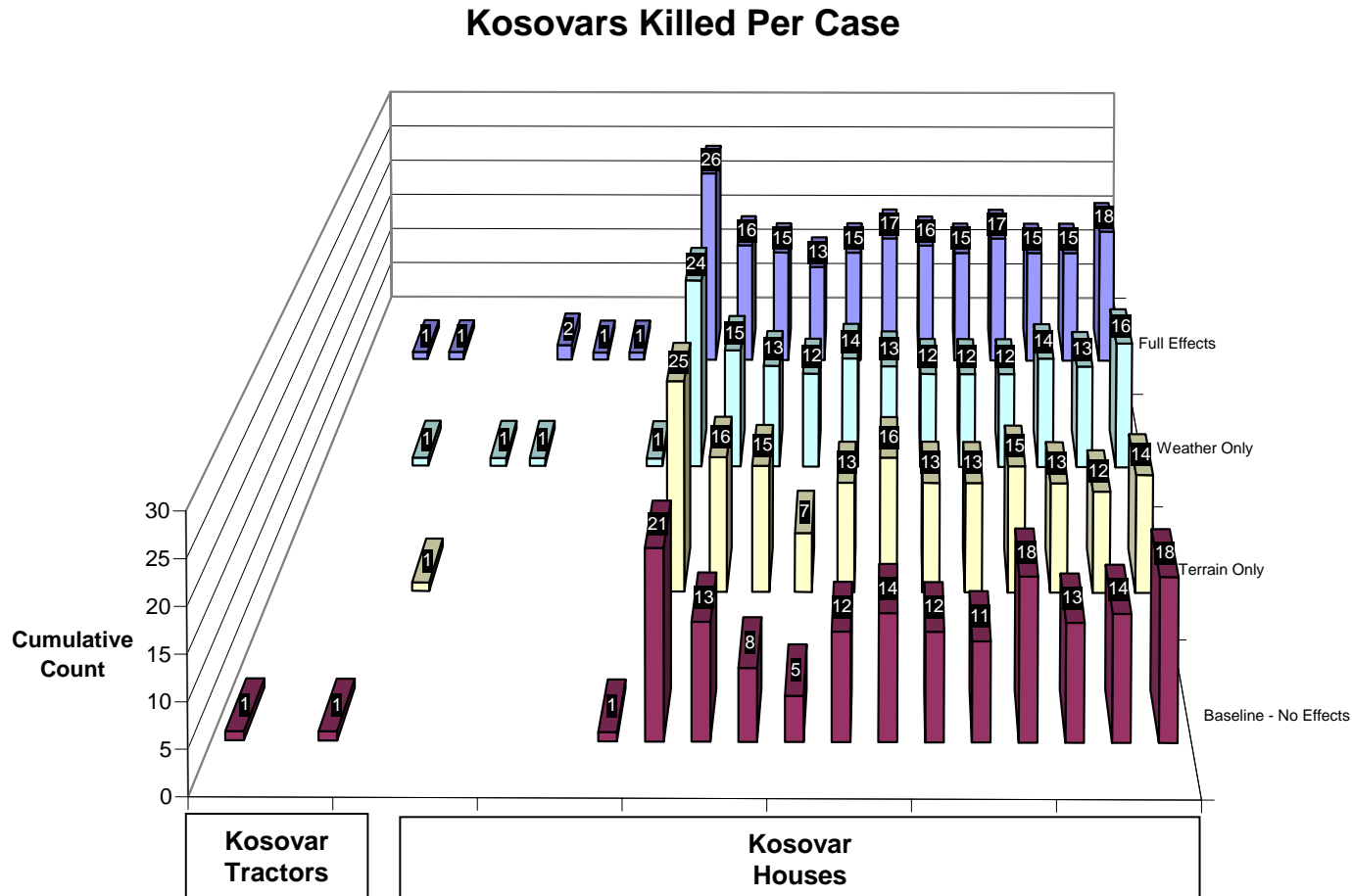


Analysis – Cognitive Domain

Effect on the Kill Chain



- A kill represents the conclusion of the kill chain
 - The *Act* of the OODA Loop (Observe, Orient, Decide, Act)





Analysis – Cognitive Domain

Effect on the Kill Chain



- Consistent trends seen in the degraded cases versus the baseline case for this admittedly rough and highly aggregated measure
 - Fewer kills and higher losses for Blue, more kills and less losses for Red, and higher losses for Brown
- **Cognitive Domain is by far the most difficult to capture with an exact quantitative measure**



Conclusions – Analysis Summary



- **Physical domain – Satellite performance was captured well by average detection distance metric**
- **Information domain – Average message loading over time provided insight into Blue's primary target sighting channel**
- **Cognitive domain – Number of kills, although highly aggregated, showed expected trends**



QUESTIONS?



Thank You