

**ECHELON 4**



# Scale-Free Command & Control

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# Outline



- Thesis
- Scale Related to C2 Policy Domains
- Federated Systems of C2 Systems
- C2 System Actor Model
- Scalable C2 Controllers
- Scalable C2 Application Services
- C2 Completion-Time Semantics
- C2 Controller Operations



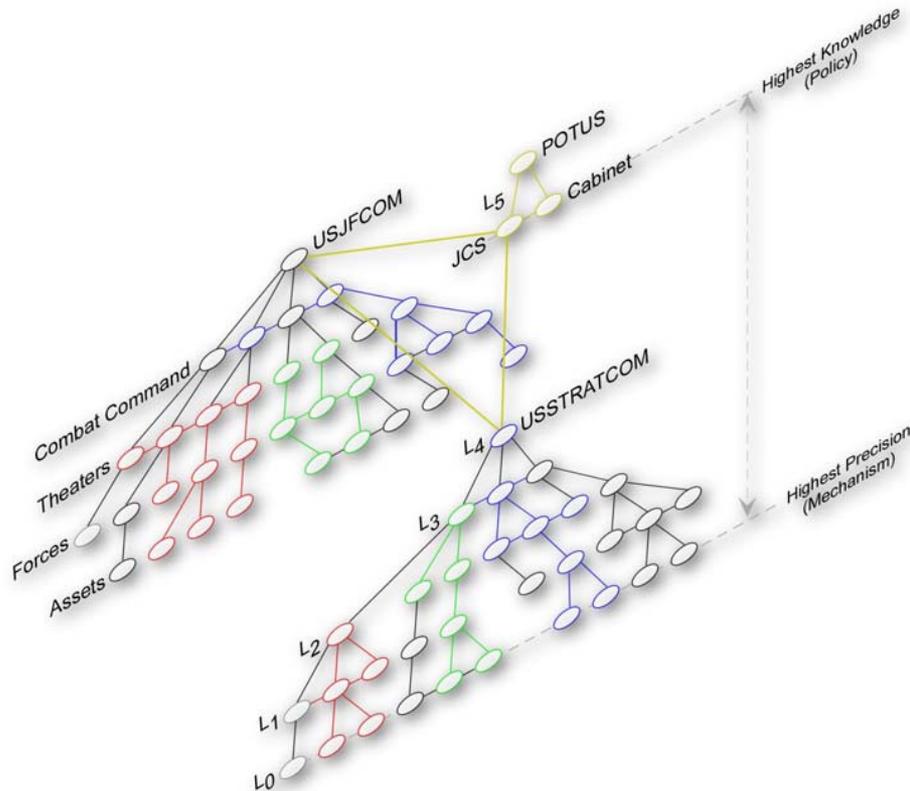
# Thesis



- Network centrality *empowers* everyone, from POTUS to soldiers at the edge, regardless of rank or service allegiance
  - Enlightened, continuous, fast paced and distributed decision making requires *trust* at all levels in support of collaboration, interoperability, and “jointness”
  - Trust implies intra- and inter-service *discipline, accountability* and *adaptability*
  - Discipline requires *formal, reproducible* and *traceable* (i.e., causal) *policies* and *processes*
- ⇒ We require a core set of scalable (“scale-free”) services supporting time-bound collaborative, distributed C2
- ⇒ Collaborative C2 services should include support for specific elements of *situation assessment, plan generation* and *plan execution*



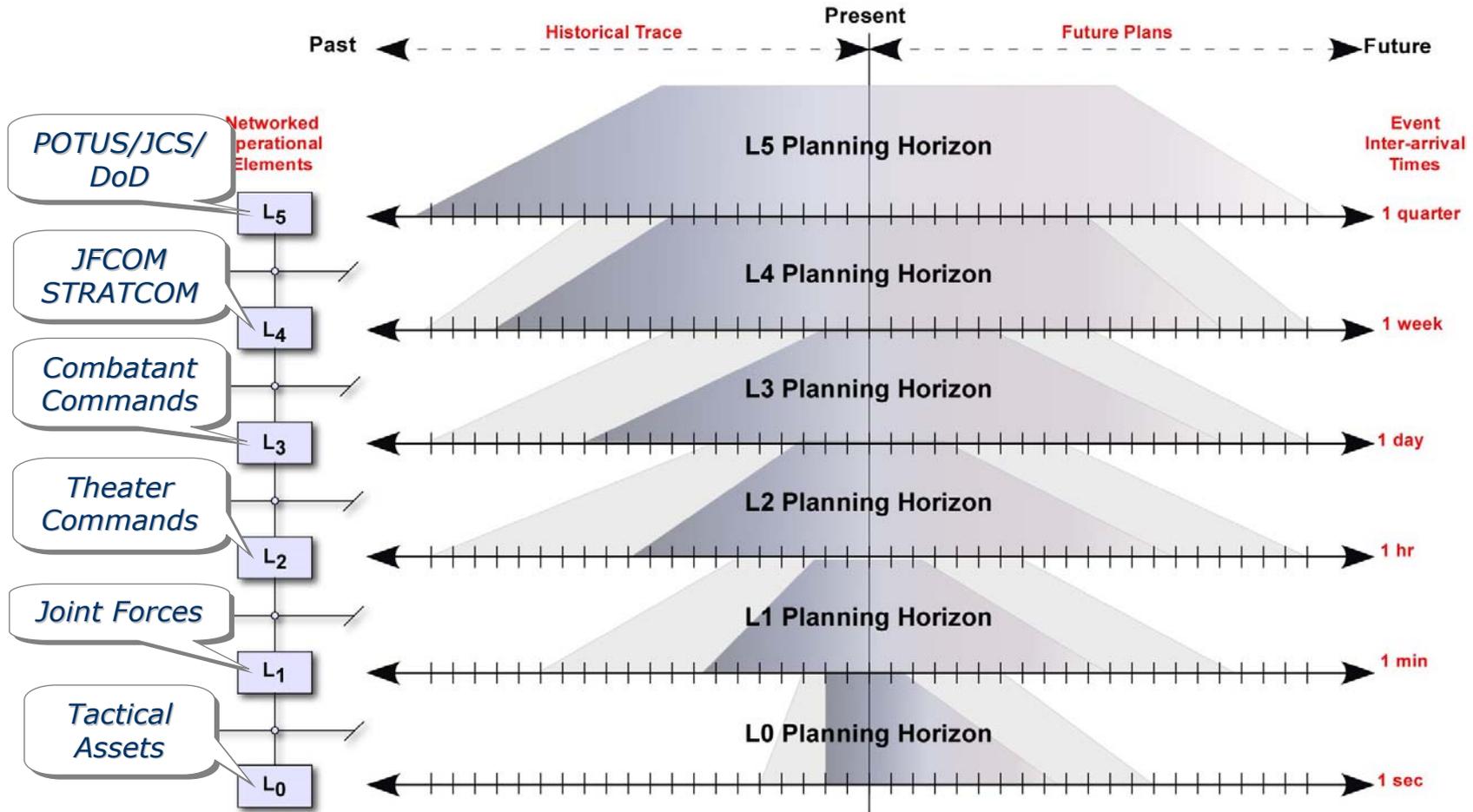
# C2 Policy Domains



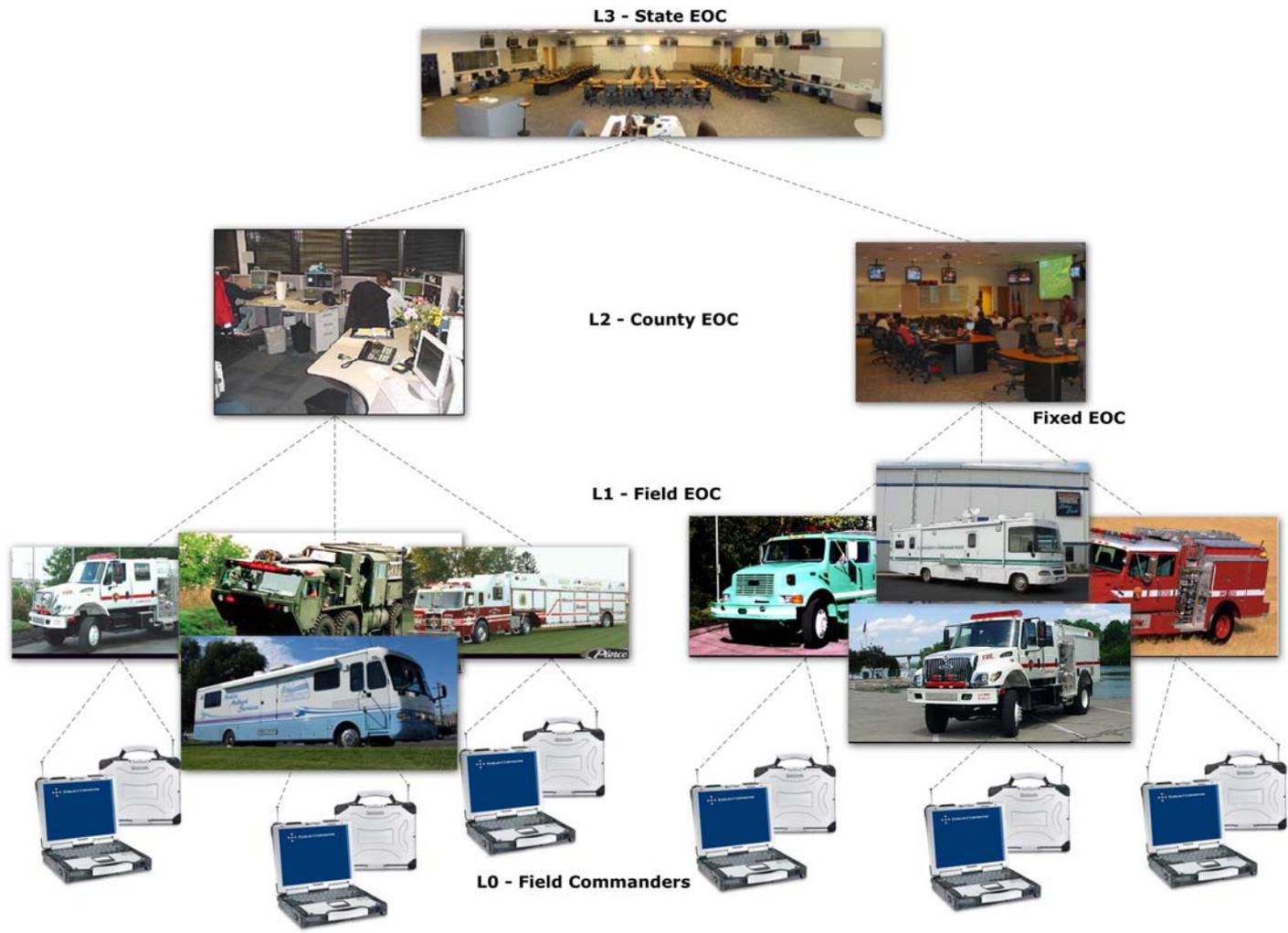
- An enterprise *accountable* to the degree it operates in a traceable command or policy domain hierarchy
- A C2 system is *scale-free* to the degree that policies and processes scale uniformly from the lowest tactical levels to the highest strategic levels of command
- A scale-free system is *manageable* to the degree it supports a uniform *performance measurement framework* that is policy domain neutral



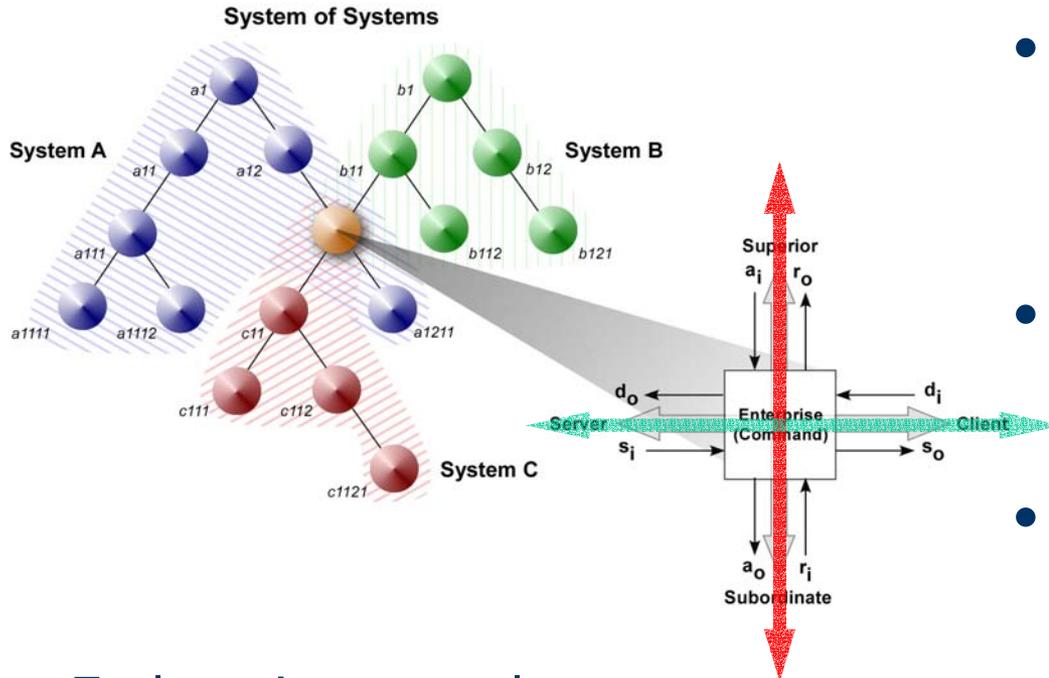
# Scale: *C2 Space*



# Civilian DHS-ICS Example



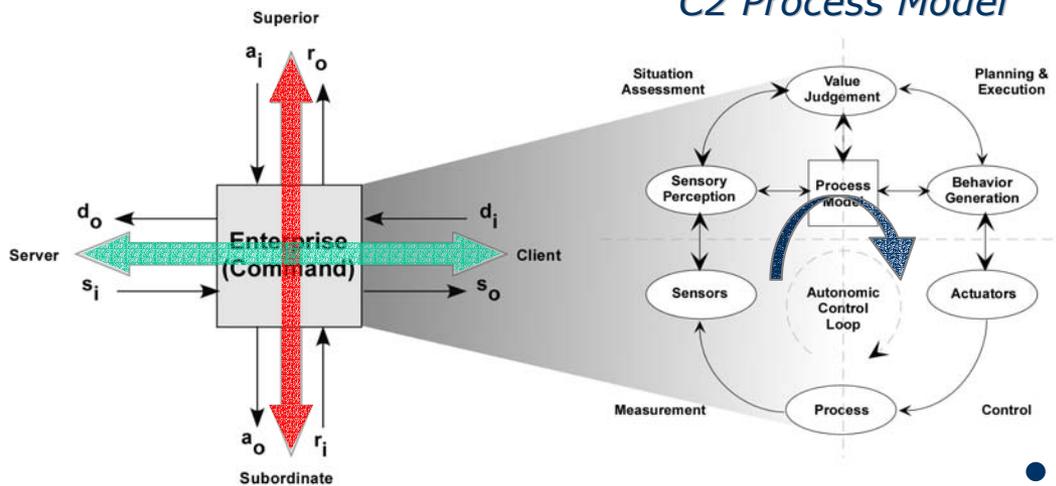
# Systems of Federated C2 Systems



- Federation members are
  - Uniquely Identifiable
  - Self Directed (Semi-Autonomous)
  - Freely Associative, and
  - Mutually Interdependent
- A given enterprise may participate in multiple federations (systems of systems)
- Each federated entity is considered a *command*, or *value production unit*
- A command is a four port object operating in a lattice or mesh interconnected by a
  - Command Axis (superior-subordinate)
  - Service Axis (client-server)



# C2 Process Model



- Federated enterprise management has two simultaneous objectives:
  - Maintaining command chain commitments (viability, homeostasis)
  - Maintaining supply chain commitments (service level agreements)
- Automation of core processes (autonomic controls) is a proven means of improving performance (yield, quality, etc.)

# Scale-Free C2 Actor Model



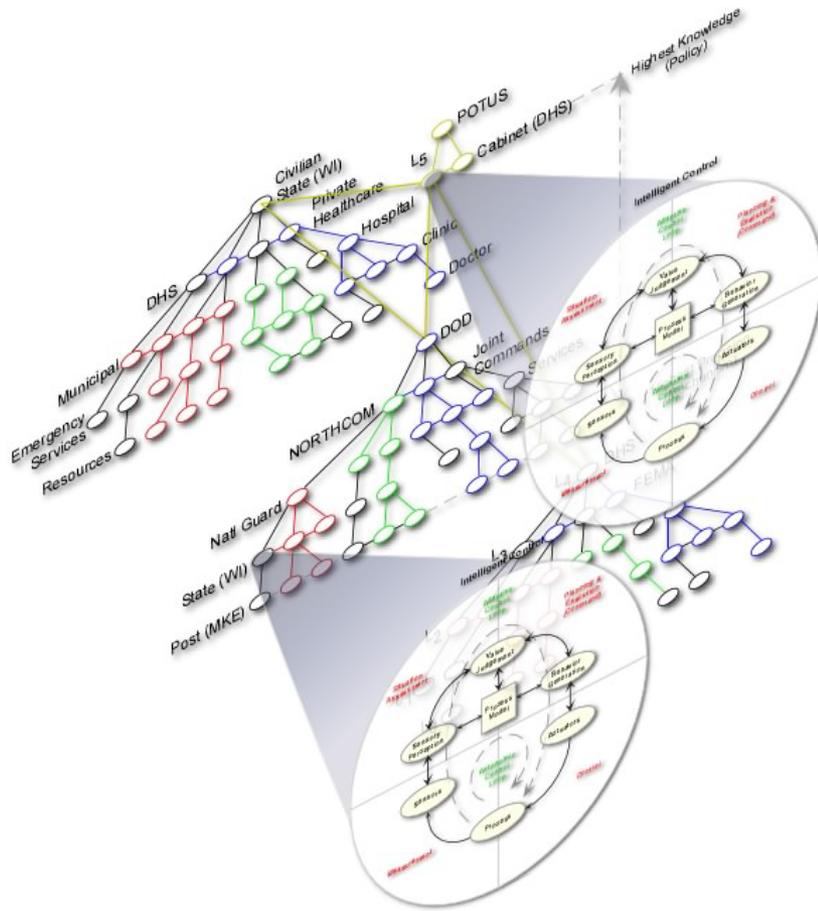
**External  
Context**

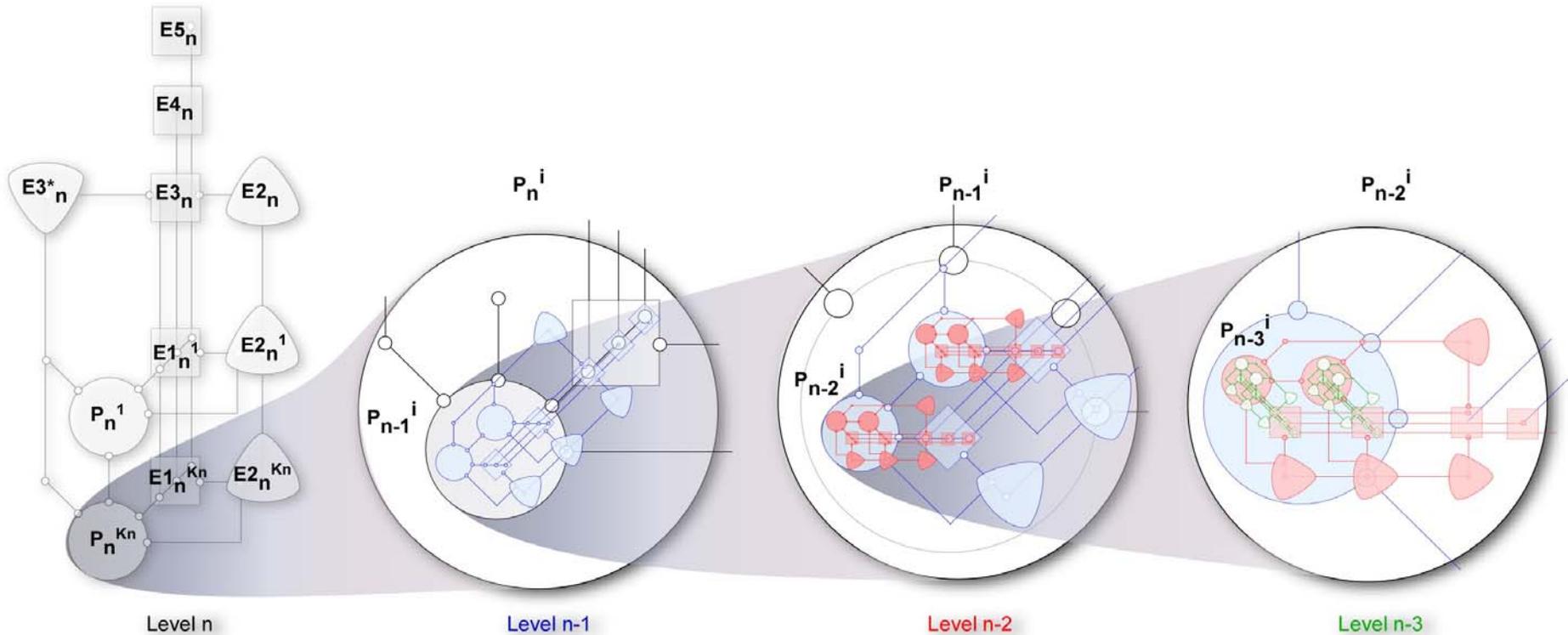
**Internal  
Context**

**Supervisory Controls**

**Regulatory Controls**

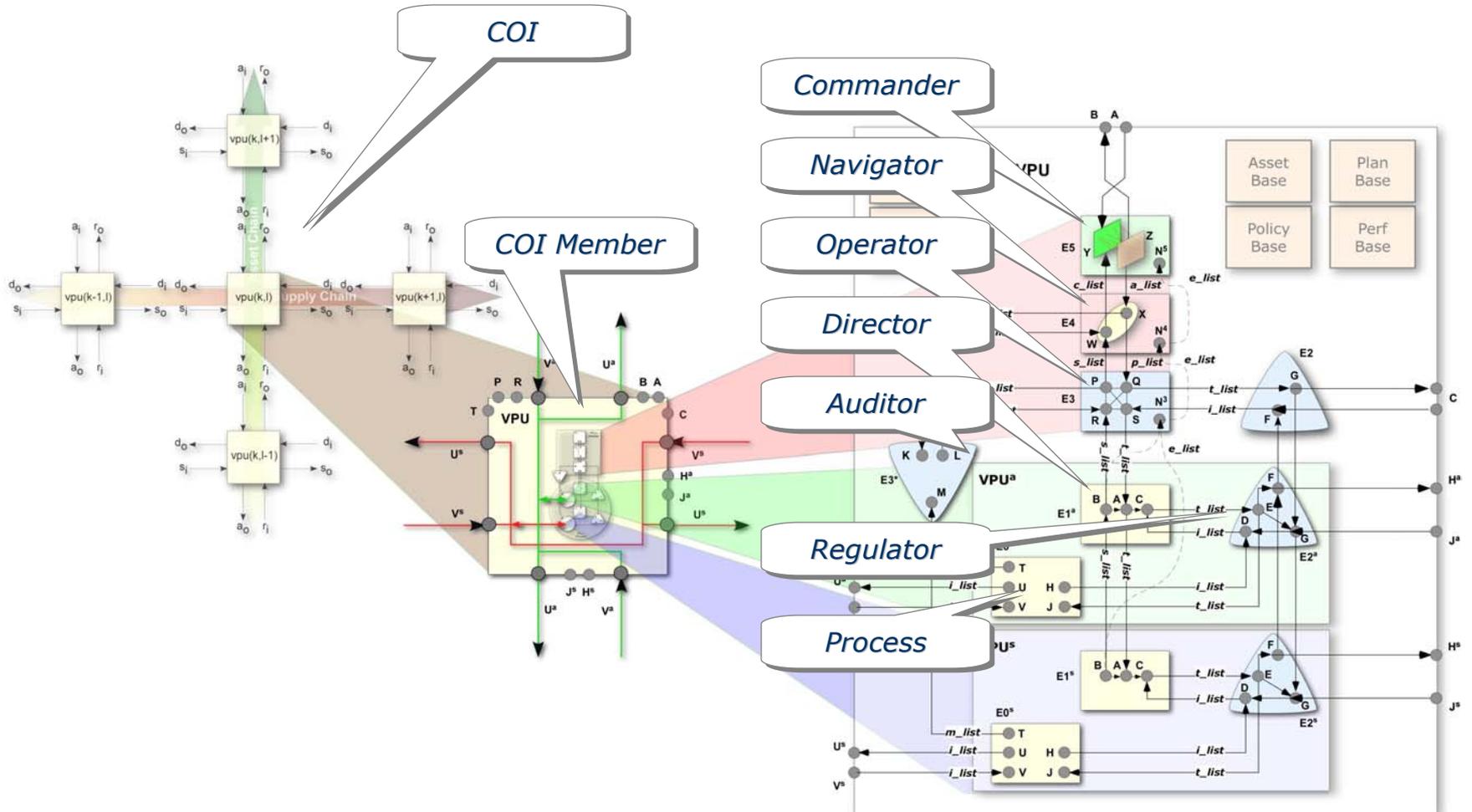
# Always-On Distributed C2







# Federation C2 Actor Model





# C2 System Overview

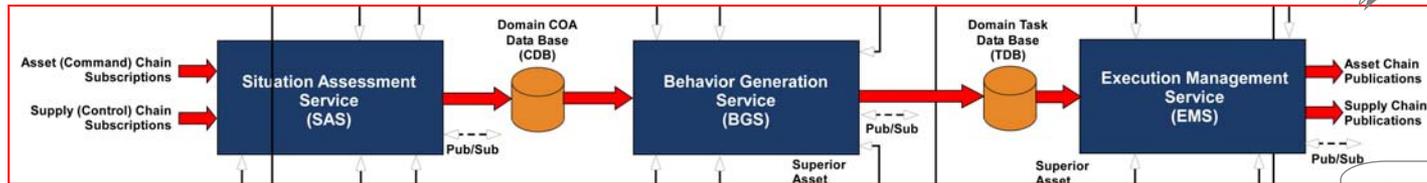


Visual Commons

Model Manager

Policy Manager

C2 Services

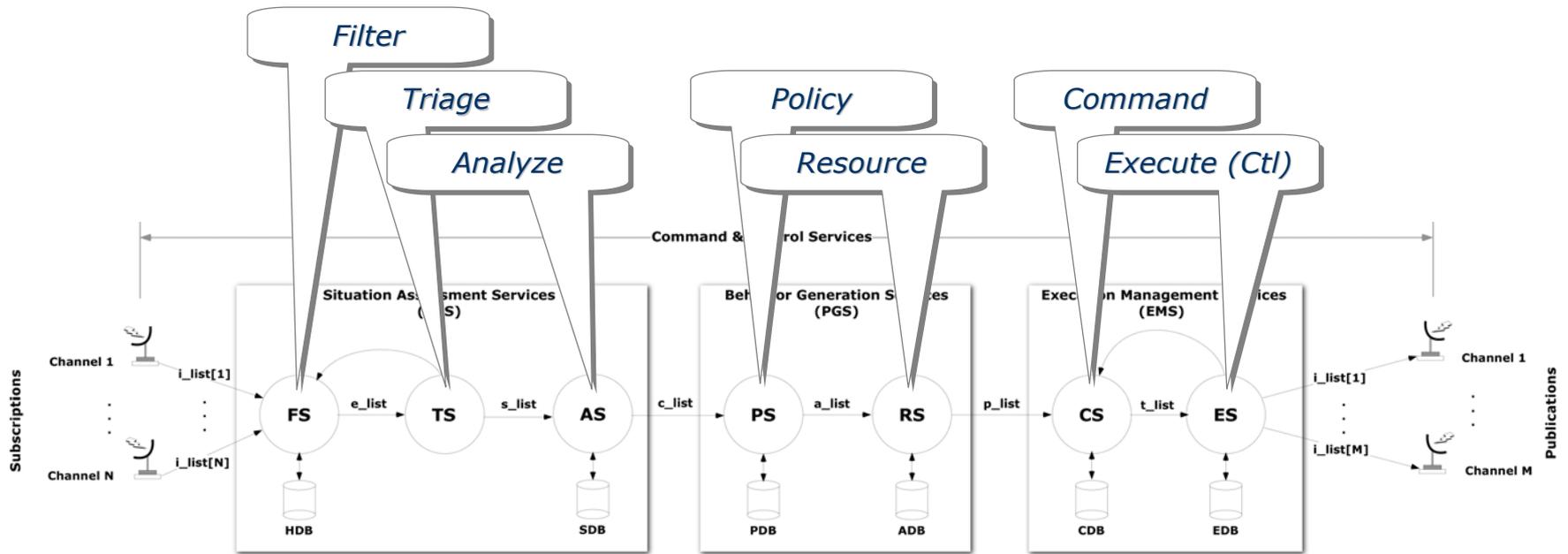


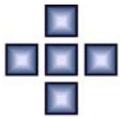
Scenario (Plan) Manager

Performance Manager

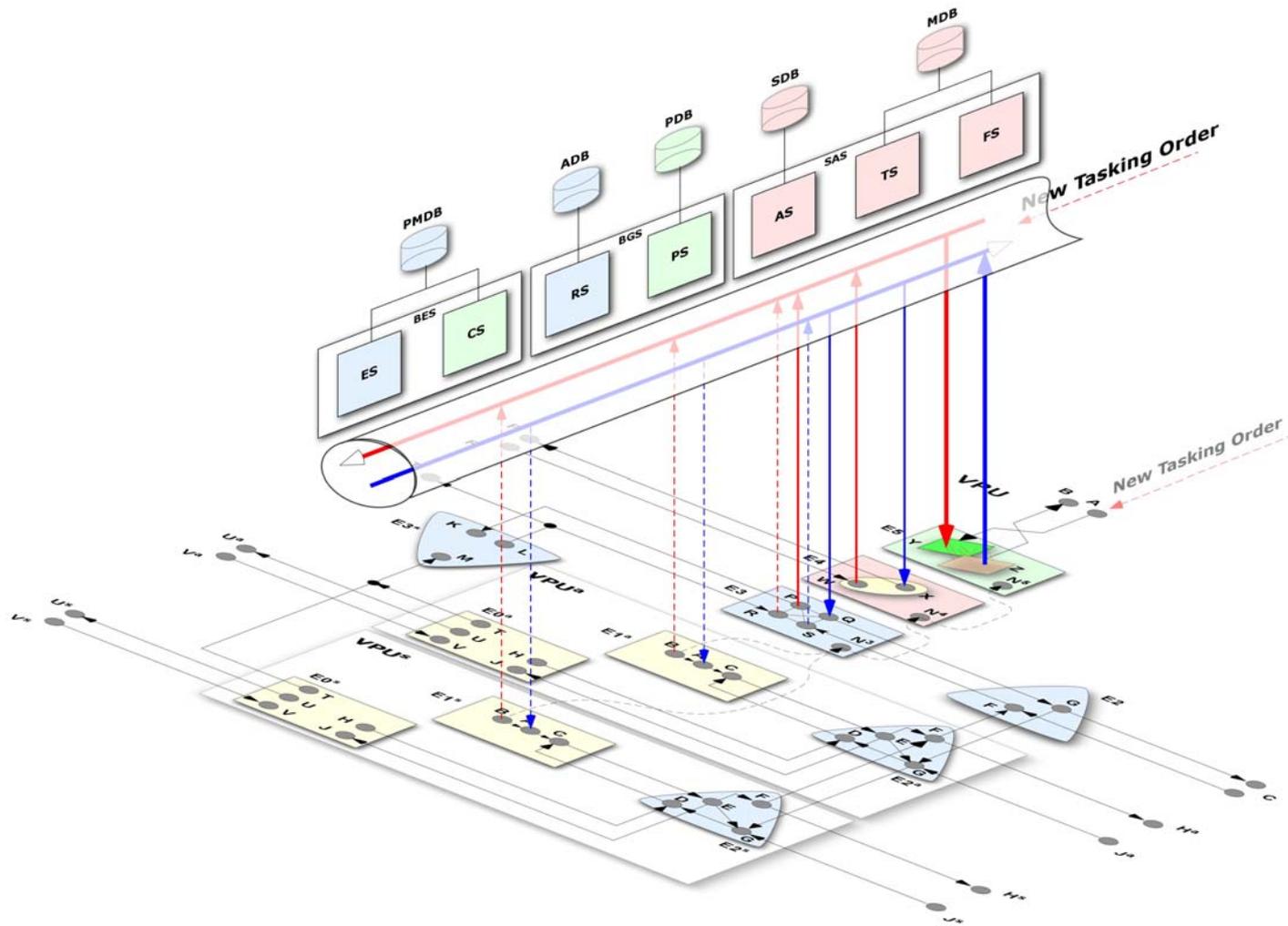
Resource Manager

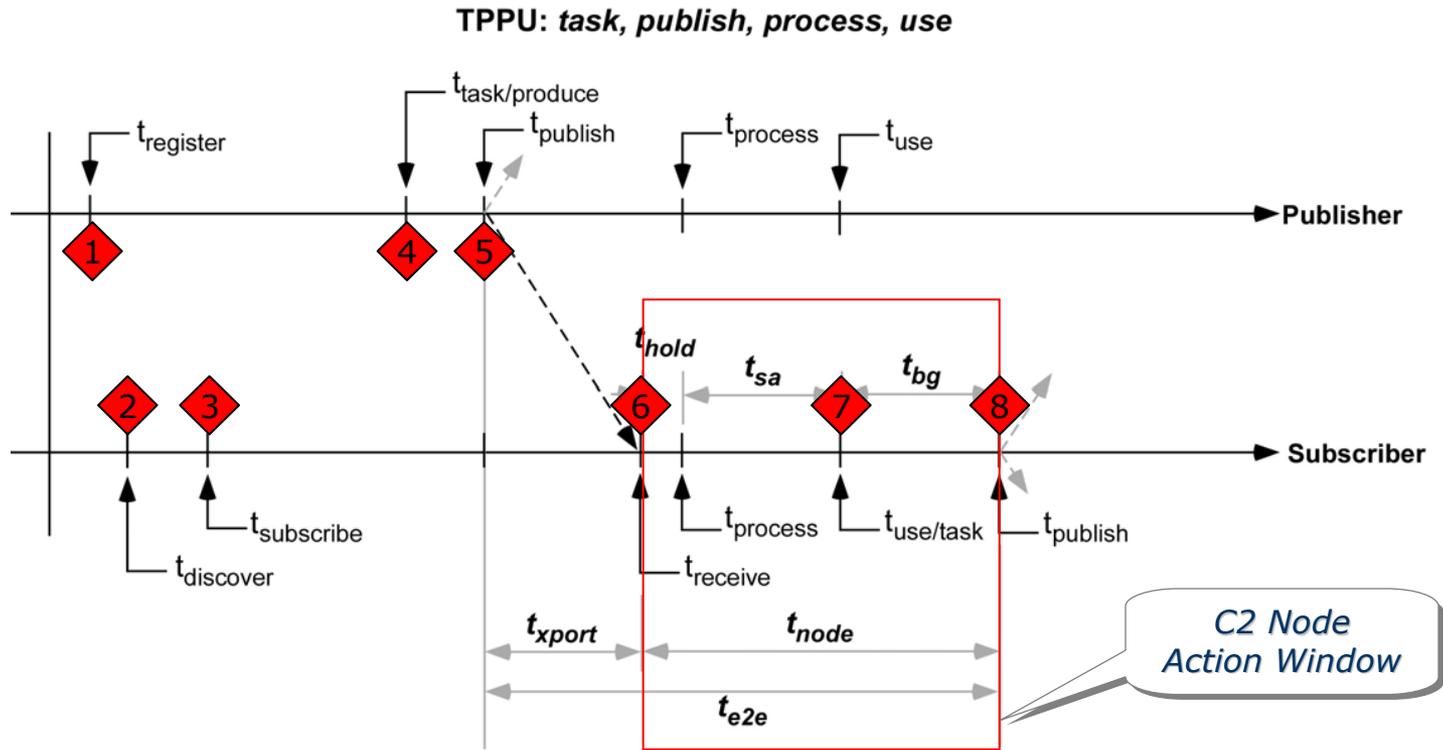
# C2 Application Services





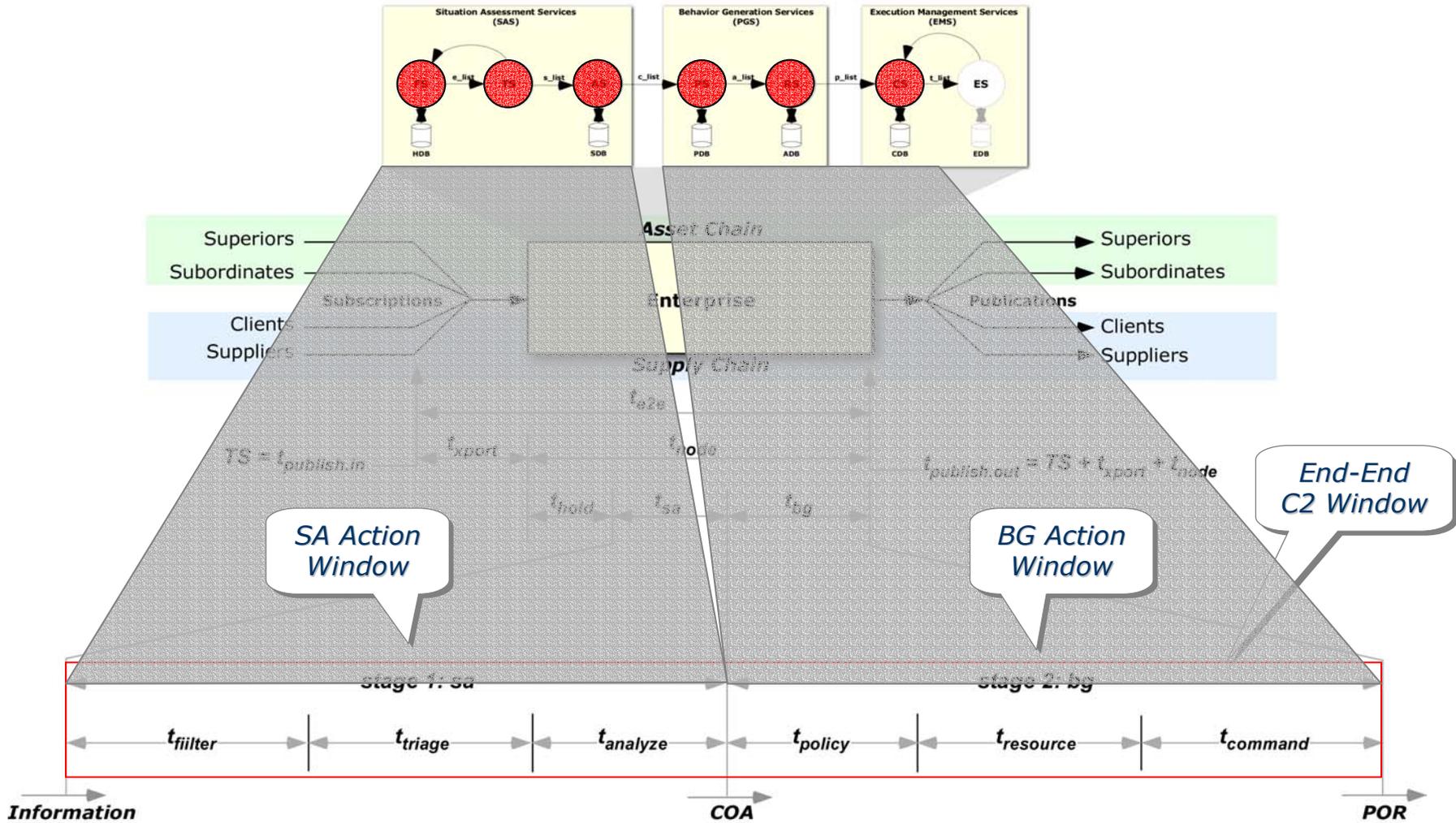
# C2 Node Structure





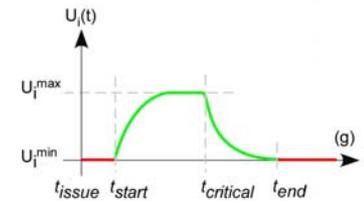
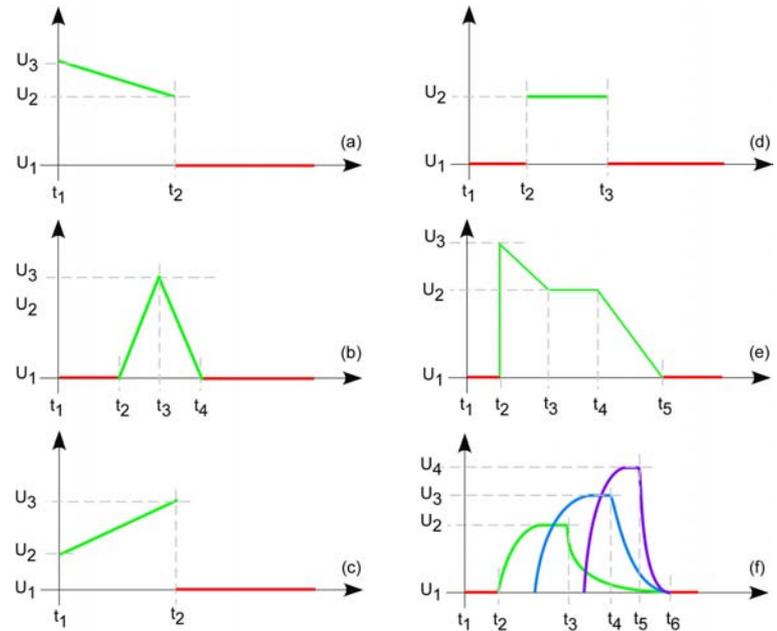
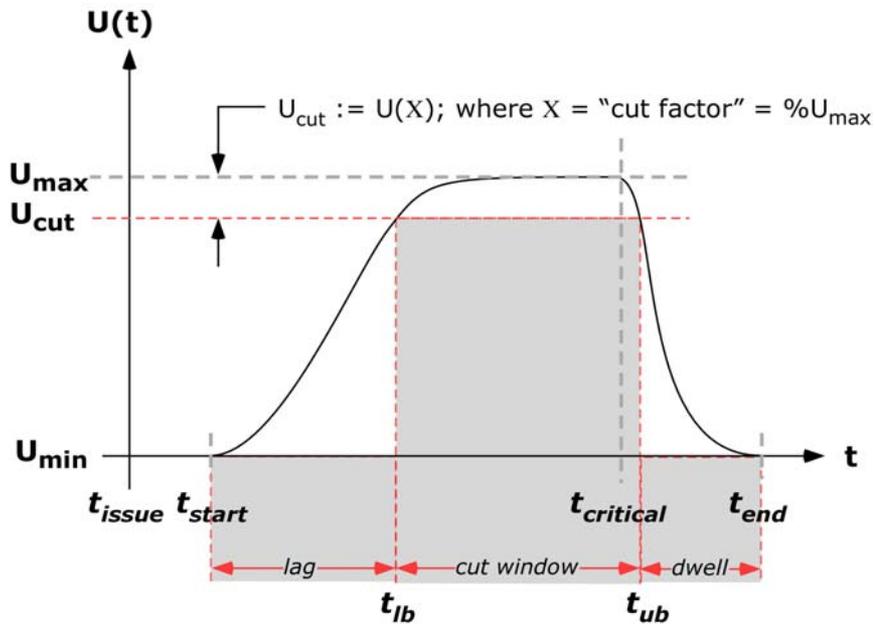
- Real-time => Meeting completion time requirements
- Grid-based => IP connected with publish-subscribe services

# C2 Node Timing

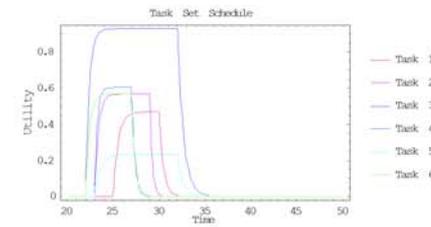
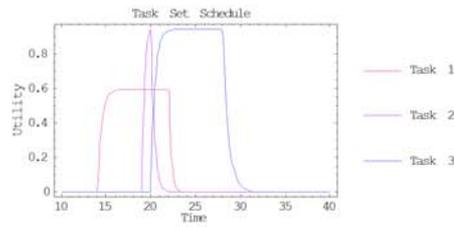
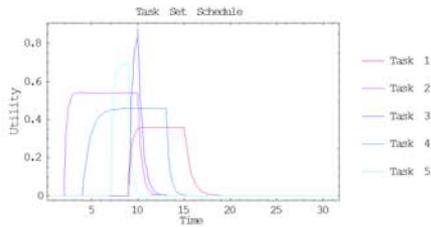
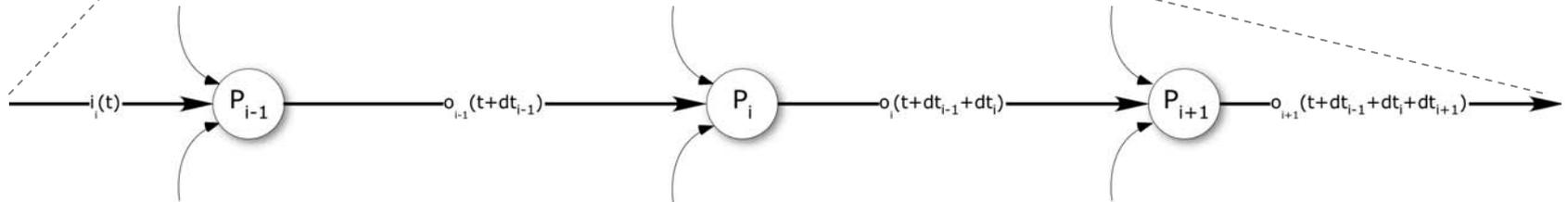
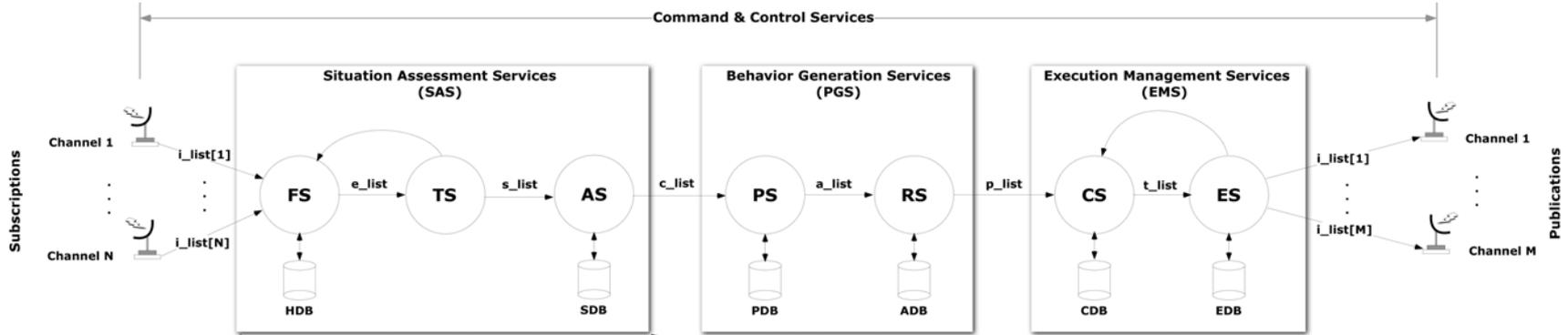




# Completion-Time Requirements

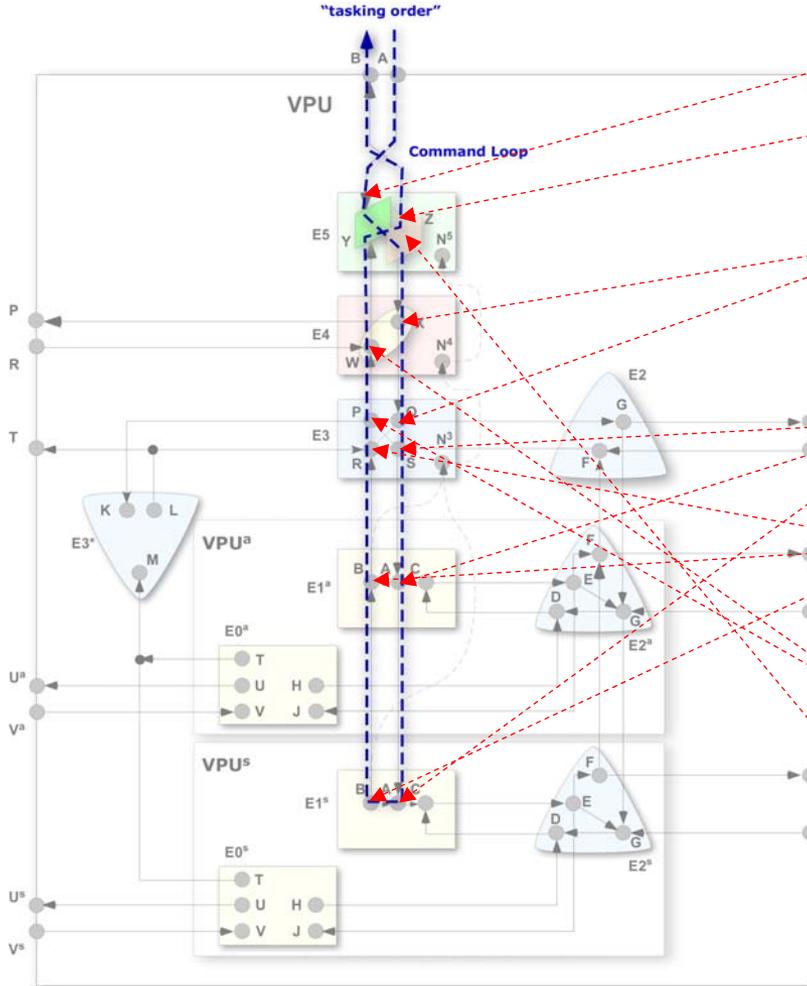


# C2 Time Management





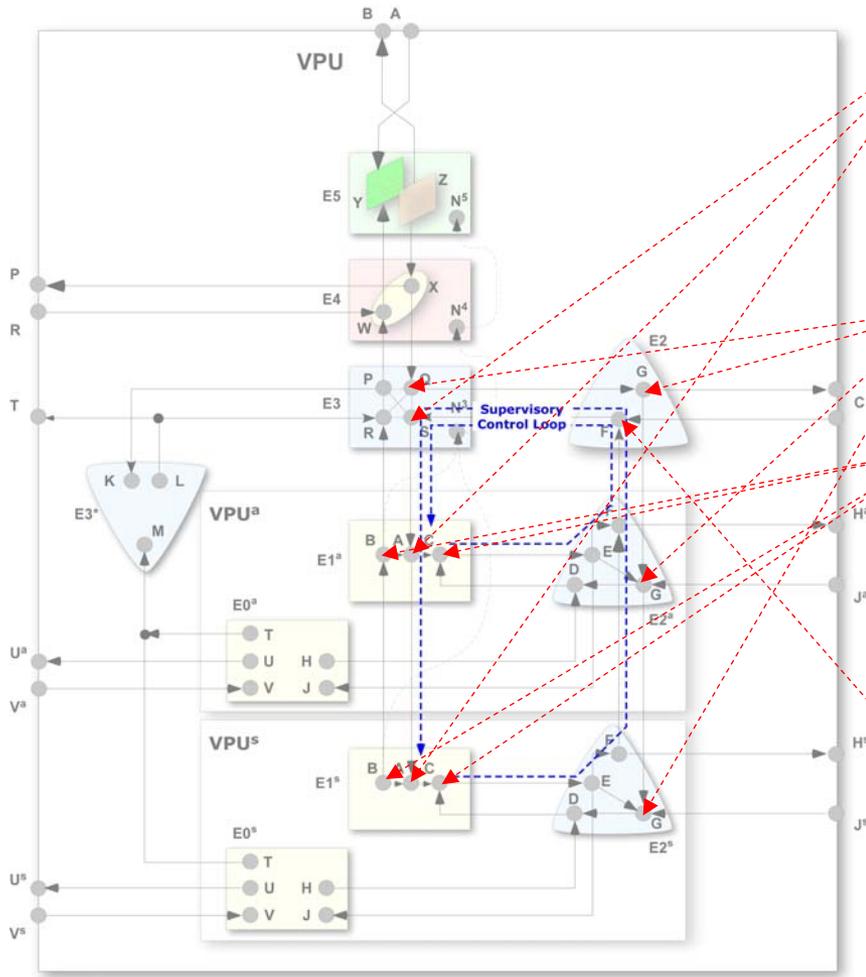
# Tasking Order Propagation



- Commander (E5) receives TO
- Commander (E5) acknowledges receipt
- Commander requests review by staff, Analyst-Planner (E4) and XO (E3)
- XO (E3) requests E1 Director review and response capability
- Directors respond with capabilities (resources, timing, etc.)
- Planner and XO produce response plan
- Commander authorizes action



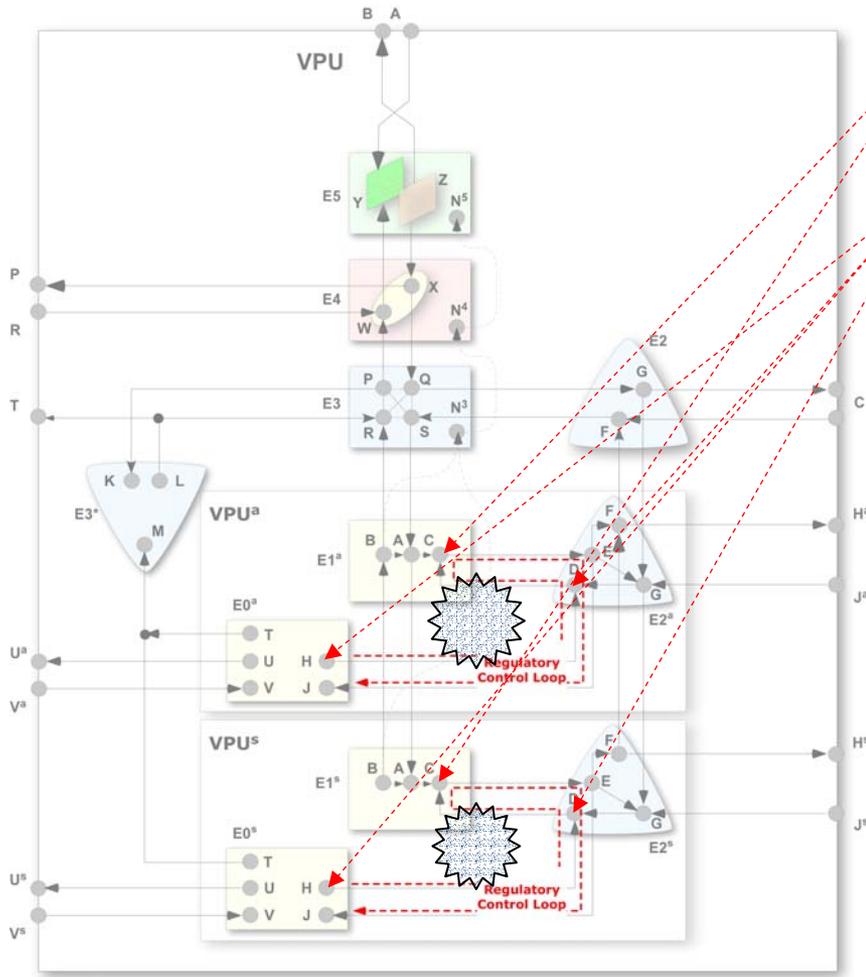
# Task Execution Scheduling



- E3 Operator issues tasking orders (TO) to subordinates (E1a and E1b Directors)
- E3 establishes synchronization logic
- E1a and E1b Directors "program" their Regulators (E2a and E2b) and acknowledge acceptance of TO to E3
- Regulators acknowledge synchronization requirements to E2



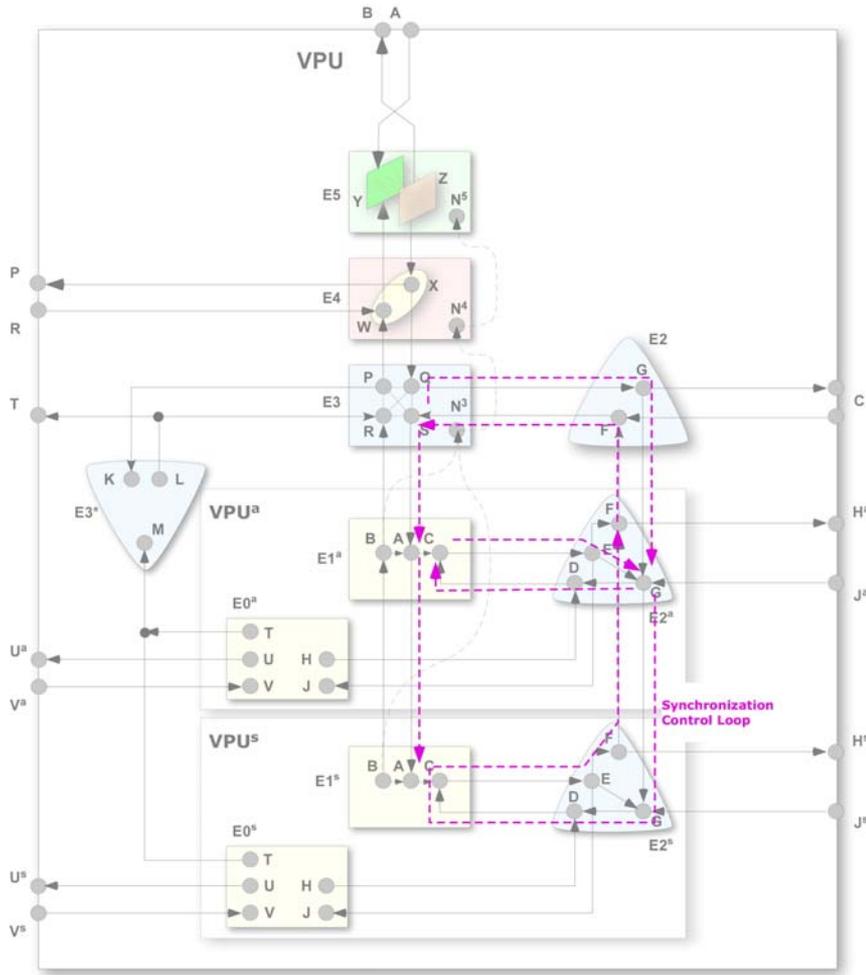
# Autonomic Task Execution



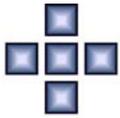
- E1a and E1b initiate action on TO
- Their respective Regulators monitor execution in the E0a and E0b "production processes"



# Task Synchronization



- For task rendezvous and resource sharing, E1a and E1b Regulators monitor and synchronize (e.g., mutex) for E3 Operator



**Thank You!**

**Are there any questions?**