

Enhanced Situation Awareness using Random Particles



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Disposition

- Ericsson Microwave Systems and target C2 system
- Our work
 - Demonstration
 - Theory
- Conclusions and future work

Ericsson Microwave Systems

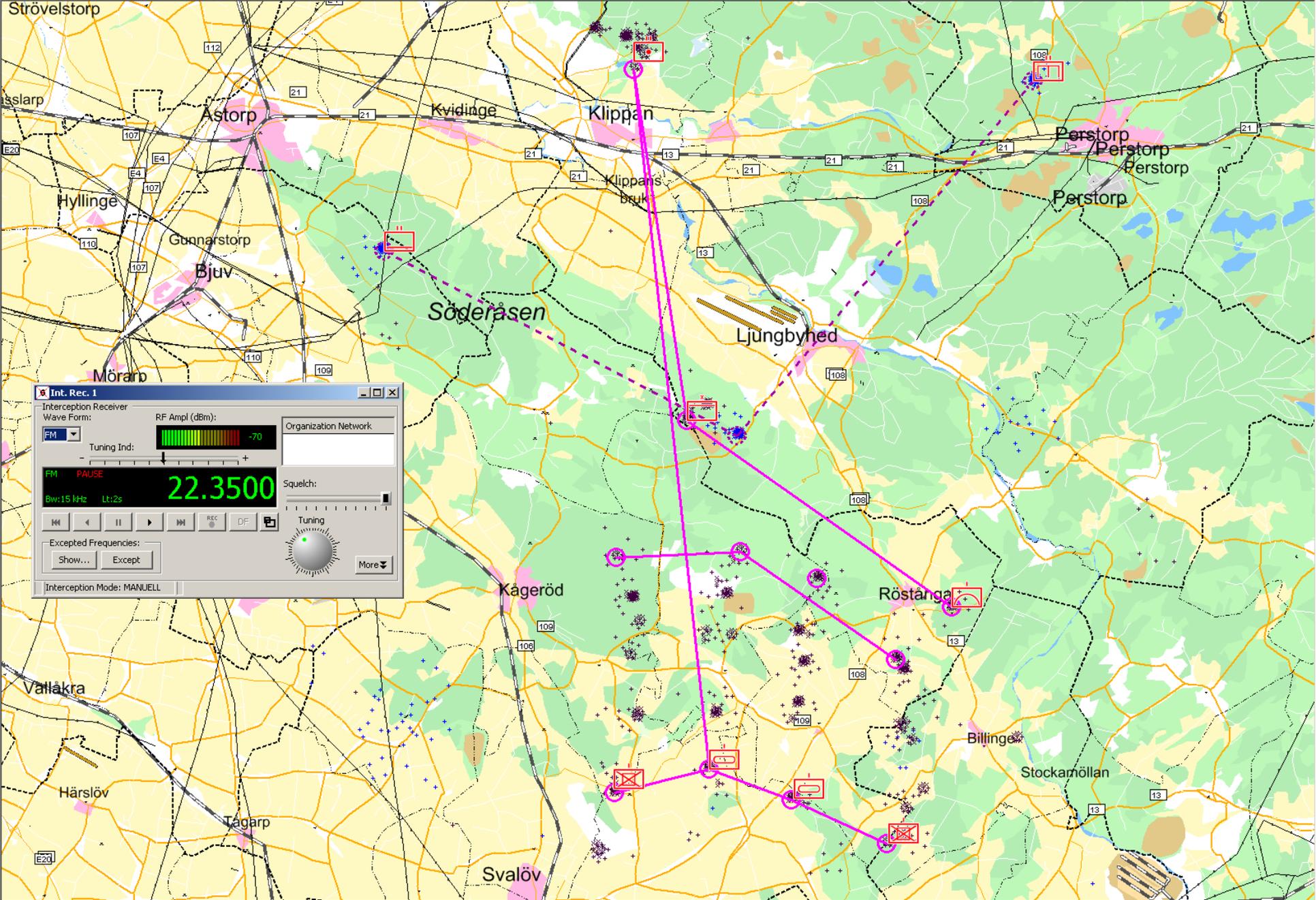


Target C2 system: GALDER - Electronic Warfare System



Our work

- Created a generic tool for prediction of forthcoming troop movements
- Implemented and tested in a tactical electronic warfare system



Int. Rec. 1

Interception Receiver
Wave Form: FM
RF Ampl: (dBm) -70
Tuning Ind: [Bar Graph]

Organization Network

Squelch: [Slider]

22.3500
Bw: 15 kHz Lb: 2s

Excerpted Frequencies:
Show... Except

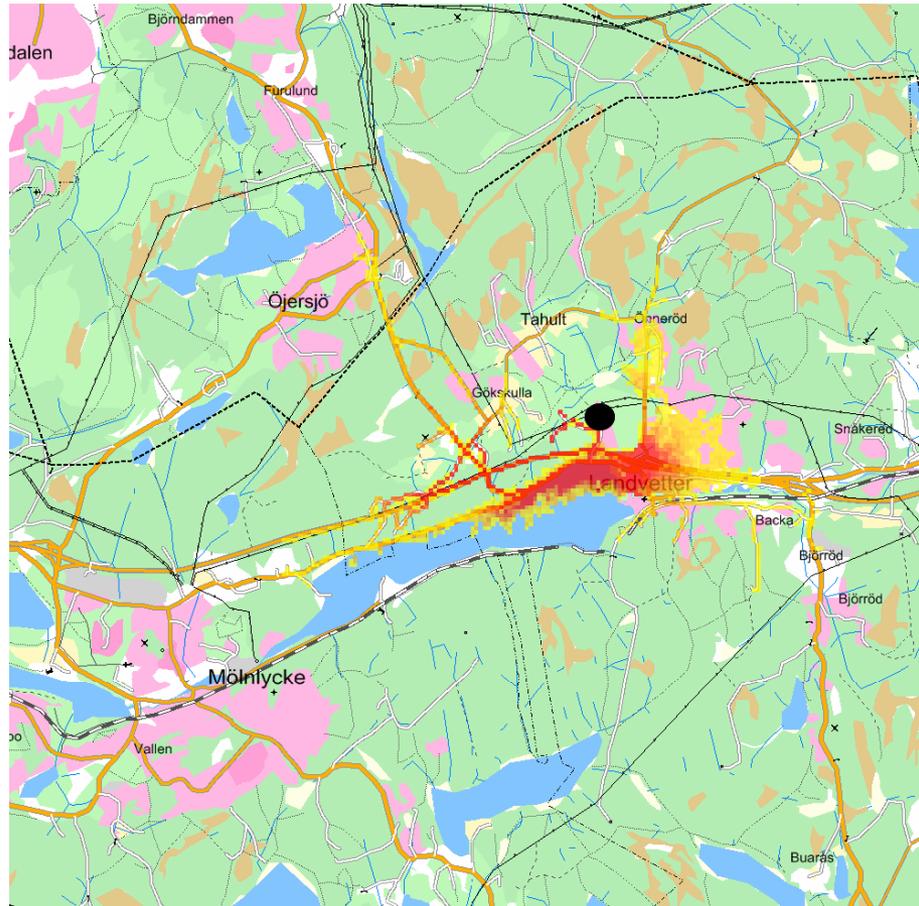
Tuning [Knob]

Interception Mode: MANUELL

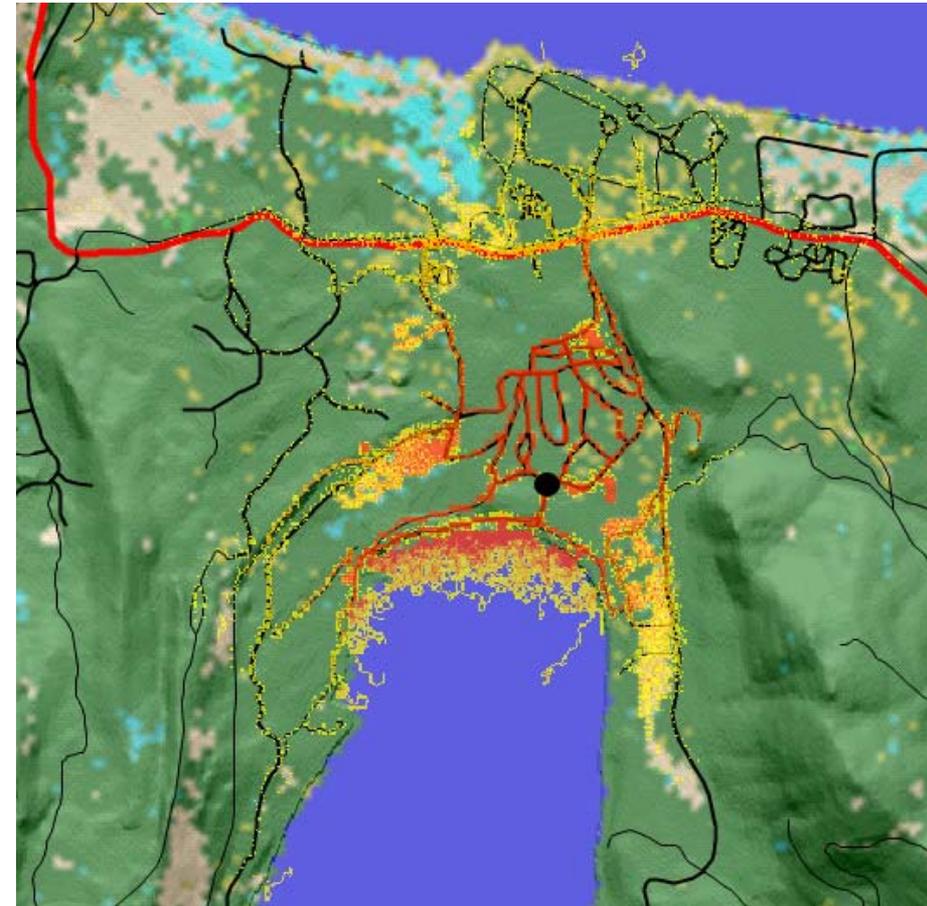
Procedure of usage

1. Operator selects an object of interest on the map
2. Selection of object type, time horizon, precision (current speed and direction)
3. Terrain is transformed to possible maximum speeds
4. Speed matrix is used for prediction calculations
5. Prediction is presented on situation picture

Examples of predictions



Map grid size: 50 by 50 m



Map grid size: 10 by 10 m

Theory

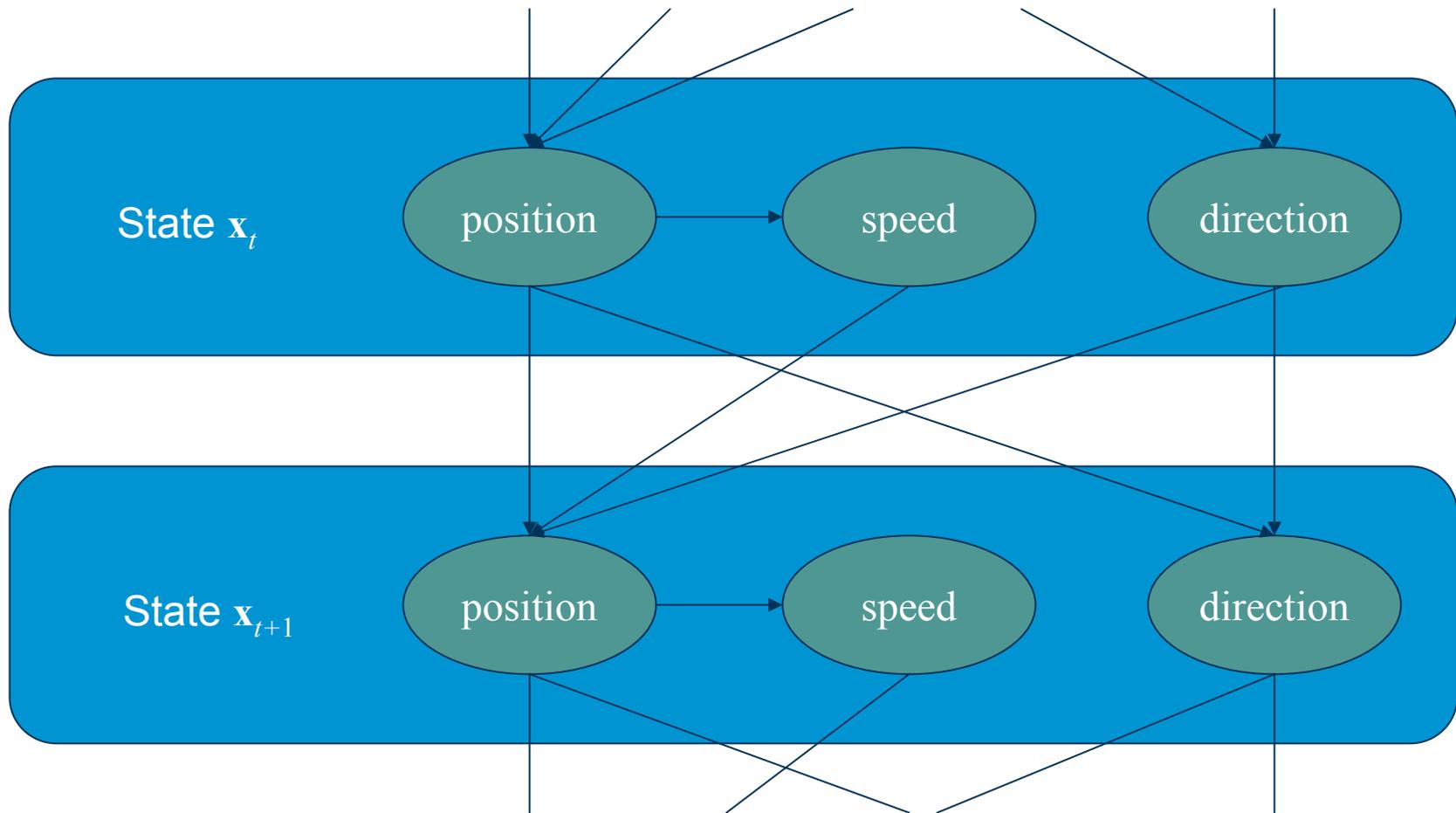
- Bayesian networks
- Dynamic Bayesian networks
- Particle filtering



Change over time

Approximate inference

Random particles

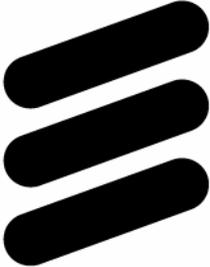


Conclusions

- Acknowledged during field tests (ASÖ05)
 - Received ideas for future work
 - Warning system
 - Disregarding old obsolete observations
- Our algorithm constitutes as a general tool for solving this type of problem
- Predictions are sound probability distributions
- Included in the next release of GALDER

Future work

- Extended functionality
- Visualization
- Evolution of models

ERICSSON 

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